Futures, Scheduling, and Work Distribution

Companion slides for
The Art of Multiprocessor
Programming
by Maurice Herlihy & Nir Shavit

How to write Parallel Apps?

- How to
 - split a program into parallel parts
 - In an effective way
 - Thread management

$$(C) = (A) \bullet (B)$$

$$c_{ij} = \sum_{k=0}^{N-1} a_{ki} * b_{jk}$$

```
class Worker extends Thread {
 int row, col;
 Worker(int row, int col) {
  this.row = row; this.col = col;
 public void run() {
  double dotProduct = 0.0;
  for (int i = 0; i < n; i++)
   dotProduct += a[row][i] * b[i][col];
  c[row][col] = dotProduct;
 }}}
```

```
class Worker extends Thread {
 int row, col;
 Worker(int row, int col)
  this.row = row; this.col =
                             a thread
 public void run() {
  double dotProduct = 0.0;
  for (int i = 0; i < n; i++)
   dotProduct += a[row][i] * b[i][col];
  c[row][col] = dotProduct;
```

```
class Worker extends Thread {
 int row, col;
 Worker (int row, int col) {
  this.row = row; this.col = col;
 public void run Which matrix entry
  for (int i = 0; i < n; ito)compute
   dotProduct += a[row][i] * b[i][col];
  c[row][col] = dotProduct;
```

```
class Worker extends Thread {
 int row, col;
 Worker(int row, int col) {
  this.row = row; this.col = col;
Actual computation
 public void run() {
  double dotProduct = 0
  for (int i = 0: i < n: i+
   dotProduct += a[row][i] * b[i][col];
  c[row][col] = dotProduct;
```

```
void multiply() {
 Worker[][] worker = new Worker[n][n];
 for (int row ...)
  for (int col ...)
   worker[row][col] = new Worker(row,col);
 for (int row ...)
  for (int col ...)
   worker[row][col].start();
 for (int row ...)
  for (int col ...)
   worker[row][col].join();
```

```
void multiply() {
 Worker[][] worker = new Worker[n][n];
 for (int row ...)
  for (int col ...)
   worker[row][col] = new Worker(row,col);
 tor (int row ...)
  for (int col ...)
   worker[row][col].start();
 for (int row ...)
                                Create nxn
  for (int col ...)
                                  threads
   worker[row][col].join();
```

```
void multiply() {
 Worker[][] worker = new Worker[n][n];
 for (int row ...)
                                 Start them
  for (int col ...)
                      = new Worker(row,col);
   worker[row][ed
 for (int row ...)
  for (int col ...)
   worker[row][col].start();
 for (int row ...)
  for (int col ...)
   worker[row][col].join();
```

```
void multiply() {
 Worker[][] worker = new Worker[n][n];
 for (int row ...)
                                  Start them
  for (int col ...)
                      = new Worker(row,col);
   worker[row][ed
 for (int row ...)
  for (int col ...)
   worker[row][col].start();
 for (int row ...)
                                     Wait for
  for (int col ...)
                                     them to
   worker[row][col].join();
                                      finish
```

```
void multiply() {
 Worker[][] worker = new Worker[n][n];
 for (int row ...)
                                 Start them
  for (int col ...)
                     = new Worker(row,col);
   worker[row][e
 for (int row ...)
       What's wrong with this
   WC
                 picture?
                                    Wait for
  for (int col ...)
                                    them to
   worker[row][col].join();
                                      finish
```

Thread Overhead

- Threads Require resources
 - Memory for stacks
 - Setup, teardown
- Scheduler overhead
- Worse for short-lived threads

Thread Pools

- More sensible to keep a pool of longlived threads
- Threads assigned short-lived tasks
 - Runs the task
 - Rejoins pool
 - Waits for next assignment

Thread Pool = Abstraction

- · Insulate programmer from platform
 - Big machine, big pool
 - And vice-versa
- Portable code
 - Runs well on any platform
 - No need to mix algorithm/platform concerns

ExecutorService Interface

- In java.util.concurrent
 - Task = Runnable object
 - If no result value expected
 - Calls run() method.
 - Task = Callable<T> object
 - · If result value of type T expected
 - Calls T call() method.

Future < T>

```
Callable<T> task = ...;
...
Future<T> future = executor.submit(task);
...
T value = future.get();
```

Future < T>

```
Callable<T> task = ...;

Future<T> future = executor.submit(task);

...

T value = future.get();

Submitting a Callable<T> task
returns a Future<T> object
```

Future < T>

```
Callable<T> task = ...;
...

Future<T> future = executor.submit(task);
...

T value = future.get();
```

The Future's get() method blocks until the value is available

Future<?>

```
Runnable task = ...;
...
Future<?> future = executor.submit(task);
...
future.get();
```

Future<?>

```
Future<?> future = executor.submit(task);
...
future.get();

Submitting a Runnable task
returns a Future<?> object
```

Future<?>

```
Runnable task = ...;
...
Future<?> future = executor.submit(task);
...
future.get();
```

The Future's get() method blocks until the computation is complete

Note

- Executor Service submissions
 - Like New England traffic signs
 - Are purely advisory in nature
- The executor
 - Like the New England driver
 - Is free to ignore any such advice
 - And could execute tasks sequentially ...

Matrix Addition

$$\begin{pmatrix} C_{00} & C_{00} \\ C_{10} & C_{10} \end{pmatrix} = \begin{pmatrix} A_{00} + B_{00} & B_{01} + A_{01} \\ A_{10} + B_{10} & A_{11} + B_{11} \end{pmatrix}$$

Matrix Addition

$$\begin{pmatrix} C_{00} & C_{00} \\ C_{10} & C_{10} \end{pmatrix} = \begin{pmatrix} A_{00} + B_{00} \\ A_{10} + B_{10} \end{pmatrix} \begin{pmatrix} B_{01} + A_{01} \\ A_{11} + B_{11} \end{pmatrix}$$
 4 parallel additions

```
class AddTask implements Runnable {
  Matrix a, b; // multiply this!
  public void run() {
    if (a.dim == 1) {
    c[0][0] = a[0][0] + b[0][0]; // base case
   } else {
    (partition a, b into half-size matrices a<sub>ii</sub> and b<sub>ii</sub>)
                                              This is not real Java code (see notes)
    Future < ?> f_{00} = exec.submit(add(a_{00}, b_{00}));
    Future < ?> f_{11} = exec.submit(add(a_{11},b_{12}))
    f<sub>00</sub>.get(); ...; f<sub>11</sub>.get();
   }}
```

```
class AddTask implements Runnable {
  Matrix a, b; // multiply this!
  public void run() {
   if (a.dim == 1) {
    c[0][0] = a[0][0] + b[0][0]; // base case
    (partition a, b into half-size matrices a;; and b;;)
    Future < ?> f_{00} = exec.submit(add(a_{00},b_{00}));
    Future<?> f_{11} = exec.submit(add(a_{11},b_{11}));
    f<sub>00</sub>.get(); ...; f<sub>11</sub>.get();
                               Base case: add directly
```

```
class AddTask implements Runnable {
  Matrix a, b; // multiply this!
  public void run() {
   if (a.dim == 1) {
    c[0][0] = a[0][0] + b[0][0]; // base case
    (partition a, b into half-size matrices a; and b;)
    Future<?> f<sub>00</sub> - exec.submit(add(a<sub>00</sub>,b<sub>00</sub>)),
    Future < ?> f_{11} = exec.submit(add(a_{12}))
    f<sub>00</sub>.get(); ...; f<sub>11</sub>.get();
                         Constant-time operation
```

```
class AddTask implements Runnable {
  Matrix a, b; // multiply this!
  public void run() {
   if (a.dim == 1) {
    c[0][0] = a[0][0] + b[0][0]; // base case
   } else {
    <u>(partition a. b into half-size matrices a.. an</u>d b<sub>ii</sub>)
    Future < ?> f_{00} = exec.submit(add(a_{00},b_{00}));
    Future < ?> f_{11} = exec.submit(add(a_{11},b_{11}));
    r<sub>nn</sub>.get(); ...; r<sub>11</sub>.get();
                                            Submit 4 tasks
```

```
class AddTask implements Runnable {
  Matrix a, b; // multiply this!
  public void run() {
   if (a.dim == 1) {
    c[0][0] = a[0][0] + b[0][0]; // base case
   } else {
    (partition a, b into half-size matrices a<sub>ii</sub> and b<sub>ii</sub>)
    Future < ?> f_{00} = exec.submit(add(a_{00},b_{00}));
    Future < ?> f_{11} = exec.submit(add(a_{11},b_{11}));
    f<sub>00</sub>.get(); ...; f<sub>11</sub>.get();
                                      Let them finish
```

Dependencies

- Matrix example is not typical
- Tasks are independent
 - Don't need results of one task ...
 - To complete another
- Often tasks are not independent

Fibonacci

$$F(n) = 0 \text{ or } 1$$

$$F(n-1) + F(n-2) \text{ otherwise}$$

- Note
 - potential parallelism
 - Dependencies

Disclaimer

- This Fibonacci implementation is
 - Egregiously inefficient
 - So don't deploy it!
 - But illustrates our point
 - How to deal with dependencies
- · Exercise:
 - Make this implementation efficient!

