

Garbage Collection

Problem: When items are allocated from the heap, how do we know when to free them?

- **Solution 1:** The programmer explicitly frees the memory.
 - Pros: Easy for compiler
 - Cons: Hard for programmer
 - Ex: C/C++
- **Solution 2:** Free any variables that aren't live.
 - Actually, use a heuristic of freeing variables that aren't reachable.
 - This is garbage collection.

Mark-and-Sweep

- Can represent heap allocated records as a directed graph
- Step 1: Mark records with a DFS
- Step 2: Sweep the heap looking for unmarked nodes
- Garbage is put into the *freelist*

Algorithm

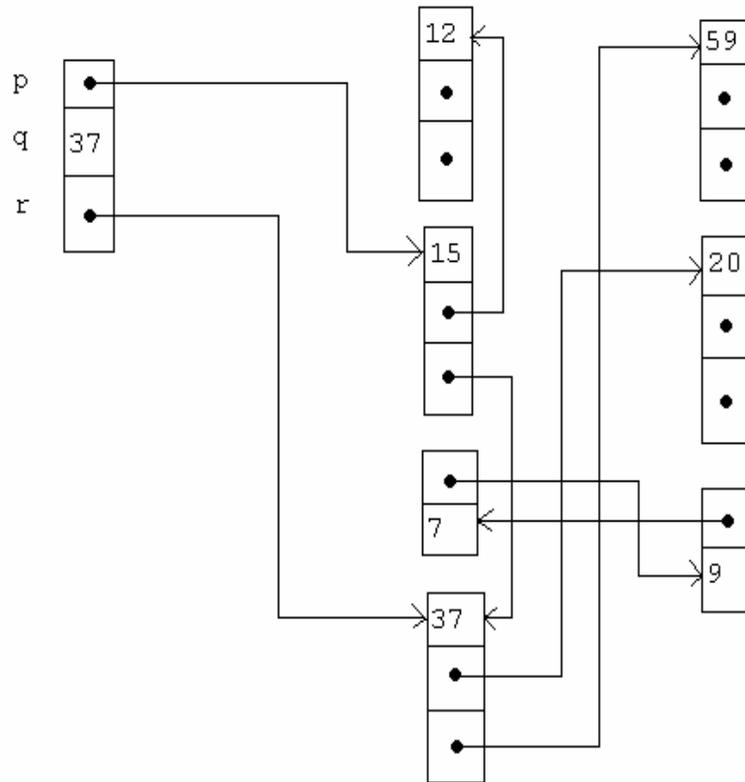
Mark phase

- For each root x , do DFS(x)

