Model Checking Java Programs
(Java PathFinder)

Slides partially compiled from the NASA JavaPathFinder project and E. Clarke's course material
Java PathFinder

• JPF is an explicit state software model checker for Java bytecode
  • JPF is a Java virtual machine that executes your program not just once (like a normal VM), but theoretically in all possible ways, checking for property violations like deadlocks or unhandled exceptions along all potential execution paths.
Symbolic Model Checking

Program → Analysis Engine → SAT Solver → SAT (counterexample exists) → UNSAT (no counterexample found)

Claim → Analysis Engine → CNF → SAT Solver
Explicit State Model Checking

The program is indeed executing

- jpf <your class> <parameters>
  - Very similar to "java <your class> <parameters>
- Execute in a way that all possible scenarios are explored
  - Thread interleaving
  - Undeterministic values (random values)

Concrete input is provided

A state is indeed a concrete state, consisting of

- Concrete values in heap/stack memory
JPF Status

- developed at the Robust Software Engineering Group at NASA Ames Research Center
- currently in it’s fourth development cycle
  - v1: Spin/Promela translator - 1999
  - v2: backtrackable, state matching JVM - 2000
  - v3: extension infrastructure (listeners, MJI) - 2004
  - v4: symbolic execution, choice generators - 4Q 2005
- open sourced since 04/2005 under NOSA 1.3 license: <javapathfinder.sourceforge.net>
- it’s a first: no NASA system development hosted on public site before
- 11100 downloads since publication 04/2005
import java.util.Random;

public class Rand {
    public static void main (String[] args) {
        Random random = new Random(42);    // (1)

        int a = random.nextInt(2);          // (2)
        System.out.println("a=" + a);

        //... lots of code here

        int b = random.nextInt(3);          // (3)
        System.out.println("b=" + b);

        int c = a/(b+a-2);                  // (4)
        System.out.println("c=" + c);
    }
}

> java Rand
a=1
    b=0
      c=-1
>
One execution corresponds to one path.
> bin/jpf Rand

JavaPathfinder v4.1 - (C) 1999-2007 RIACS/NASA Ames Research Center
--------------------------------- system under test
application: /Users/pcmehlitz/tmp/Rand.java

---------------------------------- search started: 5/23/07 11:48 PM
a=1
  b=0
  c=-1

---------------------------------- results
no errors detected

---------------------------------- search finished: 5/23/07 11:48 PM
>
> bin/jpf +vm.enumerate_random=true Rand
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================================= system under test
application: /Users/pcmehlitz/tmp/Rand.java

================================= search started: 5/23/07 11:49 PM
a=0
  b=0
    c=0
  b=1
    c=0
  b=2

================================= error #1
gov.nasa.jpf.jvm.NoUncaughtExceptionsProperty
java.lang.ArithmeticException: division by zero
    at Rand.main(Rand.java:15)

....
>

>
• JPF explores multiple possible executions GIVEN THE SAME CONCRETE INPUT
Another Example

```java
public class Racer implements Runnable {

    int d = 42;

    public void run () {
        doSomething(1000); // (1)
        d = 0;            // (2)
    }

    public static void main (String[] args){
        Racer racer = new Racer();
        Thread t = new Thread(racer);
        t.start();

        doSomething(1000); // (3)
        int c = 420 / racer.d; // (4)
        System.out.println(c);
    }

    static void doSomething (int n) {
        // not very interesting..
        try { Thread.sleep(n); } catch (InterruptedException ix) {} }
```
> bin/jpf Racer
JavaPathfinder v4.1 - (C) 1999-2007 RIACS/NASA Ames Research Center
================================= system under application: /Users/pcmehlitz/tmp/Racer.java

================================= search starts
10
10

================================= error #1
gov.nasa.jpf.jvm.NoUncaughtExceptionsProperty
java.lang.ArithmeticException: division by zero
    at Racer.main(Racer.java:20)

================================= trace #1
================================= transition #0 thread: 0
gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {main}
    [282 insn w/o sources]
    Racer.java:15 : Racer racer = new Racer();
    Racer.java:16 : public class Racer implements Runnable {
        [1 insn w/o sources]
        Racer.java:3 : int d = 42;
    Racer.java:15 : Racer racer = new Racer();
    Racer.java:16 : Thread t = new Thread(racer);
        [51 insn w/o sources]
    Racer.java:16 : Thread t = new Thread(racer);
    Racer.java:17 : t.start();

================================= transition #1 thread: 0
import java.util.concurrent.TimeUnit;

public class Racer {
    static int d = 0;
    public void doSomething() {
        try {
            Thread.sleep(1000);
        } catch (InterruptedException e) {
            // ignore
        }
    }

    public static void main(String[] args) {
        new Racer().doSomething();
    }
}

---

 transition #1 thread: 0

 gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {main, Thread-0}
 Racer.java:17 : t.start();
 Racer.java:19 : doSomething(1000); // (3)
 Racer.java:6 : try { Thread.sleep(n); } catch (InterruptedException ix) {} 
 [2 insn w/o sources]
 Racer.java:6 : try { Thread.sleep(n); } catch (InterruptedException ix) {} 
 Racer.java:/
 Racer.java:20 : int c = 420 / racer.d; // (4)
---

 transition #2 thread: 1

 gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {main, Thread-0}
 Racer.java:10 : doSomething(1000); // (1)
 Racer.java:6 : try { Thread.sleep(n); } catch (InterruptedException ix) {} 
 [2 insn w/o sources]
 Racer.java:6 : try { Thread.sleep(n); } catch (InterruptedException ix) {} 
 Racer.java:7 :
 Racer.java:11 : d - 0; // (2)
---

 transition #3 thread: 1

 gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {main, Thread-0}
 Racer.java:11 : d = 0; // (2)
 Racer.java:12 :
---

 transition #4 thread: 0

 gov.nasa.jpf.jvm.choice.ThreadChoiceFromSet {main}
 Racer.java:20 : int c = 420 / racer.d; // (4)

---

search finished: 5/24/07 12:32 AM
>
Two Essential Capabilities

- **Backtracking**
  - Means that JPF can restore previous execution states, to see if there are unexplored choices left.
    - While this is theoretically can be achieved by re-executing the program from the beginning, backtracking is a much more efficient mechanism if state storage is optimized.