Multithreaded Fibonacci

```
class FibTask implements Callable<Integer> {
 static ExecutorService exec =
Executors.newCachedThreadPool();
 int arg;
 public FibTask(int n) {
  arg = n;
 public Integer call() {
  if (arg > 2) {
   Future<Integer> left = exec.submit(new FibTask(arg-1));
   Future<Integer> right = exec.submit(new FibTask(arg-2));
   return left.get() + right.get();
  } else {
   return 1;
  }}}
```

Multithreaded Fibonacci

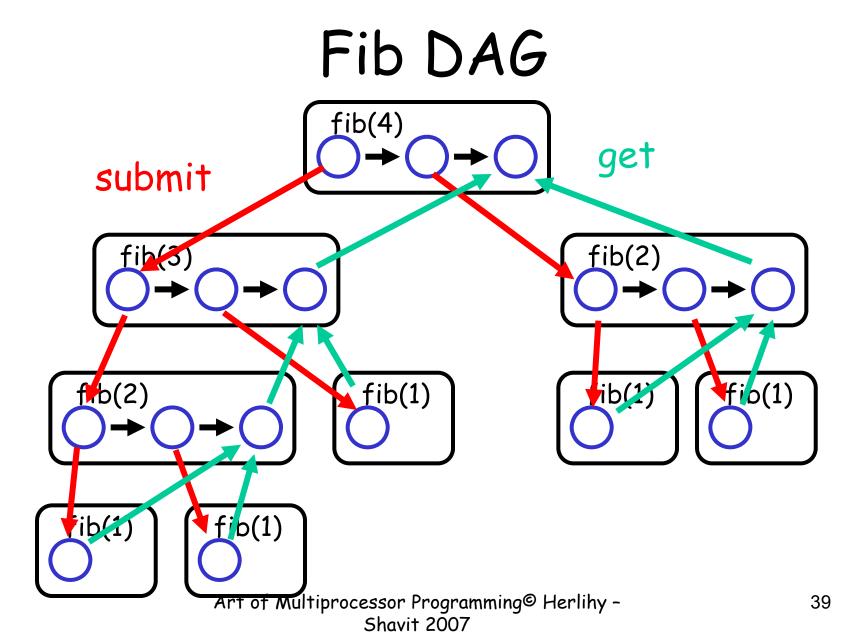
```
class FibTask implements Callable<Integer> {
 static ExecutorService exec =
Executors.newCachedThreadPool();
 int arg;
 public FibTask(int n) {
                                  Parallel calls
  arq = n:
 public Integer call() {
  if (arg > 2) {
   Future<Integer> left = exec.submit(new FibTask(arg-1));
   Future<Integer> right = exec.submit(new FibTask(arg-2));
   return left.get() + right.get();
  } else {
   return 1;
  }}}
```

Multithreaded Fibonacci

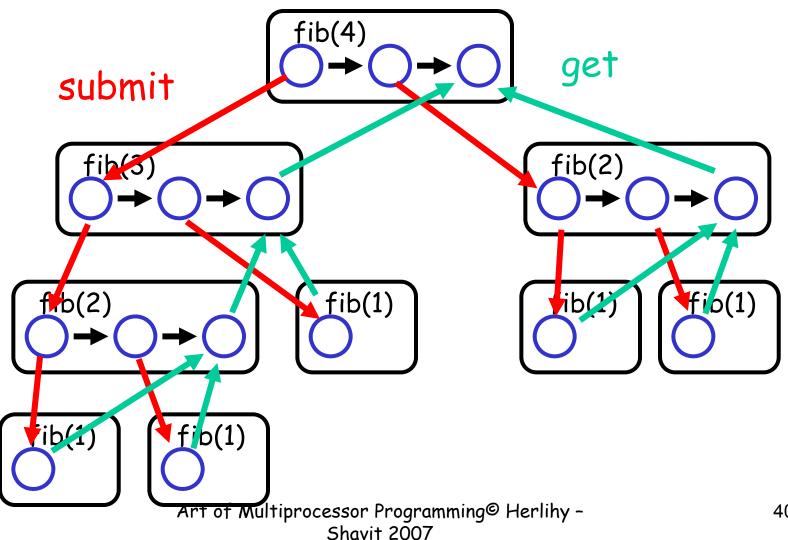
```
class FibTask implements Callable<Integer> {
 static ExecutorService exec =
Executors.newCachedThreadPool();
 int arg;
 public FibTask(int n) {
Pick up & combine results
 public Integer call() {
  if (arg > 2) {
   Future<Integer> left = exec.submit(new FibTask(arg-1));
               ger> right = exeq submit(new FibTask(arg-2));
   return left.get() + right.get();
   else {
   return 1;
  }}}
```

Dynamic Behavior

- Multithreaded program is
 - A directed acyclic graph (DAG)
 - That unfolds dynamically
- Each node is
 - A single unit of work



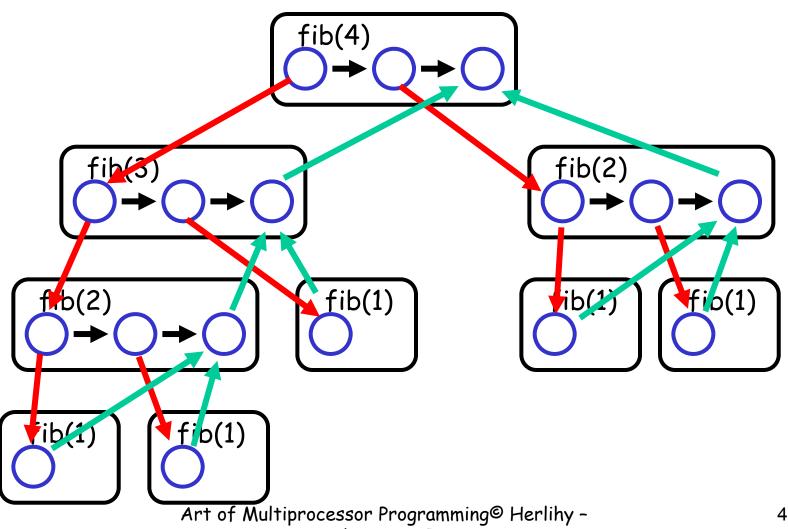
Arrows Reflect Dependencies



How Parallel is That?

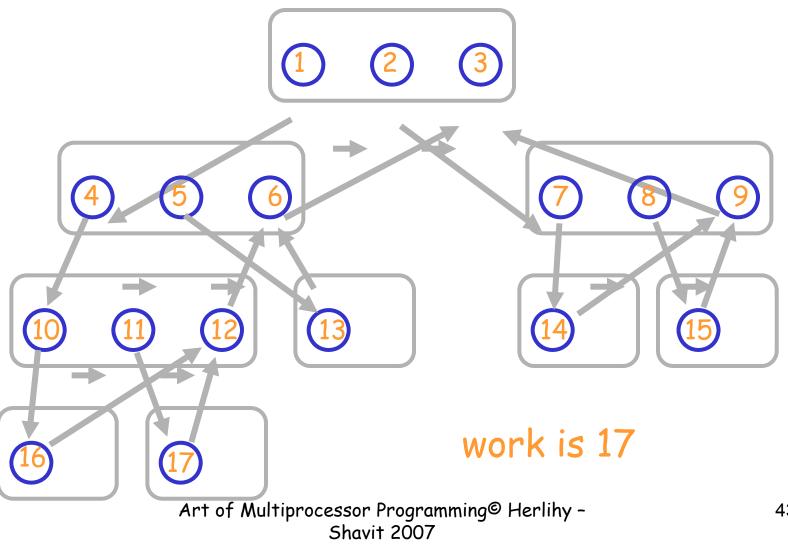
- Define work:
 - Total time on one processor
- Define critical-path length:
 - Longest dependency path
 - Can't beat that!

Fib Work

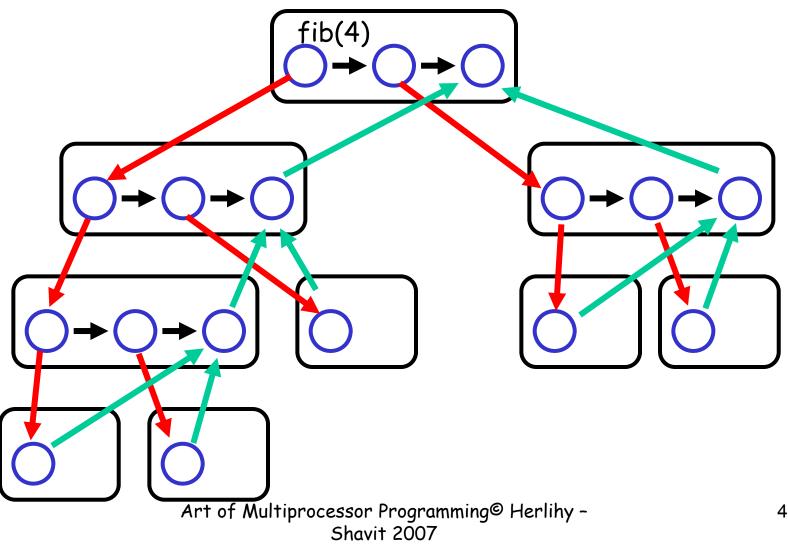


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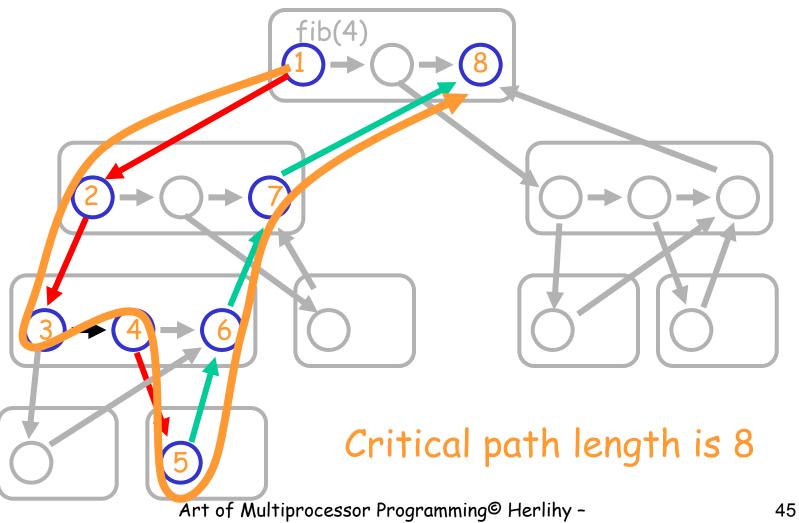
Fib Work