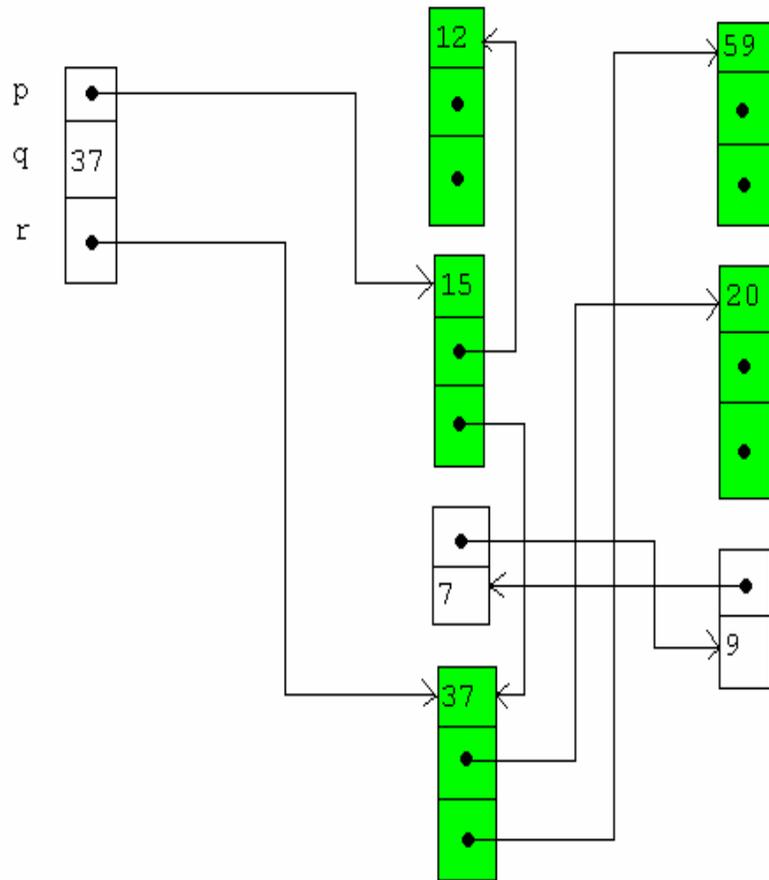
Sweep Phase

- $p \leftarrow$ First address in heap
- While $p <$ last address in heap
 1. If record p is marked, unmark p
 2. Else, let f_1 be the first field in p
 - $p.f_1 \leftarrow$ freelist
 - freelist $\leftarrow p$
 3. $p \leftarrow p +$ (size of record p)

