

Topological space(quotient space)

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Def. (quotient space): ' \sim ' an equivalence relation on Π .
 $x \in \Pi$, $[x]$ equivalence class.

- $\mathcal{S} = \Pi / \sim$ quotient set
- $(\mathcal{S}, \mathcal{S})$ quotient space where

$$\mathcal{S} = \left\{ U \subseteq \mathcal{S} \mid \{x : [x] \in U\} \in \mathcal{T} \right\}$$

Example:

$\Pi = \{u, v, (u, v)\}$
 $\mathcal{T} = \left\{ \{u\}, \{v\}, \{(u, v)\}, \{u, (u, v)\}, \{v, (u, v)\}, \{u, v, (u, v)\} \right\}$
 \sim : $u \sim v, (u, v) = (u, u)$
 $\mathcal{S} = \{[u], ([u], [u])\}$ $\mathcal{S} = \left\{ [u], \{([u], [u])\}, \{([u], ([u], [u]))\} \right\}$

Def. (Metric) : (\mathbb{T}, d) , $d: \mathbb{T} \times \mathbb{T} \rightarrow \mathbb{R}$

(identity) • $d(p, q) = 0 \iff p = q \quad \forall p, q \in \mathbb{T}$

(Symmetry) • $d(p, q) = d(q, p) \quad \forall p, q \in \mathbb{T}$

(Triangular inequality) • $d(p, q) \leq d(p, r) + d(r, q) \quad \forall p, q, r \in \mathbb{T}$

• Given the three axioms, $d(x, y) \geq 0 \quad \forall x, y \in \mathbb{T}$. (prove)

• Examples: in \mathbb{R}^2 : $d_2(x, y) = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2}$

$$d_1(x, y) = |x_1 - y_1| + |x_2 - y_2|$$

$$d_\infty(x, y) = \max\{|x_1 - y_1|, |x_2 - y_2|\}$$

$$d_\infty(f, g) = \max_x \{|f(x) - g(x)|\}$$

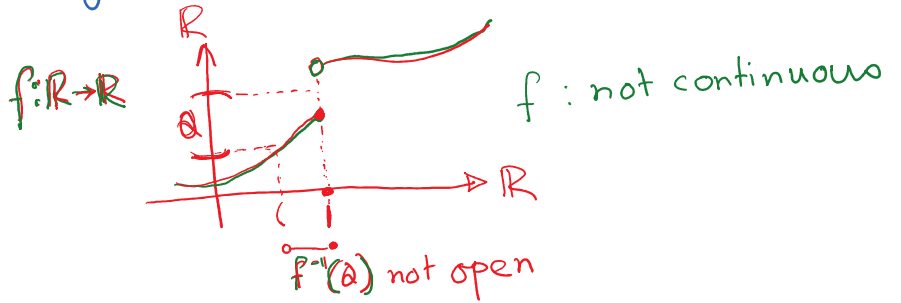
Def. (Metric space): (M, d) - the open sets are metric balls
 $B_o(c, r) = \{p \in M \mid d(p, c) < r\}$ for $r > 0$.

Examples: Euclidean space \mathbb{R}^k

$B_o^d = \{x \in \mathbb{R}^d \mid \|x\|_2 < 1\}$ d-ball (open)
 $S^d = \{x \in \mathbb{R}^d \mid \|x\|_2 = 1\}$ d-sphere
 $B^d = \{x \in \mathbb{R}^d \mid \|x\|_2 \leq 1\}$ d-ball (closed)
 $H^d = \{x \in \mathbb{R}^d \mid \|x\|_2 < 1, x_d \geq 0\}$ Half d-bdl
 (P, d) : discrete points P with interpoint distances

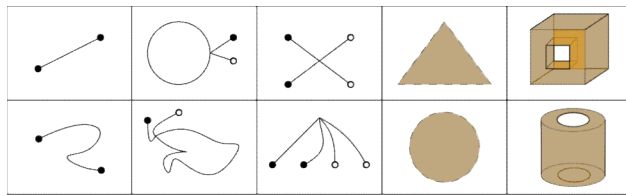
- discrete topology.
- what are metric balls?