Fib Critical Path



Fib Critical Path



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Notation Watch

- T_P = time on P processors
- T_1 = work (time on 1 processor)
- T_{∞} = critical path length (time on ∞ processors)

Simple Bounds

- $T_P \ge T_1/P$
 - In one step, can't do more than P work
- T_P ≥ T_∞
 - Can't beat infinite resources

More Notation Watch

- Speedup on P processors
 - Ratio T₁/T_P
 - How much faster with P processors
- · Linear speedup
 - $T_1/T_P = \Theta(P)$
- Max speedup (average parallelism)
 - T₁/T_∞

Matrix Addition

$$\begin{pmatrix} C_{00} & C_{00} \\ C_{10} & C_{10} \end{pmatrix} = \begin{pmatrix} A_{00} + B_{00} & B_{01} + A_{01} \\ A_{10} + B_{10} & A_{11} + B_{11} \end{pmatrix}$$

Matrix Addition

$$\begin{pmatrix} C_{00} & C_{00} \\ C_{10} & C_{10} \end{pmatrix} = \begin{pmatrix} A_{00} + B_{00} \\ A_{10} + B_{10} \end{pmatrix} \begin{pmatrix} B_{01} + A_{01} \\ A_{11} + B_{11} \end{pmatrix}$$
 4 parallel additions

- Let $A_P(n)$ be running time
 - For n x n matrix
 - on P processors
- For example
 - $A_1(n)$ is work
 - $A_{\infty}(n)$ is critical path length

• Work is Partition, synch, etc $A_1(n) = 4 A_1(n/2) + \Theta(1)$ 4 spawned additions

Work is

$$A_1(n) = 4 A_1(n/2) + \Theta(1)$$

= $\Theta(n^2)$

Same as double-loop summation

Critical Path length is

$$A_{\infty}(n) = A_{\infty}(n/2) + \Theta(1)$$
spawned additions in parallel
Partition, synch, etc

Critical Path length is

$$A_{\infty}(n) = A_{\infty}(n/2) + \Theta(1)$$
$$= \Theta(\log n)$$

Matrix Multiplication Redux

$$(C) = (A) \bullet (B)$$

Matrix Multiplication Redux

$$\begin{pmatrix} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{C}_{21} & \mathbf{C}_{22} \end{pmatrix} = \begin{pmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \end{pmatrix} \bullet \begin{pmatrix} \mathbf{B}_{11} & \mathbf{B}_{12} \\ \mathbf{B}_{21} & \mathbf{B}_{22} \end{pmatrix}$$

First Phase ...

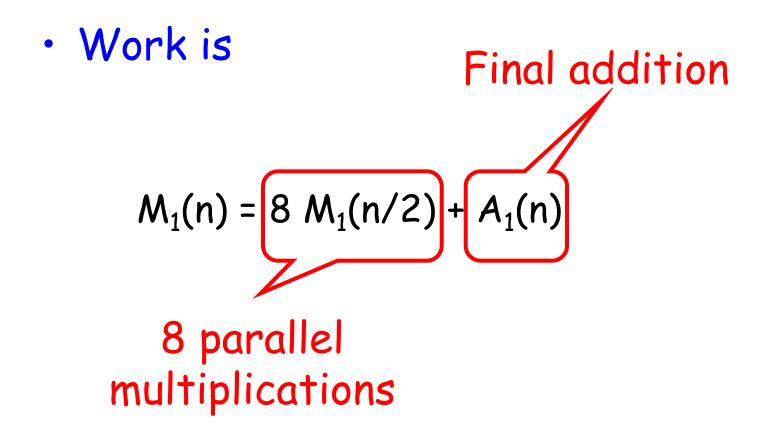
$$\begin{pmatrix} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{C}_{21} & \mathbf{C}_{22} \end{pmatrix} = \begin{pmatrix} \mathbf{A}_{11} \mathbf{B}_{11} + \mathbf{A}_{12} \mathbf{B}_{21} \\ \mathbf{A}_{21} \mathbf{B}_{11} + \mathbf{A}_{22} \mathbf{B}_{21} \\ \mathbf{A}_{21} \mathbf{B}_{12} + \mathbf{A}_{22} \mathbf{B}_{22} \end{pmatrix}$$

$$8 \text{ multiplications}$$

Second Phase ...

$$\begin{pmatrix} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{C}_{21} & \mathbf{C}_{22} \end{pmatrix} = \begin{pmatrix} \mathbf{A}_{11}\mathbf{B}_{11} + \mathbf{A}_{12}\mathbf{B}_{21} & \mathbf{A}_{11}\mathbf{B}_{12} + \mathbf{A}_{12}\mathbf{B}_{22} \\ \mathbf{A}_{21}\mathbf{B}_{11} + \mathbf{A}_{22}\mathbf{B}_{21} & \mathbf{A}_{21}\mathbf{B}_{12} + \mathbf{A}_{22}\mathbf{B}_{22} \end{pmatrix}$$

$$4 \text{ additions}$$



Work is

$$M_1(n) = 8 M_1(n/2) + \Theta(n^2)$$

= $\Theta(n^3)$

Same as serial triple-nested loop

Critical path length is

Final addition
$$M_{\infty}(n) = M_{\infty}(n/2) + A_{\infty}(n)$$
 Half-size parallel multiplications

Critical path length is

$$M_{\infty}(n) = M_{\infty}(n/2) + A_{\infty}(n)$$

$$= M_{\infty}(n/2) + \Theta(\log n)$$

$$= \Theta(\log^2 n)$$

Parallelism

- $M_1(n)/M_\infty(n) = \Theta(n^3/\log^2 n)$
- To multiply two 1000×1000 matrices
 - $-1000^3/10^2=10^7$
- Much more than number of processors on any real machine

Shared-Memory Multiprocessors

- Parallel applications
 - Do not have direct access to HW processors
- Mix of other jobs
 - All run together
 - Come & go dynamically

Ideal Scheduling Hierarchy

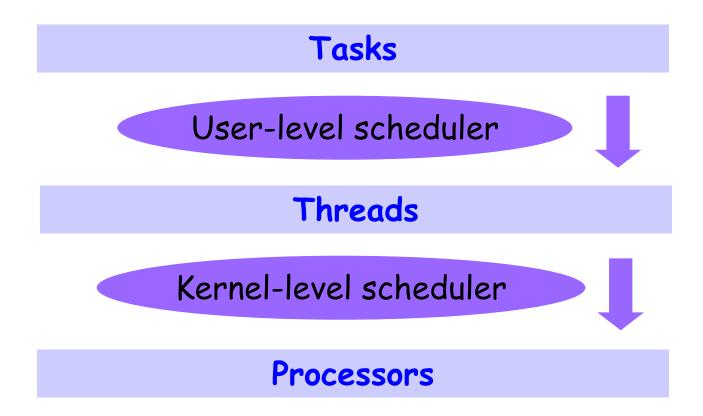
Tasks

User-level scheduler



Processors

Realistic Scheduling Hierarchy



For Example

- Initially,
 - All P processors available for application
- Serial computation
 - Takes over one processor
 - Leaving P-1 for us
 - Waits for I/O
 - We get that processor back

Speedup

- Map threads onto P processes
- Cannot get P-fold speedup
 - What if the kernel doesn't cooperate?
- · Can try for speedup proportional to
 - time-averaged number of processors the kernel gives us

Scheduling Hierarchy

- User-level scheduler
 - Tells kernel which threads are ready
- Kernel-level scheduler
 - Synchronous (for analysis, not correctness!)
 - Picks p_i threads to schedule at step i
 - Processor average over T steps is: $\mathbf{p}_{A} = \frac{1}{T} \sum_{i=1}^{T} \mathbf{p}_{i}$

Greed is Good

- · Greedy scheduler
 - Schedules as much as it can
 - At each time step
- Optimal schedule is greedy (why?)
- But not every greedy schedule is optimal

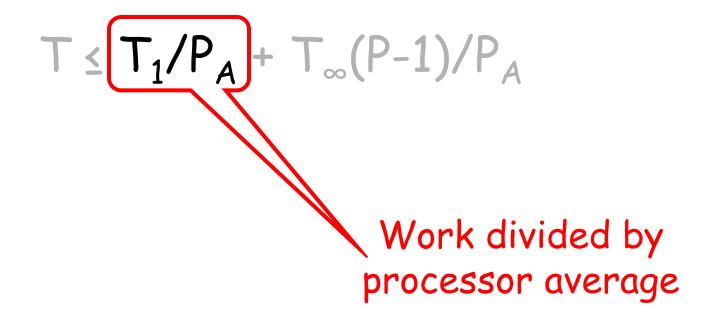
Theorem

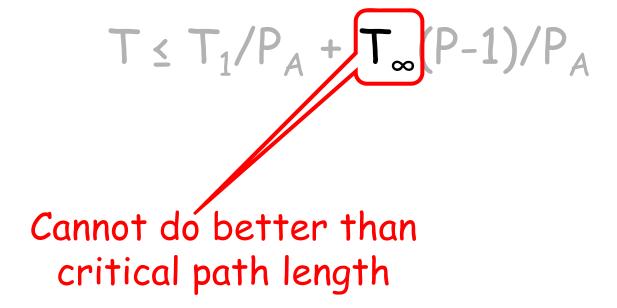
· Greedy scheduler ensures that

$$T \leq T_1/P_A + T_{\infty}(P-1)/P_A$$

$$T \leq T_1/P_A + T_\infty(P-1)/P_A$$

$$T \le T_1/P_A + T_\infty(P-1)/P_A$$
Actual time





$$T \le T_1/P_A + T_{\infty}(P-1)/P_A$$
The higher the average

the better it is ...