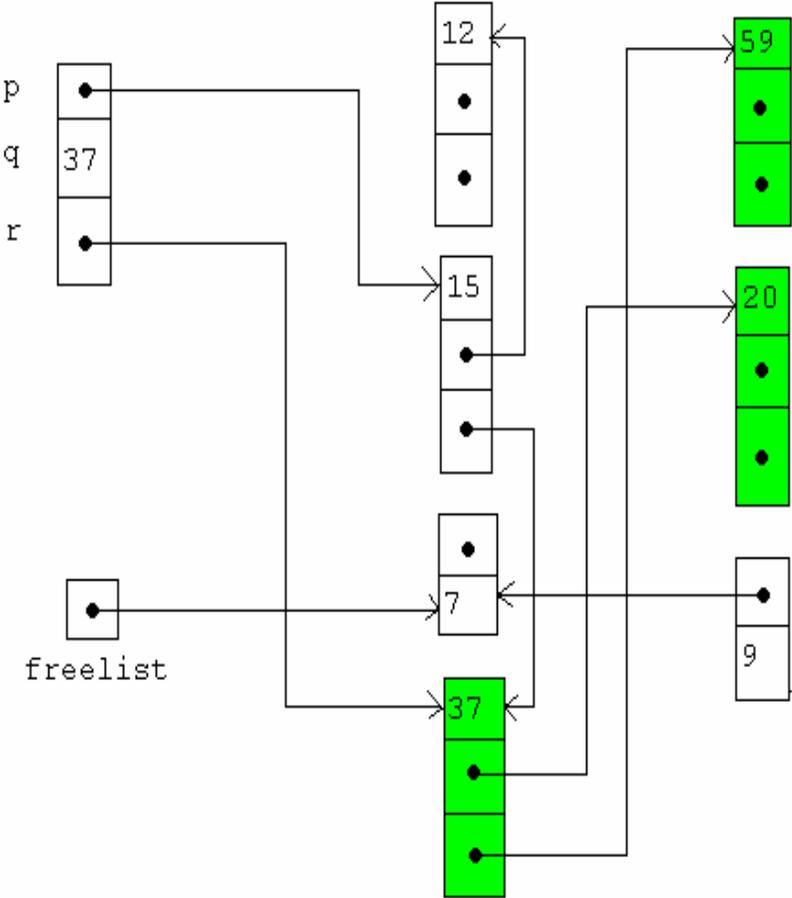
Example
Beginning Heap



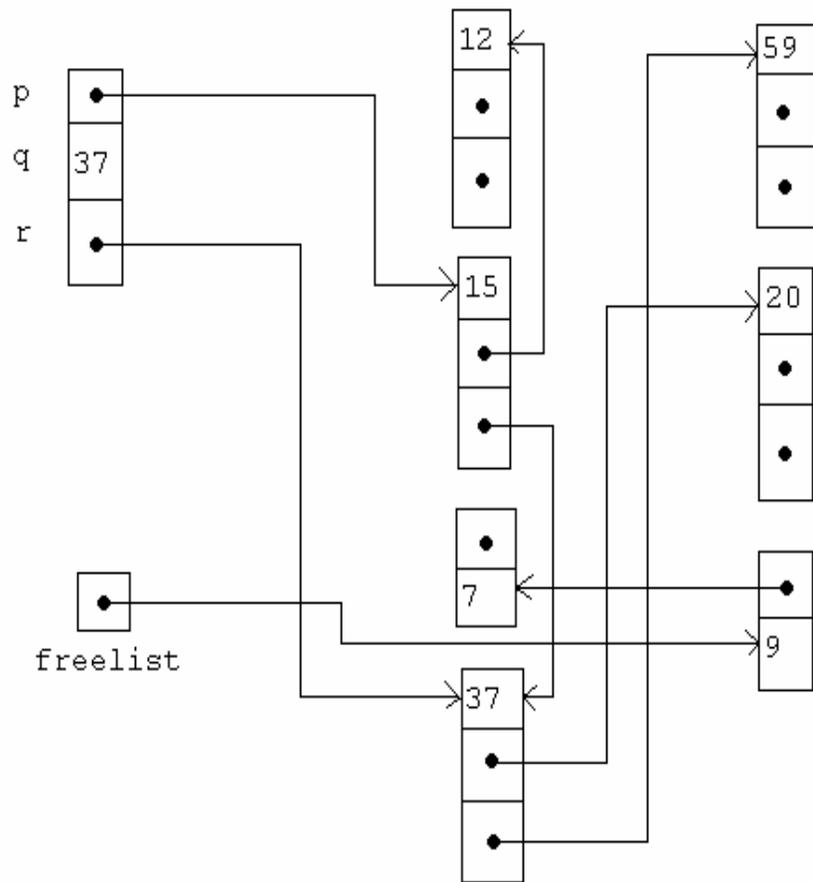
After mark phase



During Sweep phase



After Sweep phase



Complexity

- R = number of reachable records
- H = size of the heap
- Amortized cost: $(C_1R + C_2H) / (H - R)$
- What does this mean?

Implementation Issues

- If we use recursion, the run-time stack could reach a size of H activation records!
- If we use an explicit stack, we could still have a stack of size H words!
- Pointer Reversal – Use the elements in the heap as the stack itself, reversing the pointers as you go
- Array of Freelists – $\text{freelist}[i]$ stores records of size i
- Fragmentation – Internal and External

