

Modification Algorithms in the Theory of Orthogonal Polynomials

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Orthogonal Polynomials

$d\lambda$ (positive) measure on $[a, b]$, $-\infty \leq a < b \leq \infty$

$(\cdot, \cdot) = (\cdot, \cdot)_{d\lambda}$ inner product $(u, v)_{d\lambda} = \int_{\mathbb{R}} u(t)v(t)d\lambda(t)$

$\pi_k(\cdot) = \pi_k(\cdot; d\lambda)$ (monic) polynomial of degree k orthogonal relative to the measure $d\lambda$

$$(\pi_k, \pi_\ell)_{d\lambda} \begin{cases} = 0 & \text{if } k \neq \ell \\ > 0 & \text{if } k = \ell \end{cases}$$

$$\|\pi_k\|_{d\lambda} \text{ norm } \sqrt{(\pi_k, \pi_k)_{d\lambda}}$$

Three-Term Recurrence Relation

$$\pi_{k+1}(z) = (z - \alpha_k)\pi_k(z) - \beta_k\pi_{k-1}(z), \quad k = 0, 1, 2, \dots$$

$$\pi_{-1}(z) = 0, \quad \pi_0(z) = 1$$

where $\alpha_k = \alpha_k(d\lambda) \in \mathbb{R}$, $\beta_k = \beta_k(d\lambda) > 0$ (if $d\lambda$ is positive)

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Darboux formulae

$$\alpha_k = \frac{(t\pi_k, \pi_k)d\lambda}{(\pi_k, \pi_k)d\lambda}, \quad k = 0, 1, 2, \dots$$

$$\beta_k = \frac{(\pi_k, \pi_k)d\lambda}{(\pi_{k-1}, \pi_{k-1})d\lambda}, \quad k = 1, 2, \dots$$

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convention: $\beta_0 = \int_{\mathbb{R}} d\lambda(t)$

Jacobi matrix

of infinite order

$$\mathbf{J}_\infty = \mathbf{J}_\infty(d\lambda) := \begin{bmatrix} \alpha_0 & \sqrt{\beta_1} & & & & & & \mathbf{0} \\ \sqrt{\beta_1} & \alpha_1 & \sqrt{\beta_2} & & & & & \\ & \sqrt{\beta_2} & \alpha_2 & \sqrt{\beta_3} & & & & \\ & & \ddots & \ddots & \ddots & & & \\ & \mathbf{0} & & & & & & \end{bmatrix}$$

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$$\mathbf{J}_n = \mathbf{J}_n(d\lambda) := [\mathbf{J}_\infty(d\lambda)]_{[1:n,1:n]}$$

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The n -point **Gauss quadrature** formula for $\mathbf{d}\lambda$ is computable from the eigenvalues and first components of the corresponding normalized eigenvectors of \mathbf{J}_n (Golub and Welsch, 1969)

Cauchy integrals of orthogonal polynomials

$$\rho_n(z) = \rho_n(z; d\lambda) = \int_{\mathbb{R}} \frac{\pi_n(t; d\lambda)}{z - t} d\lambda(t), \quad n \geq 0, z \in \mathbb{C} \setminus [a, b]$$

Theorem If the moment problem for $d\lambda$ is **determined**, and $z \in \mathbb{C} \setminus [a, b]$, then the sequence $\rho_{-1}(z) = 1, \rho_0(z), \rho_1(z), \dots$ is a **minimal solution** of the basic three-term recurrence relation, i.e.,

$$\lim_{n \rightarrow \infty} \frac{\rho_n(z)}{y_n} = 0$$

for any solution $\{y_n\}$ linearly independent of $\{\rho_n\}$. Moreover,

$$\frac{\rho_n(z)}{\rho_{n-1}(z)} = \frac{\beta_n}{z - \alpha_n} - \frac{\beta_{n+1}}{z - \alpha_{n+1}} - \frac{\beta_{n+2}}{z - \alpha_{n+2}} - \dots, \quad n \geq 0$$

Continued Fraction Algorithm

Problem compute $\rho_n(z)$ for $z \in \mathbb{C} \setminus [a, b]$, $n = 0, 1, 2, \dots, N$