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Proof Strategy

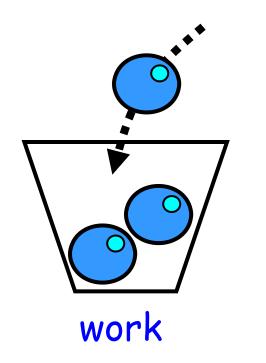
$$\mathbf{P}_{A} = \frac{1}{T} \sum_{i=1}^{T} \mathbf{p}_{i}$$

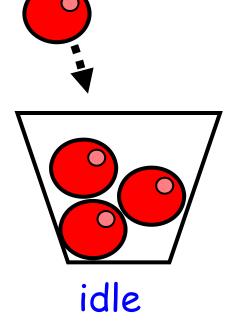
$$\mathbf{T} = \frac{1}{\mathbf{P}_{A}} \sum_{i=1}^{T} \mathbf{p}_{i}$$
Bound this

Put Tokens in Buckets

Processor found work

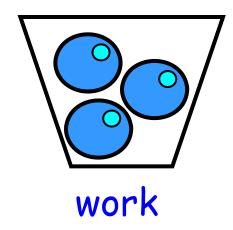
Processor available butcouldn't find work

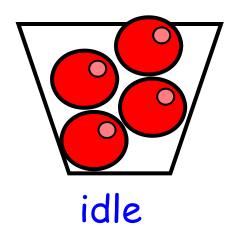




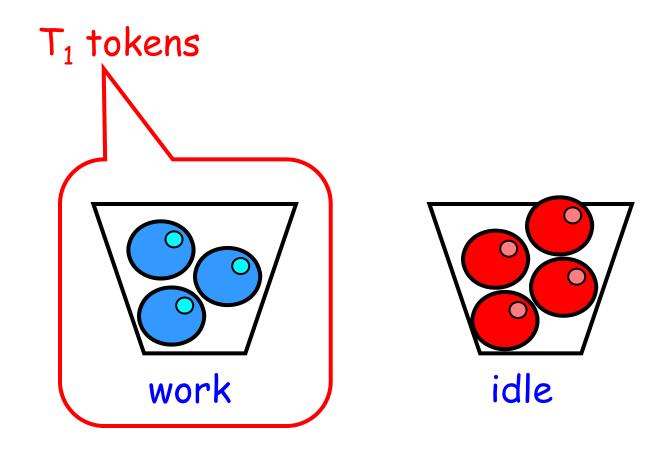
At the end

Total #tokens =
$$\sum_{i=1}^{T} \mathbf{p}_{i}$$

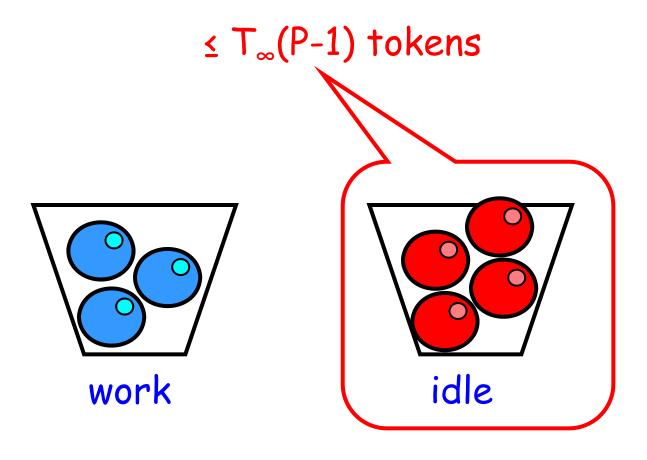




At the end



Must Show



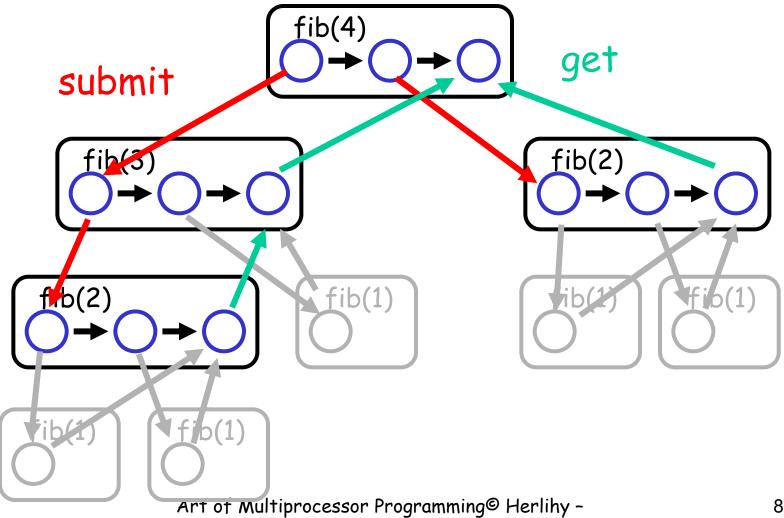
Idle Steps

- An idle step is one where there is at least one idle processor
- Only time idle tokens are generated
- Focus on idle steps

Every Move You Make ...

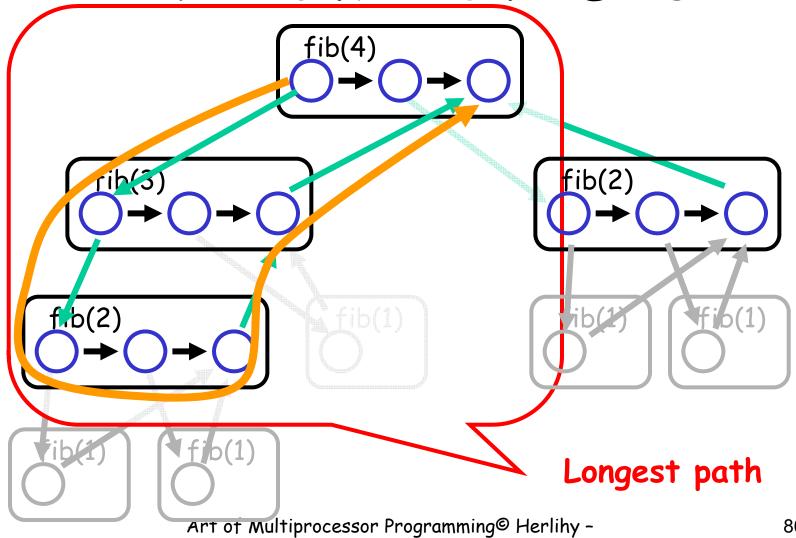
- Scheduler is greedy
- · At least one node ready
- Number of idle threads in one idle step
 - At most p_i -1 \leq P-1
- How many idle steps?

Unexecuted sub-DAG



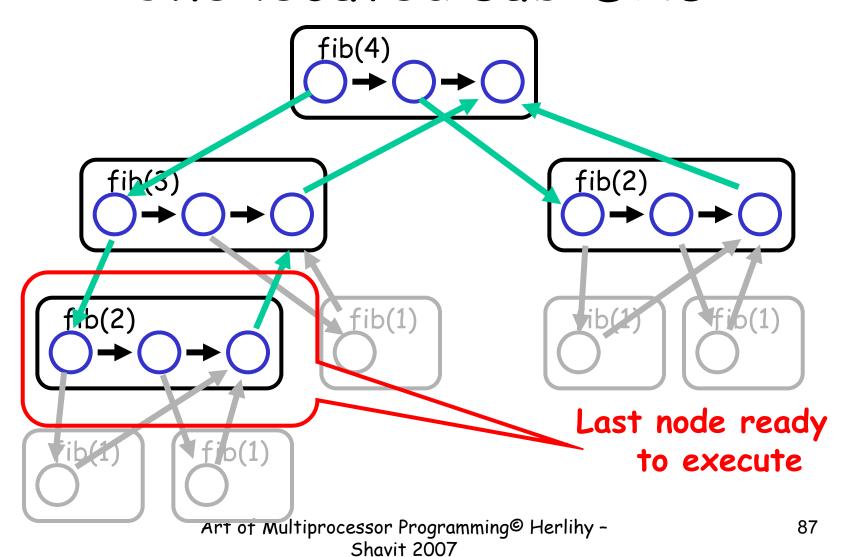
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Unexecuted sub-DAG



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Unexecuted sub-DAG



Every Step You Take ...