Copying Collection

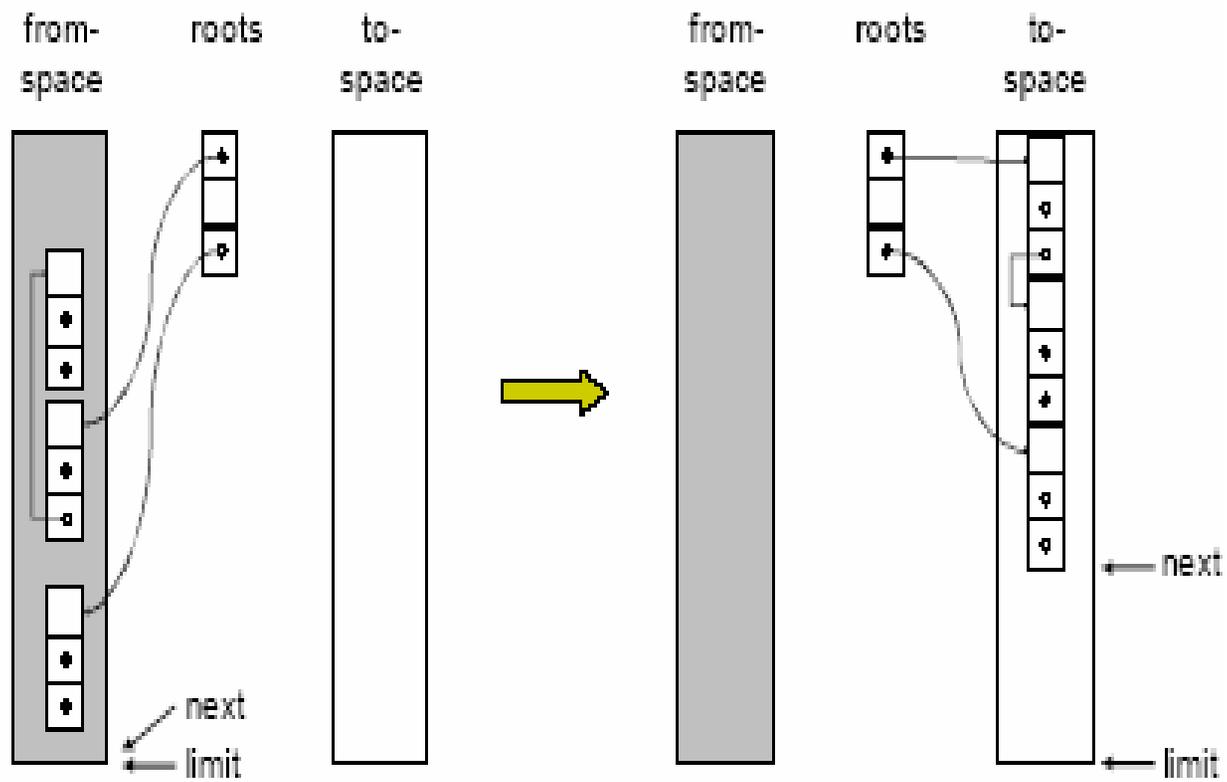
- traverse graph
- need two heaps
 - from-space (working heap)
 - to-space (heap for garbage collection)
- redirect roots to to-space (new space)
- copy records from old space to new space
 - create isomorphic copy in to-space
- after all records moved, swap new and old space
- copy is contiguous – no external fragmentation

Advantage:

- simplicity - no stack or pointer reversal required
- doesn't move garbage
- makes free space contiguous,
 - allocation cheap
 - no freelist

Disadvantage:

- half of memory is wasted
- maintain accurate pointer
 - heap pointers (next, scan)
 - record pointer



Pointer Forwarding

Given pointer p :

Redirect record from from-space to to-space

Case 1:

If p points to already copied record, $p.fl$ is forwarding pointer that tells where copy is in to-space.

Return forwarding pointer

Case 2:

If p points to record that has not been copied, copy record to the next free location in to-space and store forwarding pointer into $p.fl$. Return forwarding pointer

Case 3:

p points outside of from-space (to-space/not garbage collected arena)

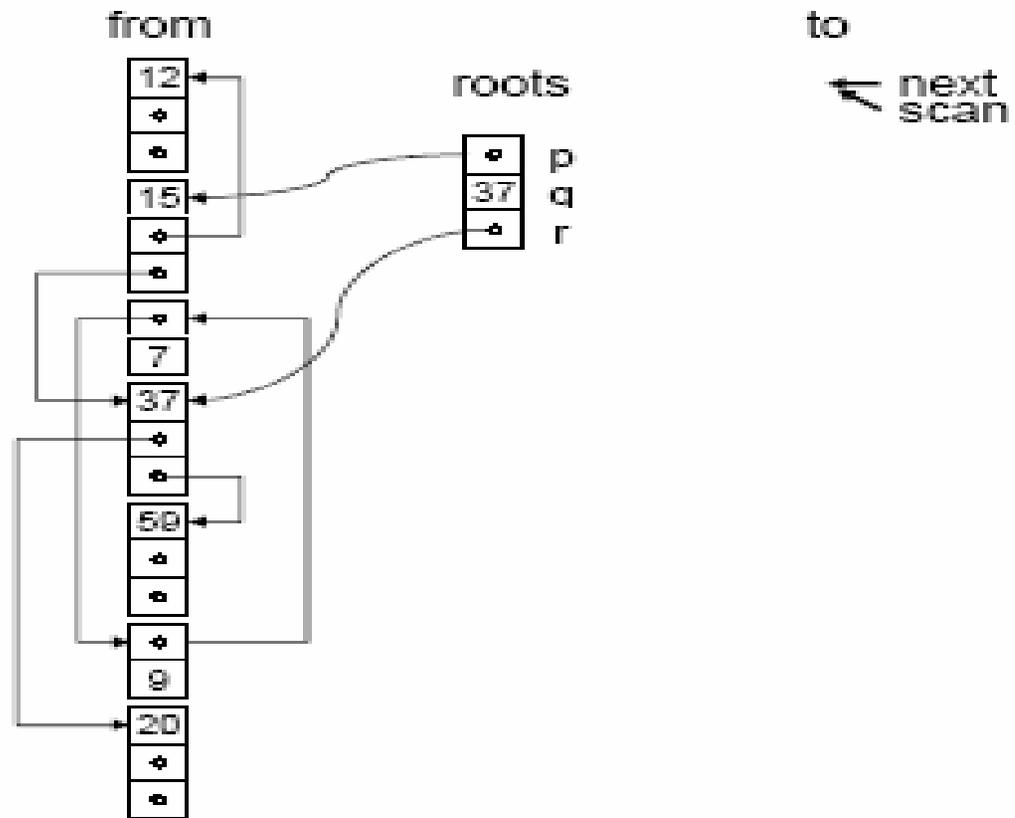
```
forward (p) {  
  if p points t from-space  
    then if p.f1 points to to-space  
      then return p.f1  
    else for each field fi of p  
      next.fi := p.fi  
      p.f1 := next  
      next := next + (size of *p)  
      return p.f1  
  else return p
```