Solution define $r_n = \rho_{n+1}(z)/\rho_n(z)$ and let $\nu \geq N$

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in theory

$$r_{n-1} = \frac{\beta_n}{z - \alpha_n - r_n}, \quad n = \nu, \nu - 1, \dots, 0$$

$$\rho_{-1}(z) = 1, \quad \rho_n(z) = r_{n-1}\rho_{n-1}(z), \quad n = 0, 1, \dots, N$$

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in practice

$$r_\nu^{[\nu]} = 0, \quad r_{n-1}^{[\nu]} = \frac{\beta_n}{z - \alpha_n - r_n^{[\nu]}}, \quad n = \nu, \nu - 1, \dots, 0$$

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Fact under the assumptions of the Theorem,

$$\lim_{\nu \rightarrow \infty} \rho_n^{[\nu]} = \rho_n(z)$$

Modification algorithms

Problem: given the recurrence coefficients of $d\lambda$, generate those of

$$d\hat{\lambda}(t) = r(t)d\lambda(t), \quad r \geq 0 \text{ on } \text{supp}(d\lambda), \text{ rational}$$

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Example: Galant, 1971

$$r(t) = s(t - c), \quad c \in \mathbb{R} \setminus \text{supp}(d\lambda), \quad s = \pm 1$$

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$$r(t) = s(t - c), \quad c \in \mathbb{R} \setminus \text{supp}(d\lambda), \quad s = \pm 1$$

one step of (symmetric, shifted) LR algorithm:

$$s[\mathbf{J}_{n+1}(d\lambda) - c\mathbf{I}] = \mathbf{L}\mathbf{L}^T$$

$$\mathbf{J}_n(d\hat{\lambda}) = (\mathbf{L}^T\mathbf{L} + c\mathbf{I})_{[1:n,1:n]}$$

nonlinear recurrence algorithm

generalized Christoffel theorem (Uvarov, 1969)

$$d\hat{\lambda}(t) = \frac{u(t)}{v(t)}d\lambda(t), \quad u(t) = \pm \prod_{\lambda=1}^{\ell}(t - u_{\lambda}), \quad v(t) = \prod_{\mu=1}^m(t - v_{\mu})$$

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Let $m \leq n$. Then

$$u(t)\pi_n(t; d\hat{\lambda}) = \text{const} \times$$

$\pi_{n-m}(t)$	\cdots	$\pi_{n-1}(t)$	$\pi_n(t)$	\cdots	$\pi_{n+l}(t)$
$\pi_{n-m}(u_1)$	\cdots	$\pi_{n-1}(u_1)$	$\pi_n(u_1)$	\cdots	$\pi_{n+l}(u_1)$
\cdots	\cdots	\cdots	\cdots	\cdots	\cdots
$\pi_{n-m}(u_{\ell})$	\cdots	$\pi_{n-1}(u_{\ell})$	$\pi_n(u_{\ell})$	\cdots	$\pi_{n+l}(u_{\ell})$
$\rho_{n-m}(v_1)$	\cdots	$\rho_{n-1}(v_1)$	$\rho_n(v_1)$	\cdots	$\rho_{n+l}(v_1)$
\cdots	\cdots	\cdots	\cdots	\cdots	\cdots
$\rho_{n-m}(v_m)$	\cdots	$\rho_{n-1}(v_m)$	$\rho_n(v_m)$	\cdots	$\rho_{n+l}(v_m)$

where

$$\rho_k(z) = \int_{\mathbb{R}} \frac{\pi_k(t; d\lambda)}{z-t} d\lambda(t), \quad k = 0, 1, 2, \dots \quad \square$$

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Christoffel's theorem: $m = 0$