- Consider longest path in unexecuted sub-DAG at step i
- At least one node in path ready
- Length of path shrinks by at least one at each step
- Initially, path is T_∞
- So there are at most T_∞ idle steps

Counting Tokens

- At most P-1 idle threads per step
- At most T_∞ steps
- So idle bucket contains at most
 - $T_{\infty}(P-1)$ tokens
- Both buckets contain
 - $T_1 + T_{\infty}(P-1)$ tokens

Recapitulating

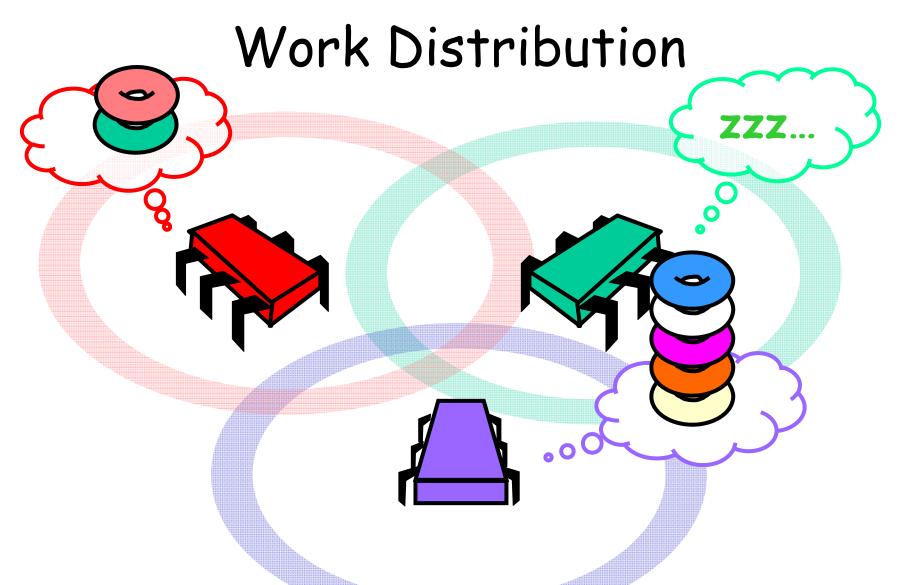
$$T = \frac{1}{P_A} \sum_{i=1}^{T} p_i$$

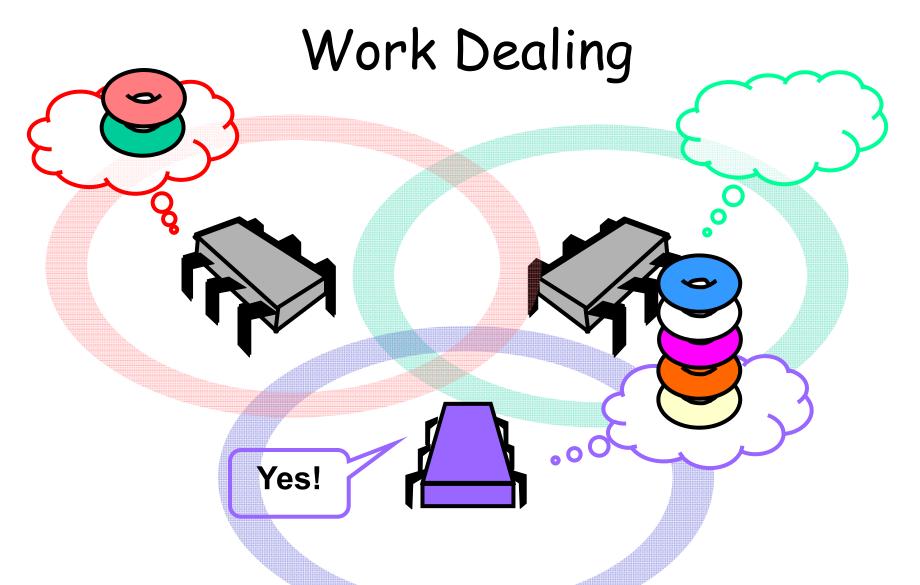
$$\sum_{i=1}^{T} \mathbf{p}_{i} \leq \mathbf{T}_{1} + \mathbf{T}_{\infty}(\mathbf{P} - 1)$$

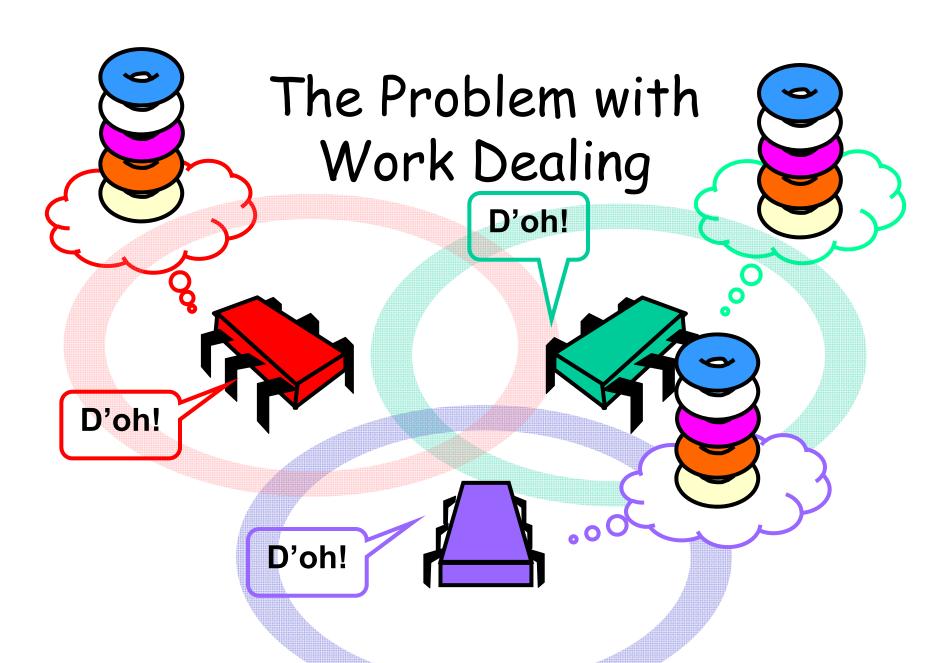
$$\mathsf{T} \leq \frac{1}{\mathsf{P}_{\!\scriptscriptstyle A}} \big(\mathsf{T}_{\!\scriptscriptstyle 1} \, + \, \mathsf{T}_{\!\scriptscriptstyle \infty} (\mathsf{P} \, - \, \mathsf{1}) \big)$$

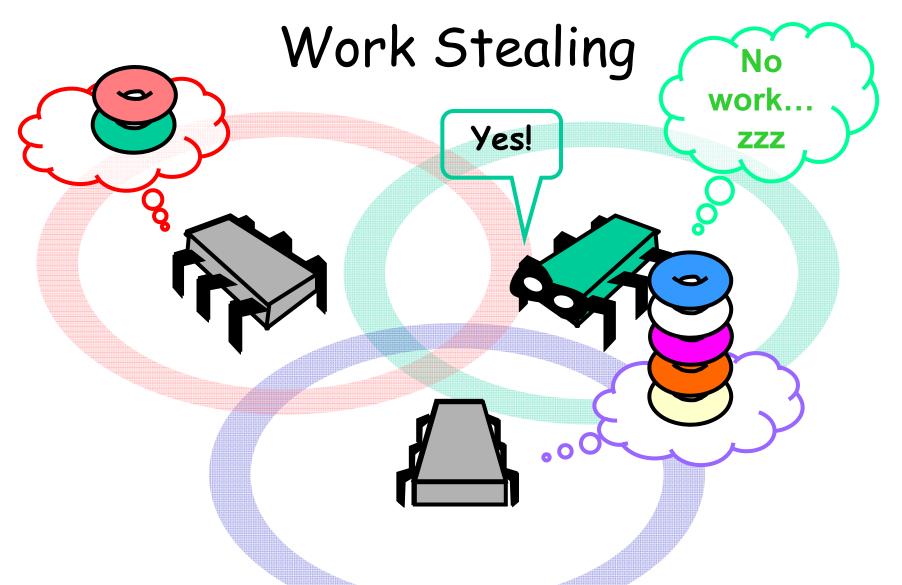
Turns Out

- This bound is within a factor of 2 of optimal
- · Actual optimal is NP-complete







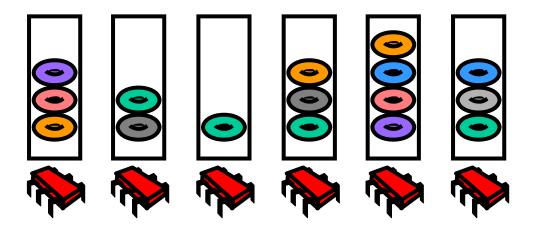


Lock-Free Work Stealing

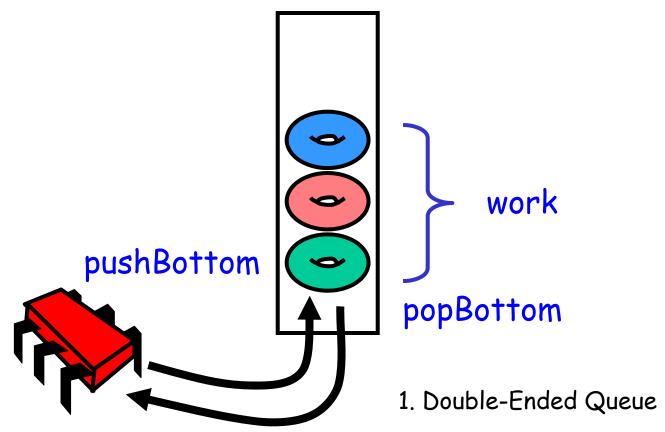
- Each thread has a pool of ready work
- Remove work without synchronizing
- If you run out of work, steal someone else's
- Choose victim at random

Local Work Pools

Each work pool is a Double-Ended Queue



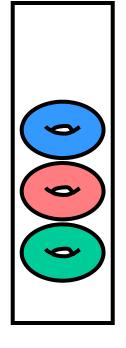
Work DEQueue¹



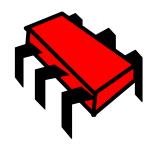
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Obtain Work