Def (Continuous): $f: \mathbb{T} \rightarrow \mathbb{U}$ is continuous if for every open $Q \subseteq \mathbb{U}$, $f^{-1}(Q)$ is open.



Def (homeomorphism): $h: \mathbb{T} \rightarrow \mathbb{U}$ is a homeomorphism if

- h is bijective, continuous
- h^{-1} is continuous

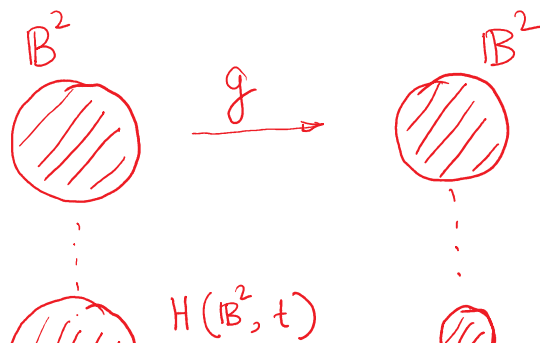


\mathbb{T} & \mathbb{U} are homeomorphic if \exists a homeomorphism $h: \mathbb{T} \rightarrow \mathbb{U}$

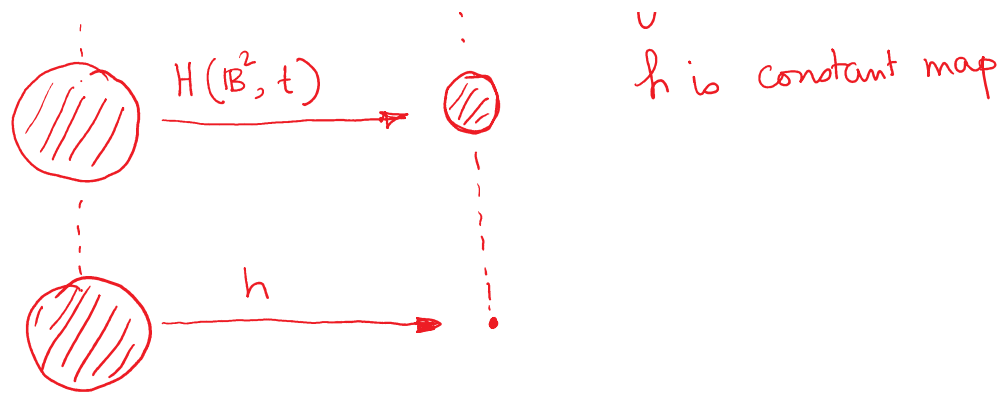
- If \mathbb{T} & \mathbb{U} are compact metric spaces, then it is sufficient that h is continuous because h^{-1} in that case is necessarily continuous.

Def (homotopy): $g: \mathbb{X} \rightarrow \mathbb{U}$, $h: \mathbb{X} \rightarrow \mathbb{U}$ are homotopic if \exists continuous $H: \mathbb{X} \times [0, 1] \rightarrow \mathbb{U}$ called homotopy s.t.

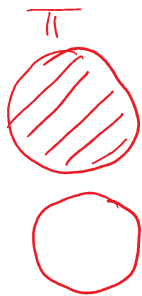
- $H(\mathbb{X}, 0) = g$, $H(\mathbb{X}, 1) = h$



g is identity map
 h is constant map



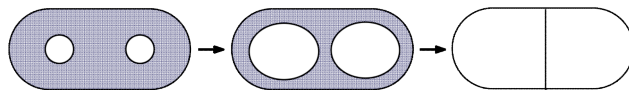
Def (homotopy equivalent): U & Π are homotopy equivalent if $\exists g: \Pi \rightarrow U$, $h: U \rightarrow \Pi$ s.t. $h \circ g$ is identity $\Pi \rightarrow \Pi$, and $g \circ h$ is identity $U \rightarrow U$.