Cheney's Algorithm

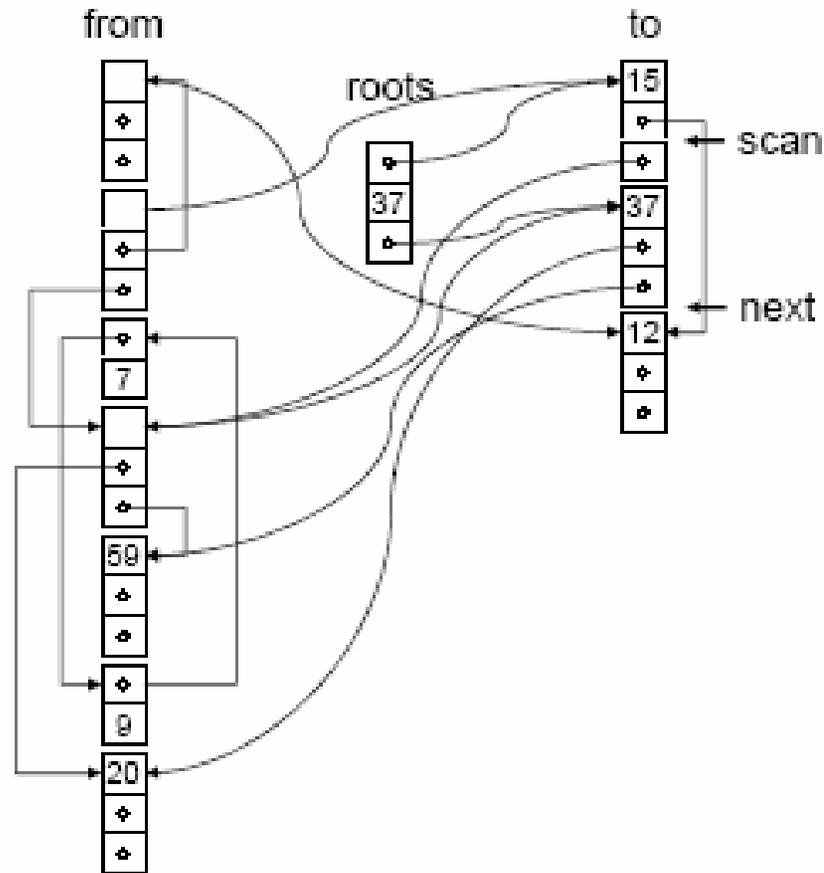
- Performs a breadth-first copy
- 1. Scan and Next points to start of to-space
 - Roots are forwarded
 - Records reachable from roots copied to to-space
 - Next pointer incremented accordingly
- 2. Scan \leftrightarrow Next contain records copied to to-space but fields not yet forwarded (ie fields point to from-space)
 - Scanning a record
 - Forwards fields of each record not yet in to-space
 - Both next and scan are incremented
 - Garbage collection done when scan reaches next

```
scan := begin-of-to-space
next := scan
for each root r
  r := forward(r)
while scan < next
  for each field fi of *scan
    scan.fi := forward(scan.fi)
  scan := scan + (size of *scan)
```