- ·Obtain work
- ·Run thread until
- ·Blocks or terminates

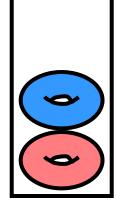


popBottom

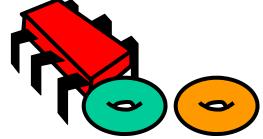


New Work

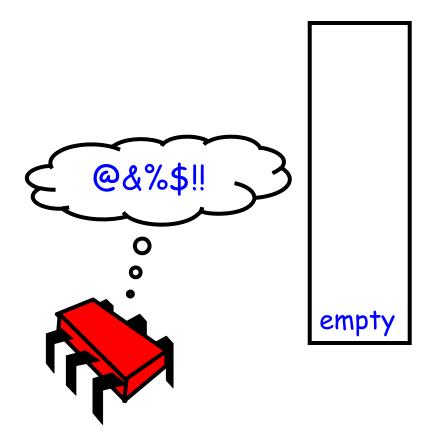
- ·Unblock node
- ·Spawn node



pushBottom

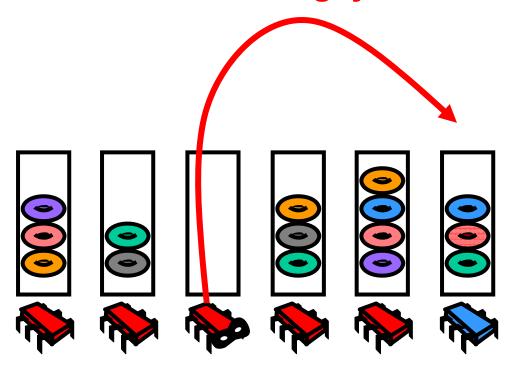


Whatcha Gonna do When the Well Runs Dry?



Steal Work from Others

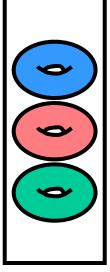
Pick random guy's DEQeueue



Steal this Thread!









Thread DEQueue

- Methods

 - popTop

pushBottompopBottomConcurrently

Thread DEQueue

- Methods
 - pushBottom
 - popBottom
 - popTop

These most common - make them fast (minimize use of CAS)

Ideal

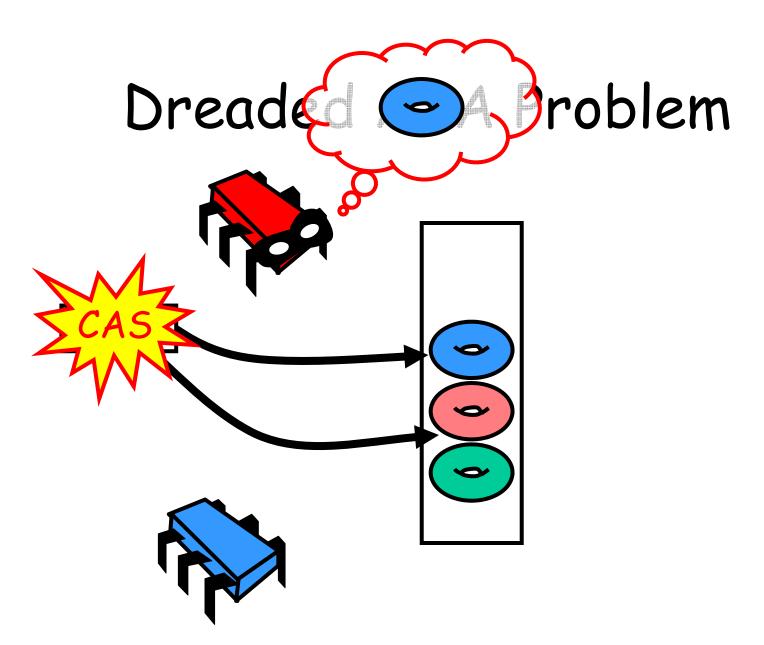
- · Wait-Free
- · Linearizable
- · Constant time

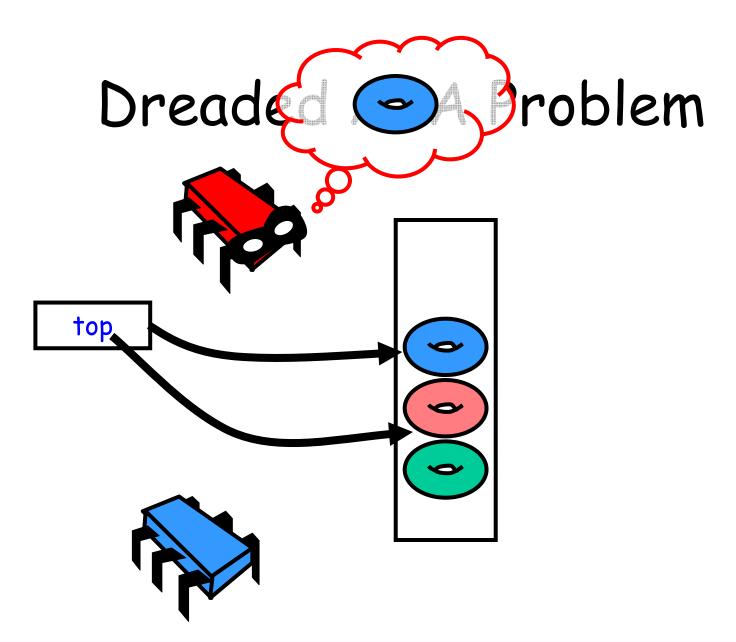
Fortune Cookie: "It is better to be young, rich and beautiful, than old, poor, and ugly"

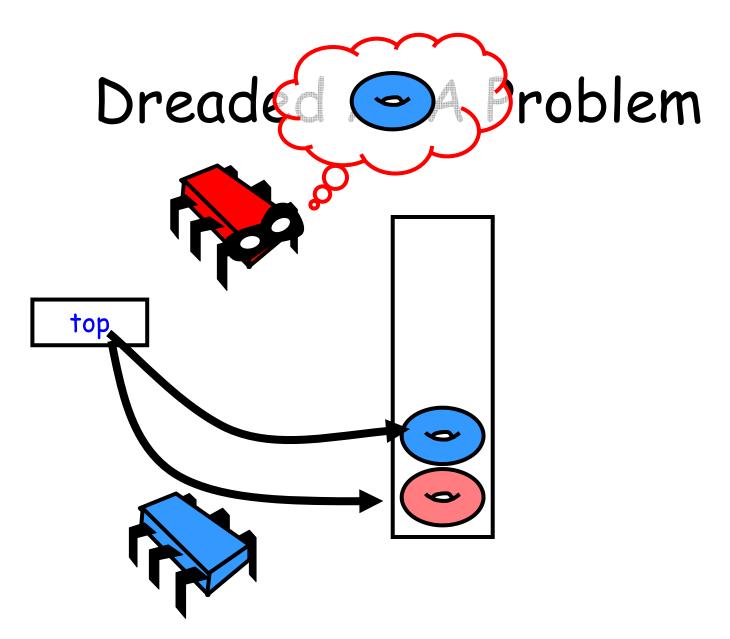
Compromise

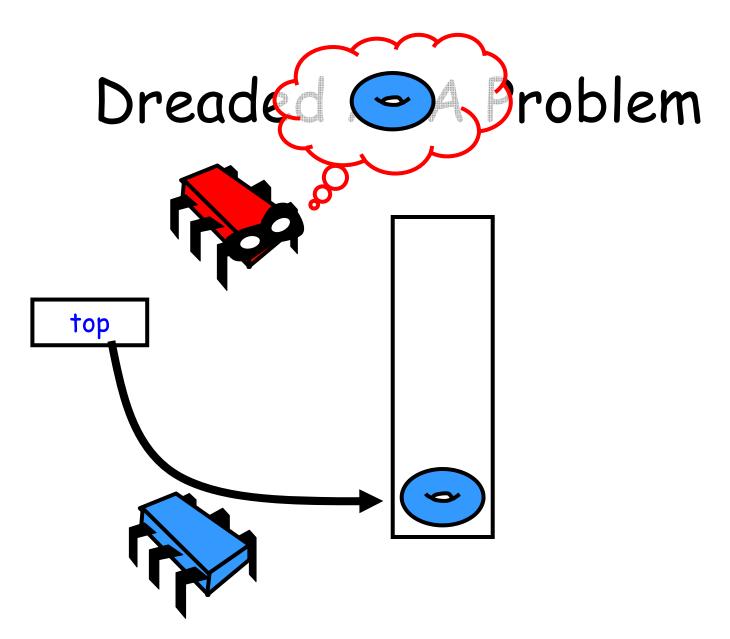
- Method popTop may fail if
 - Concurrent popTop succeeds, or a
 - Concurrent popBottom takes last work

Blame the victim!