Theorem (Uvarov, 1969) Let $m > n$. Then

$$u(t)\pi_n(t; d\hat{\lambda}) = \text{const} \times$$

0	0	...	0	$\pi_0(t)$...	$\pi_{n+l}(t)$
0	0	...	0	$\pi_0(u_1)$...	$\pi_{n+l}(u_1)$
...
0	0	...	0	$\pi_0(u_\ell)$...	$\pi_{n+l}(u_\ell)$
1	v_1	...	v_1^{m-n-1}	$\rho_0(v_1)$...	$\rho_{n+l}(v_1)$
...
1	v_m	...	v_m^{m-n-1}	$\rho_0(v_m)$...	$\rho_{n+l}(v_m)$

where $\rho_k(z)$ is the Cauchy integral defined previously. \square

Theorem (Uvarov, 1969) Let $m > n$. Then

$$u(t)\pi_n(t; d\hat{\lambda}) = \text{const} \times \begin{vmatrix} 0 & 0 & \cdots & 0 & \pi_0(t) & \cdots & \pi_{n+l}(t) \\ 0 & 0 & \cdots & 0 & \pi_0(u_1) & \cdots & \pi_{n+l}(u_1) \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & \cdots & 0 & \pi_0(u_\ell) & \cdots & \pi_{n+l}(u_\ell) \\ 1 & v_1 & \cdots & v_1^{m-n-1} & \rho_0(v_1) & \cdots & \rho_{n+l}(v_1) \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ 1 & v_m & \cdots & v_m^{m-n-1} & \rho_0(v_m) & \cdots & \rho_{n+l}(v_m) \end{vmatrix}$$

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The generalized Christoffel theorems remain valid for complex u_λ, v_μ if orthogonality is understood in the sense of **formal orthogonality**.

linear factor $d\hat{\lambda}(t) = (t - z)d\lambda(t)$, $z \in \mathbb{C} \setminus [a, b]$

Christoffel:

$$(t - z)\hat{\pi}_n(t) = \frac{\begin{vmatrix} \pi_n(t) & \pi_{n+1}(t) \\ \pi_n(z) & \pi_{n+1}(z) \end{vmatrix}}{-\pi_n(z)} = \pi_{n+1}(t) - r_n \pi_n(t), \quad r_n = \frac{\pi_{n+1}(z)}{\pi_n(z)}$$

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write $(t - z)t\hat{\pi}_k(t)$ in two ways (Verlinden, 1999)

$$\begin{aligned} (t - z)t\hat{\pi}_k(t) &= t\pi_{k+1}(t) - r_k \cdot t\pi_k(t) \\ &= \pi_{k+2}(t) + (\alpha_{k+1} - r_k)\pi_{k+1}(t) + (\beta_{k+1} - r_k\alpha_k)\pi_k(t) - r_k\beta_k\pi_{k-1}(t) \end{aligned}$$

$$\begin{aligned} (t - z)t\hat{\pi}_k(t) &= (t - z)[\hat{\pi}_{k+1} + \hat{\alpha}_k\hat{\pi}_k(t) + \hat{\beta}_k\hat{\pi}_{k-1}(t)] \\ &= \pi_{k+2}(t) + (\hat{\alpha}_k - r_{k+1})\pi_{k+1}(t) + (\hat{\beta}_k - r_k\hat{\alpha}_k)\pi_k(t) - r_{k-1}\hat{\beta}_k\pi_{k-1}(t) \end{aligned}$$

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comparison:

$$\hat{\alpha}_k - r_{k+1} = \alpha_{k+1} - r_k, \quad r_{k-1}\hat{\beta}_k = r_k\beta_k$$

Algorithm modification by a linear factor $t - z$

initialization:

$$\begin{aligned} r_0 &= z - \alpha_0, & r_1 &= z - \alpha_1 - \beta_1/r_0, \\ \hat{\alpha}_0 &= \alpha_1 + r_1 - r_0, & \hat{\beta}_0 &= -r_0 \beta_0 \end{aligned}$$

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continuation (if $n > 1$): for $k = 1, 2, \dots, n - 1$ do

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Matlab

```
ab=chri1(N,ab0,z)
```

see:

<http://www.cs.purdue.edu/archives/2002/wxg/codes>

Algorithm quadratic factor $(t - x)^2 + y^2 = (t - z)(t - \bar{z})$

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Matlab `ab=chri2(N,ab0,x,y)`

special quadratic factor $d\hat{\lambda}(t) = (t - x)^2 d\lambda(t)$, $x \in \mathbb{R}$

warning: x is often inside the support of $d\lambda$

one step of the QR algorithm with shift x

$$\mathbf{J}_{n+2}(d\lambda) - x\mathbf{I} = QR$$

$$\mathbf{J}_n(d\lambda) = (RQ + x\mathbf{I})_{[1:n,1:n]}$$

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higher-order factors

$$d\hat{\lambda}(t) = (t - x)^{2m} d\lambda(t)$$

m applications of the shifted QR algorithm applied to

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$$d\hat{\lambda}(t) = (t - x)^{2m+1} d\lambda(t), \quad x \in \mathbb{R} \setminus [a, b]$$

m applications of the shifted QR algorithm applied to

$\mathbf{J}_{n+2m+1}(d\lambda)$ followed by one step of the symmetric, shifted LR algorithm

linear divisor $d\hat{\lambda}(t) = \frac{d\lambda(t)}{t-z}$, $z \in \mathbb{C} \setminus [a, b]$

generalized Christoffel:

$$\hat{\pi}_n(t) = \frac{\begin{vmatrix} \pi_{n-1}(t) & \pi_n(t) \\ \rho_{n-1}(z) & \rho_n(z) \end{vmatrix}}{-\rho_{n-1}(z)} = \pi_n(t) - r_{n-1}\pi_{n-1}(t), \quad r_n = \frac{\rho_{n+1}(z)}{\rho_n(z)}$$

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Algorithm modification by a linear divisor $t - z$

initialization:

$$\hat{\alpha}_0 = \alpha_0 + r_0, \quad \hat{\beta}_0 = -\rho_0(z)$$

continuation (if $n > 1$): for $k = 1, 2, \dots, n - 1$ do

$$\hat{\alpha}_k = \alpha_k + r_k - r_{k-1},$$

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computation of the r_k : **continued fraction algorithm**

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Matlab

```
[ab,nu]=chri4(N,ab0,z,eps0,nu0,numax,rho0,iopt)
```

quadratic divisor $d\hat{\lambda}(t) = \frac{d\lambda(t)}{(t-x)^2+y^2}$, $z = x + iy$

notations

$$r_n = \frac{\rho_{n+1}(z)}{\rho_n(z)} = r'_n + ir''_n$$

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$$\hat{\alpha}_0 = x + \rho'_0 y / \rho''_0, \quad \hat{\beta}_0 = -\rho''_0 / y,$$