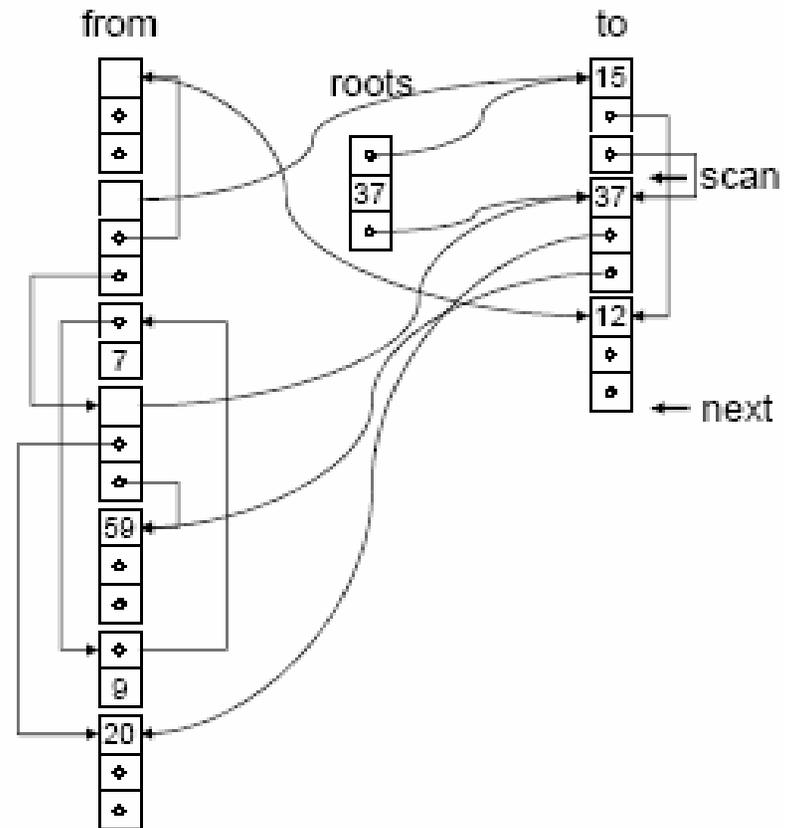
Example Before



Scan and Forward

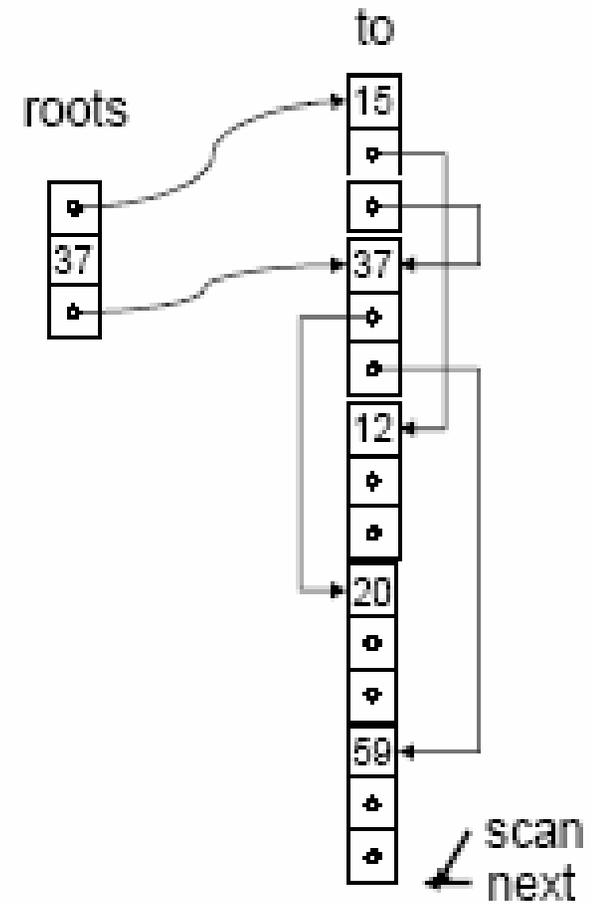
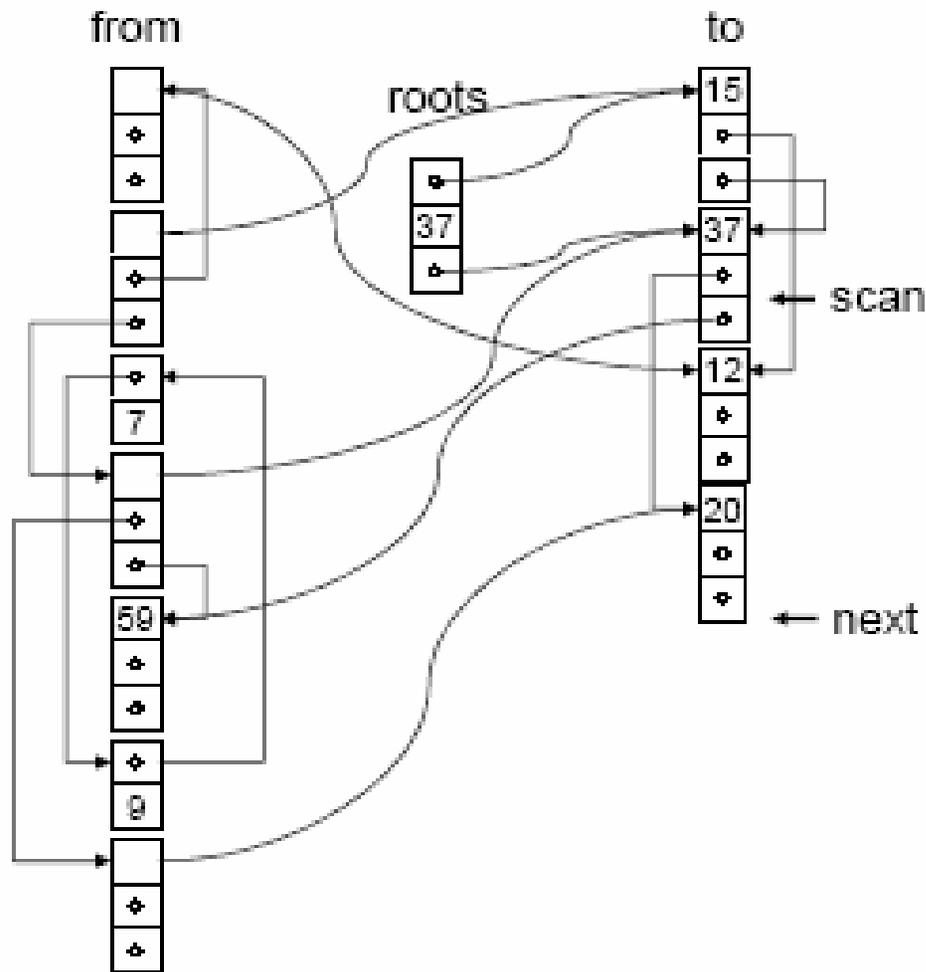


Scan and Forward



Scan and Forward

Done



Bad locality of reference:

- breadth-first copy
 - records end far apart in memory
 - bad for virtual memory and caching

Solution:

Hybrid of breadth-first and depth-first

Use breadth-first but forward the child of a node immediately, if possible

Cost

- breadth-first copying & hybrid

Amortized cost $C_3 R / (H/2 - R)$

$C_3 R$ = Total cost of collection based on number of records copied

$H/2 - R$ = heap divided by two – words/records to allocate before next collection

$H \gg R$, cost approaches 0