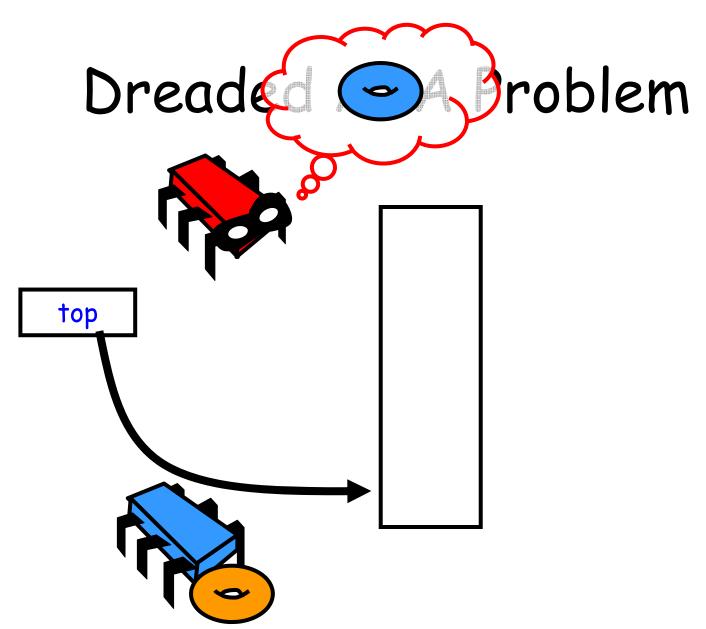




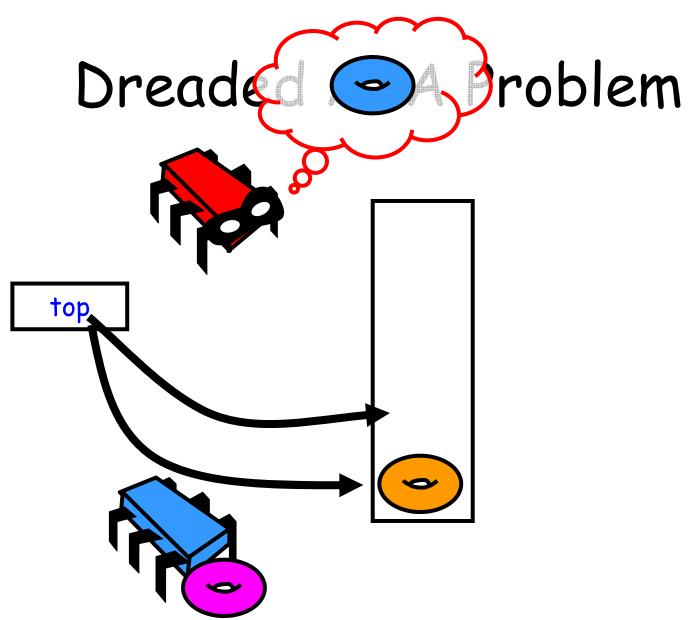




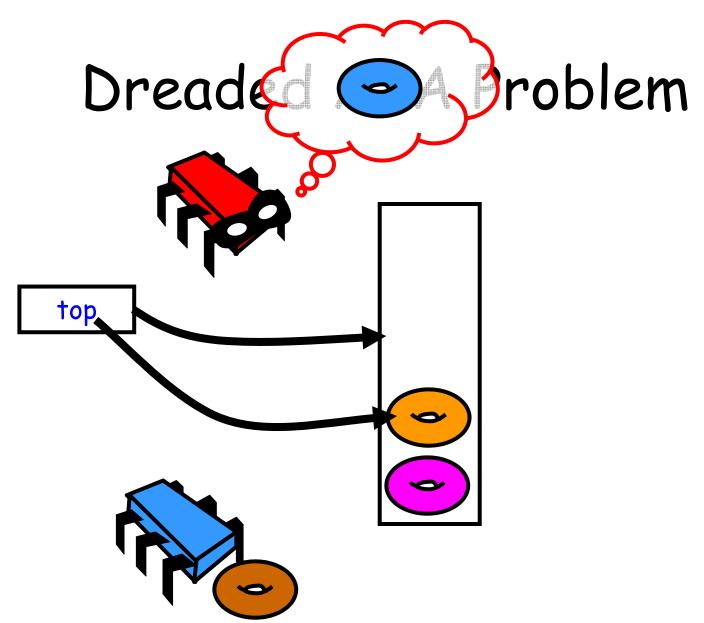
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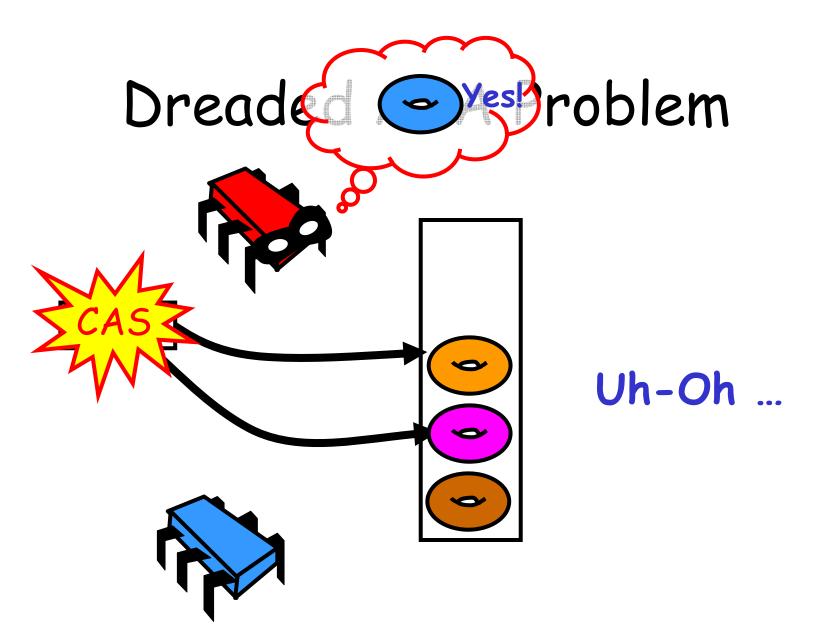
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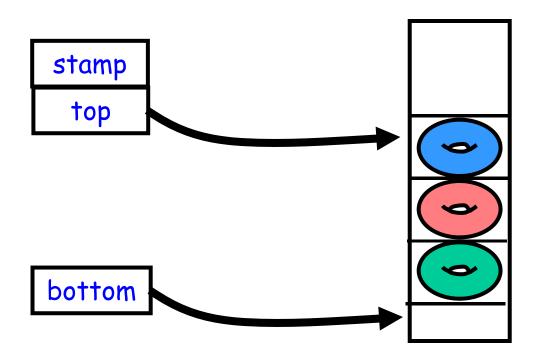
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Fix for Dreaded ABA



Bounded DEQueue

```
public class BDEQueue {
  AtomicStampedReference<Integer> top;
  volatile int bottom;
  Runnable[] tasks;
...
}
```

Bounded DQueue

```
public class BDEQueue {
   AtomicStampedReference<Integer> top;
   volatile int bottom;
   Runnable[] tasks;
...
}
```

Index & Stamp (synchronized)

Bounded DEQueue

```
public class BDEQueue {
  AtomicStampedReference<Integer> top;
  Volatile int bottom;
  Runnable[] deq;
...
}
```

Index of bottom thread (no need to synchronize The effect of a write must be seen - so we Art of Multiprocessor Programming Herlihy -Shavit 2007

Bounded DEQueue

```
public class BDEQueue {
  AtomicStampedReference<Integer> top;
  volatile int bottom;
  Runnable[] tasks;
}

Array holding tasks
```

pushBottom()

```
public class BDEQueue {
    ...
    void pushBottom(Runnable r) {
      tasks[bottom] = r;
      bottom++;
    }
    ...
}
```

pushBottom()

```
public class BDEQueue {
    ...
    void pushBottom(Runnable r) {
        tasks[bottom] = r;
        bottom++;
    }
    Bottom is the index to store
        the new task in the array
```