- **State matching**
  - JPF checks every new state if it already has seen an equal one, in which case there is no use to continue along the current execution path, and JPF can backtrack to the nearest non-explored non-deterministic choice.
    - Heap and thread-stack snapshots.
The Challenge

```c
int x, y, r;
int *p, *q, *z;
int **a;

thread_1(void) /* initialize p, q, and r */
{
    p = &x;
    q = &y;
    z = &r;
}

thread_2(void) /* swap contents of x and y */
{
    r = *p;
    *p = *q;
    *q = r;
}

thread_3(void) /* access z via a and p */
{
    a = &p;
    *a = z;
    **a = 12;
}
```

3 asynchronous threads
accessing shared data
3 statements each
how many test runs are needed to check that no data corruption can occur?
The Challenge (cont.)

- The number of possible thread interleavings is...
  \[ \frac{9!}{6! \cdot 3!} \cdot \frac{6!}{3! \cdot 3!} \cdot \frac{3!}{3!} = 1,680 \text{ possible executions} \]

- Placing 3 sets of 3 tokens in 9 slots

- Are all these executions okay?
- Can we check them all? Should we check them all?
- In classic system testing, how many would normally be checked?

State Explosion!!
JPF’s Solution

- **Configurable search strategy**
  - Directing the search so that defects can be found quicker
    - A debugging tool instead of a “proof” system.
  - User can easily develop his/her own strategy

- **Host VM Execution**
  - Delegate execution to the underlying host VM (no state tracking).

- **Reducing state storage**
  - State collapsing
    - Premise: only a tiny part of the state is changed upon each transaction. (e.g. a single stack frame)
    - Dividing a state into components, use hashtable to index a specific value for a component.
Solution - State Collapsing

Java Virtual Machine State

Static Area
- Fields
- Monitor

Dynamic Area
- Fields
- Monitor

Thread List
- ThreadInfo
- Frame

Collapse

Fields Pool

Monitor Pool

Frame Pool

Integer Vector
Solution (3) – State Reduction

- Orthogonal (our focus)
- State Abstraction
- Partial Order Reduction
Abstraction

- Eliminate details irrelevant to the property
- Obtain simple finite models sufficient to verify the property

Disadvantage
- Loss of Precision: False positives/negatives
Data Abstraction

Abstraction Function $h : S \to S'$
Abstraction proceeds component-wise, where variables are components.
How do we Abstract Behaviors?

- Abstract domain $A$
  - Abstract concrete values to those in $A$

- Then compute transitions in the abstract domain
Data Type Abstraction

Code

int x = 0;
if (x == 0)
x = x + 1;

Abstract Data domain

int

( n<0) : NEG
( n==0) : ZERO
( n>0) : POS

Si gns

x = ZERO;
if ( Si gns. eq( x, ZERO) )
x = Si gns. add( x, POS);

NEG ZERO POS
Existential/Universal Abstractions

Existential

- Make a transition from an abstract state if at least one corresponding concrete state has the transition.
- Abstract model $M'$ simulates concrete model $M$

Universal

- Make a transition from an abstract state if all the corresponding concrete states have the transition.
Existential Abstraction (Over-approximation)
Universal Abstraction (Under-Approximation)
Guarantees from Abstraction

Assume $M'$ is an abstraction of $M$

- **Strong Preservation:**
  - $P$ holds in $M'$ iff $P$ holds in $M$

- **Weak Preservation:**
  - $P$ holds in $M'$ implies $P$ holds in $M$
Guarantees from Exist. Abstraction

Let $\varphi$ be a *hold-for-all-paths* property

$M'$ existentially abstracts $M$

**Preservation Theorem**

$M' \models \varphi \rightarrow M \models \varphi$

Converse does not hold

$M' \not\models \varphi \nrightarrow M \not\models \varphi$

$M' \not\models \varphi$: counterexample may be spurious
Guarantees from Univ. Abstraction

Let $\varphi$ be an existential-quantified property and $M$ simulates $M'$

Preservation Theorem

$$M' \not\models \varphi \rightarrow M \not\models \varphi$$

Converse does not hold

$$M \not\models \varphi \rightarrow M' \not\models \varphi$$
Spurious counterexample in Over-approximation

Diagram showing states and transitions, with labels for deadend states, bad states, and failure state.
Refinement

- **Problem:** Deadend and Bad States are in the same abstract state.
- **Solution:** Refine abstraction function.
- The sets of Deadend and Bad states should be separated into different abstract states.
Refinement
Automated Abstraction/Refinement

- **Good abstractions are hard to obtain**
  - Automate both Abstraction and Refinement processes

- **Counterexample-Guided AR (CEGAR)**
  - Build an abstract model $M'$
  - Model check property $P$, $M' \models P$?
  - If $M' \models P$, then $M \models P$ by Preservation Theorem
  - Otherwise, check if Counterexample (CE) is spurious
  - Refine abstract state space using CE analysis results
  - Repeat
Counterexample-Guided Abstraction-Refinement (CEGAR)

1. Build New Abstract Model
2. Model Check
   - Pass: No Bug
   - Fail:
     - Spurious CE: Obtain Refinement Cue
     - Real CE: Check Counterexample
       - Bug