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Matlab

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[ab,nu]=chri5(N,ab0,z,eps0,nu0,numax,rho0,iopt)
```


Applications

constrained least squares approximation

Problem given a function f on $[a, b]$ and a discrete (positive) N -point measure $d\lambda_N$ on $[a, b]$, find $p \in \mathbb{P}_n$, $n \ll N$, such that

$$\|f - p\|_{d\lambda_N}^2 = \min$$

subject to

$$p(s_j) = f_j, \quad j = 1, 2, \dots, m; \quad m \leq n,$$

where s_j are distinct points in $[a, b]$.

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simplifying assumption the s_j are different from the support points of $d\lambda_N$

Solution reduction to an **unconstrained** problem: write
 $p(t) = p_m(f; t) + \sigma_m(t)q(t)$, $q \in \mathbb{P}_{n-m}$, where
 $\sigma_m(t) = \prod_{j=1}^m (t - s_j)$ and $p_m(f; \cdot) \in \mathbb{P}_{m-1}$ is the polynomial
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\implies multiplication of $d\lambda_N$ by m quadratic factors $(t - s_j)^2$

Example Bessel function $f = J_0$ on $[0, j_{0,3}]$

$$s_1 = j_{0,1}, \quad s_2 = j_{0,2}, \quad s_3 = j_{0,3} \quad \implies \quad p_3(f; \cdot) \equiv 0$$

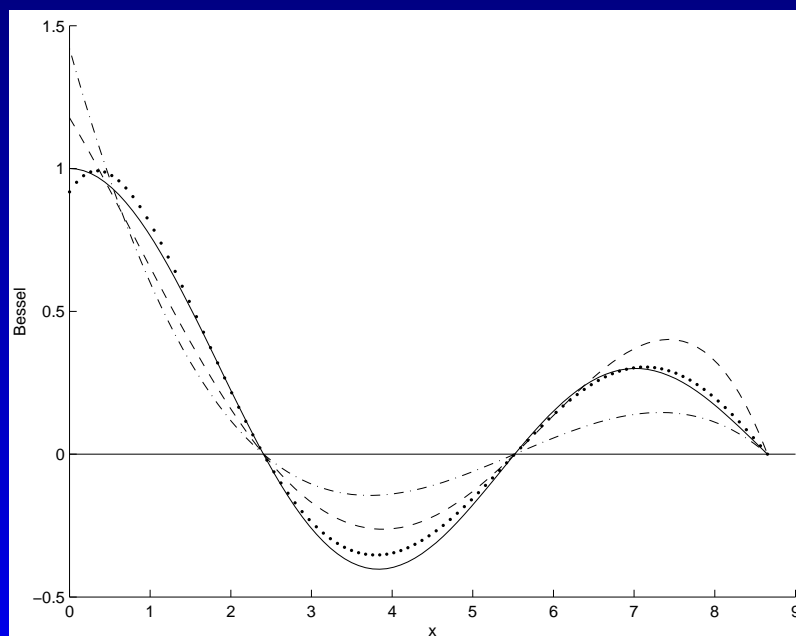
$$f^*(t) = \frac{J_0(t)}{\sigma_3(t)}, \quad \sigma_3(t) = (t - j_{0,1})(t - j_{0,2})(t - j_{0,3})$$

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results for $n - m = 0, 1, 2$



Example (continued)

derivative constraints

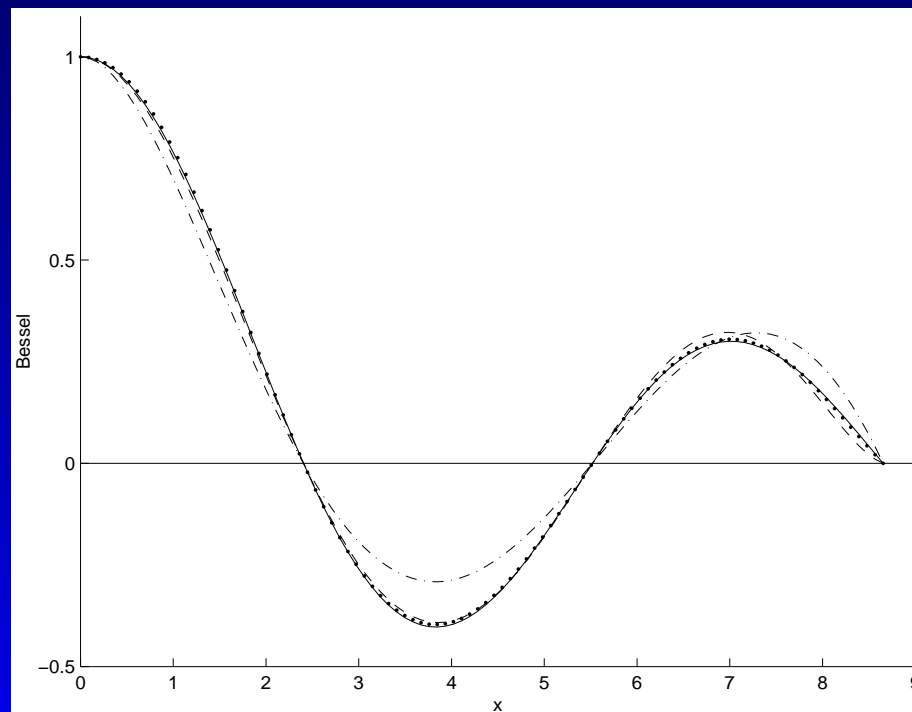
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Example (continued)

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$$G(x, y; a) = \int_{-\infty}^{\infty} J_0(at) \frac{e^{-t^2}}{(t-x)^2 + y^2} dt$$

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modification of the **Hermite weight** by a quadratic divisor followed by the **Golub/Welsch** algorithm to generate Gaussian quadrature formulae for

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Example $x = 0, y = 0.1, a = 7.5$

n	Modified Hermite	Hermite
5	22.7...	94.7...
10	19.7...	-0.6...
15	19.966...	55.4...
20	19.96350...	4.1...
25	19.96352269...	42.8...
30	19.96352266624...	7.3...
35	19.963522666263	36.5...
40	19.963522666263	9.6...