pushBottom()

```
public class BDEQueue {
...
void pushBottom(Runn top) {
   tasks[bottom] = r;
   bottom++;
}
```

```
public Runnable popTop() {
  int[] stamp = new int[1];
  int oldTop = top.get(stamp), newTop = oldTop + 1;
  int oldStamp = stamp[0], newStamp = oldStamp + 1;
  if (bottom <= oldTop)
    return null;
  Runnable r = tasks[oldTop];
  if (top.CAS(oldTop, newTop, oldStamp, newStamp))
    return r;
  return null;
}</pre>
```

```
public Runnable popTop() {
  int[] stamp = new int[1];
  int oldTop = top.get(stamp), newTop = oldTop + 1;
  int oldStamp = stamp[0], newStamp = oldStamp + 1;
  if (bottom <= oldTop)
    return null;
  Runnable r = tasks[oldTop];
  if (top.CAS(oldTop, newNop, oldStamp, newStamp))
    return r;
  return null;
  }
  Read top (value & stamp)</pre>
```

```
public Runnable popTop() {
  int[] stamp = new int[1];
  int oldTop = top.get(stamp),
  int oldStamp = stamp[0], newStamp = oldStamp + | | |
  if (bottom <= oldTop)
    return null;
  Runnable r = tasks[oldTop];
  if (top.CAS(oldTop newTop, oldStamp, newStamp))
    return r;
  return null;
  Quit if queue is empty
}</pre>
```

```
public Runnable popTop() {
int[] stamp = new int[1];
int oldTop = top.get(stamp), newTop
                               bottom.
int oldStamp = stamp[0], new
 if (bottom <= oldTop)</pre>
   return null:
Runnable r = tasks[oldTop];
 if (top. CAS(oldTop, newTop, oldStamp, newStamp))
  return r:
 return null;
                Try to steal the task
```

```
public Runnable popTop() {
  int[] stamp = new int[1];
  int oldTop = top.get(stamp), newTop = oldTop + 1;
  int oldStamp = stamp[0], newStamp = oldStamp + 1;
  if (bottom <= oldTop)
    return null;
  Runnable r = tasks[oldTop];
  if (top.CAS(oldTop, newTop, oldStamp, newStamp))
    return r;
  return null;
  }
    Give up if
    conflict occurs</pre>
```

```
Runnable popBottom() {
 if (bottom == 0) return null;
 bottom--:
 Runnable r = tasks[bottom];
 int[] stamp = new int[1];
 int oldTop = top.get(stamp), newTop = 0;
 int oldStamp = stamp[0], newStamp = oldStamp + 1;
 if (bottom > oldTop) return r;
 if (bottom == oldTop){
   bottom = 0:
   if (top. CAS(oldTop, newTop, oldStamp, newStamp))
     return r:
 top. set(newTop, newStamp); return null;
```

```
Punnahle nonRottom()
if (bottom == 0) return null;
bottom--:
Runnable r = tasks[bottom
int[] stamp = new int[1];
int oldTop = top.get(stamp), newTop = 0;
int oldStamp = stamp[0], newStamp = oldStamp + 1;
if (bottom > oldTop) return
if (bottom == oldTop){
  bottom = 0:
  if (top.CAS(oldTop, newTop, ol\Stamp, newStamp))
    return r
           Make sure queue is non-empty
top. set(newTop, newStamp); return null;
```

```
Runnable popBottom() {
if (bottom == 0) return null;
bottom--:
Runnable r = tasks[bottom];
int[] stamp = new int[1];
int oldTop = top.get(stamp), newTop = 0;
int oldStamp = stamp[0], newStamp = oldStamp + 1;
 if (bottom > oldTop) return r;
 if (bottom == oldTop)
  bottom = 0:
  if (top. CAS(oldTop, newTop, oldStamp, newStamp))
     return r
             Prepare to grab bottom task
top. set(newTop, newStamp); return null;
```

```
Runnable popBottom() {
if (bottom == 0) return null;
 bottom--:
Runnable r = tasks[bottom];
int[] stamp = new int[1];
int oldTop = top.get(stamp), newTop = 0;
int oldStamp = stamp[0], newStamp = oldStamp + 1;
if (bottom > oldTop) return
if (bottom == oldTop){
   bottom = 0;
   if (top. CAS(oldTop, newTop
                               oldStamp, newStamp))
    return [
            Read top, & prepare new values
top. set(newTop, newStamp); return null;
                     Shavit 2007
```

```
Runnable popBottom() {
if (bottom == 0) return null:
                             stamp
bottom--:
                             top
Runnable r = tasks[bottom];
int[] stamp = new int[1];
int oldTop = top.get(stamp) bottom
int oldStamp = stamp[0]. newStamp = oldStamp
if (bottom > oldTop) return r;
if (bottom == old op){
  bottom = 0;
  if (top.CAS(oldTop, newTop, oldStamp, newStamp))
    If top & bottom 1 or more
return null; apart, no conflict
```

```
Runnable popBottom() {
 if (bottom == 0) return null:
                               stamp
 bottom--:
                               top
 Runnable r = tasks[bottom];
 int[] stamp = new int[1];
 int oldTop = top.get(stamp) | bottom
 int oldStamp = stamp[0], newStamp = oldStamp
  f (bottom > oldTop) return r;
if (bottom == oldTop){
   pottom = 0:
   if (top. CAS(oldTop, newTop, oldStamp, newStamp))
     return
            At most one item left
 top. set(newTop, newStamp); return null;
                      Shavit 2007
```

```
Try to steal last item.
In any case reset Bottom
 because the DEQueue will be empty
even if unsucessful (why?) o;
int oldStamp = stamp[0], newStamp = oldStamp + 1;
if (bottom > oldTop) return r;
if (bottom == oldTop){
  bottom = 0;
  if (top. CAS(oldTop, newTop, oldStamp, newStamp))
    return r;
top. set(newTop, newStamp); return null;
                     Shavit 2007
```

```
Ruphable popBottom() {
    I win CAS) return null;
 bottom--;
 Runnable r = tasks[bottom];
 int[] stamp = new int[1];
 int oldTop = top.get(stamp), |
 int oldStamp = stamp[0], newStamp = oldStamp +
 if (bottom > oldTop) return r;
 if (bottom == oldTop) {
   bottom = 0;
   if (top. CAS(oldTop, newTop, oldStamp, newStamp))
     return r;
 top. set(newTop, newStamp); return null;
```

```
Ruphable popBottom() {

I OSE CAS return null;
 Thief must
 Runnable r = tasks[bottom];
have won new int[1];
 int oldTop = top.get(stamp), |
 int oldStamp = stamp[0], newStamp = oldStamp +
 if (bottom > oldTop) return r;
 if (bottom == oldTop){
   bottom = 0;
   if (top. CAS(oldTop, newTop, oldStamp, newStamp))
     return r;
 top. set(newTop, newStamp); return null;
```

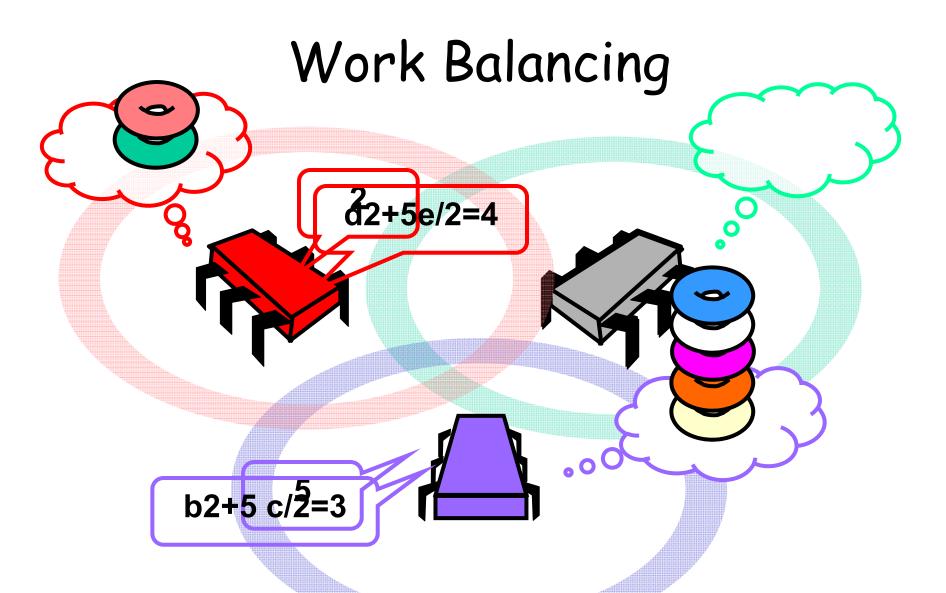
```
Runnable popBottom() {
 if (bottom == 0) return null;
 bottom--:
 Runnable r = tasks[bottom];
 int[] stamp = new int[1];
 int oldTop = tofailed to get last item
int oldStamp = stamp[0] polistamp = oldStamp + 1;
if (bottom > oldTop) Teturn reset top
 if (bottom == oldTop){
   bottom = 0:
   if (top. CAS(oldTop, newTop, oldStamp, newStamp))
     return r:
 top. set(newTop, newStamp); return null;
```

Old English Proverb

- "May as well be hanged for stealing a sheep as a goat"
- From which we conclude
 - Stealing was punished severely
 - Sheep were worth more than goats

Variations

- Stealing is expensive
 - Pay CAS
 - Only one thread taken
- What if
 - Randomly balance loads?



```
public void run() {
 int me = ThreadID.get();
 while (true) {
  Runnable task = queue[me].deq();
  if (task != null) task.run();
  int size = queue[me].size();
  if (random.nextInt(size+1) == size) {
   int victim = random.nextInt(queue.length);
   int min = ..., max = ...;
    synchroni zed (queue[mi n]) {
     synchroni zed (queue[max]) {
        bal ance(queue[mi n], queue[max]);
}}}}
```

```
public void run() {
 int me = ThreadID.get();
 while (true) {
 Runnable task = queue[me].deq();
  if (task != null) task.run();
 int size = queue[me] size()
  if (random.nextInt(size:1) == size) {
   int victim = random.nextInt(vueue.length);
   int min = ..., max = ...;
    synchroni zed (queue[mi n]) {
                                   Keep running tasks
     synchroni zed (queue[max]) {
        bal ance(queue[min], queue[max]);
}}}}
```

```
public void run() {
                                     With probability
 int me = ThreadID.get();
                                        1/|queue|
 while (true) {
  Runnable task = queue[me].de
  if (task != null) task. pun
  int size = queue[me].size();
  if (random.nextInt(size+1) == size) {
  int victim = random.nextInt(queue.length);
   int min = ..., max = ...;
    synchroni zed (queue[mi n]) {
     synchroni zed (queue[max]) {
        bal ance(queue[min], queue[max]);
}}}}
```

```
public void run() {
 int me = ThreadID.get();
                             Choose random victim
while (true) {
  Runnable task = queue[me].deq();
  if (task != null) task.run();
  int size = queue[me].size();
  if (random. nextInt(size+1) == size)
   int victim = random.nextInt(queue.length);
   int min = ..., max = ...;
    synchroni zed (queue[mi n]) {
     synchroni zed (queue[max]) {
        bal ance(queue[min], queue[max]);
}}}}
```

```
public void run() {
int me = ThreadID.get();
                       Lock queues in canonical order
while (true) {
 Runnable task = queue[me].deq()
 if (task != null) task.run()
 int size = queue[me].size
  if (random.nextInt(size+1) == size) {
   int victim = random.nextInt(queue.length);
  int min = ..., max = ...;
    synchroni zed (queue[mi n]) {
     synchroni zed (queue[max]) {
        bal ance(queue[min], queue[max]);
}}}}
```

```
public void run() {
 int me = ThreadID.get();
                              Rebalance queues
while (true) {
  Runnable task = queue[me].deq();
  if (task != null) task.run();
 int size = queue[me].size();
  if (random.nextInt(size+1) == size)
   int victim = random.nextInt(queue.length);
   int min = ..., max = ...;
    synchroni zed (queue[mi n]
     synchroni zed (queue[max]
        bal ance(queue[min], queue[max]);
}}}}
```

Work Stealing & Balancing

- Clean separation between app & scheduling layer
- Works well when number of processors fluctuates.
- Works on "black-box" operating systems

TOM MARVOLO RID DLE



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