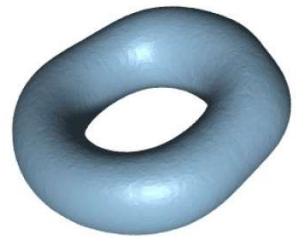
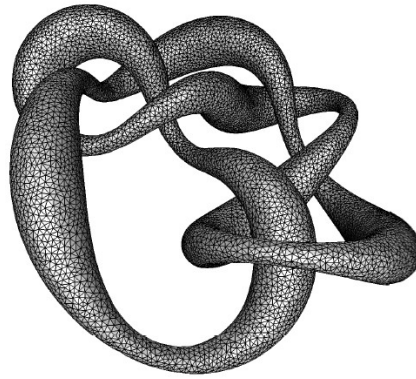
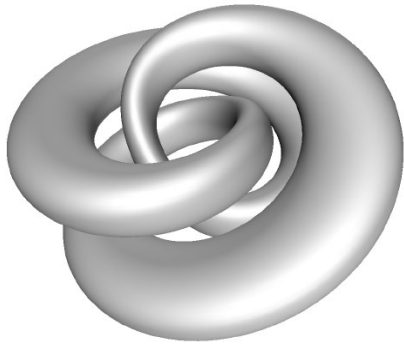
- U homotopy equivalent
- not homotopy equivalent

Def (Deformation retract): $U \subseteq \Pi$ is a deformation retract of Π if \exists homotopy $H: \Pi \times [0, 1] \rightarrow U$ with

- $H(\Pi, 0) = \text{identity on } \Pi$
- $H(\Pi, 1) = \text{retract } r: \Pi \rightarrow U, r(x) = x \text{ if } x \in U$
- $H(\Pi, t)(x) = x \text{ if } x \in U$.

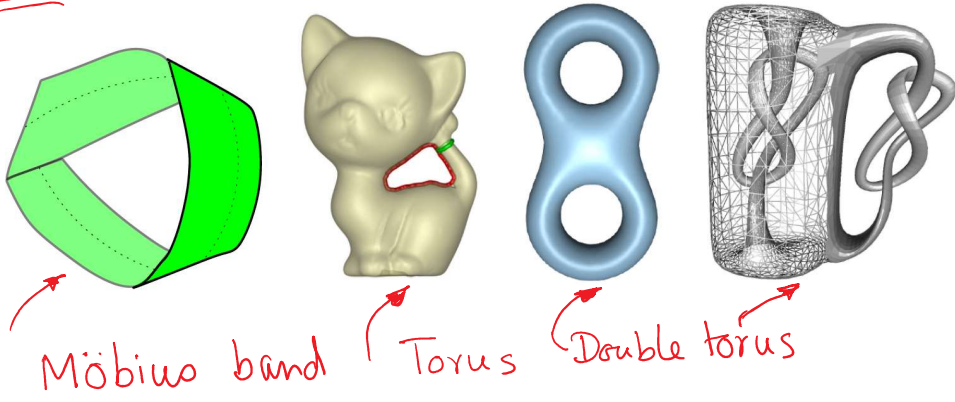


- if U is a deformation retract of Π , then Π & U are homotopy equivalent.

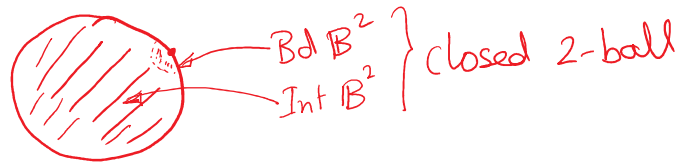


- Homeomorphic spaces, but their embeddings are different.
(All are torus)

Def. (Manifold): M is a manifold if every $x \in M$ has a neighborhood homeomorphic to B_0^m or H^m .
 m is the dimension of M called m -manifold. ↑ open ball ↑ Half ball



Def (Interior, boundary): points in M with neighborhood of open balls constitute $\text{Int } M$. $\text{Bd } M = M \setminus \text{Int } M$.
 $\text{Bd } M$ consists of points with neighborhood of H^m .



Orientability: One can "orient" the manifold to define two "distinct" sides.

Möbius band is non-orientable.

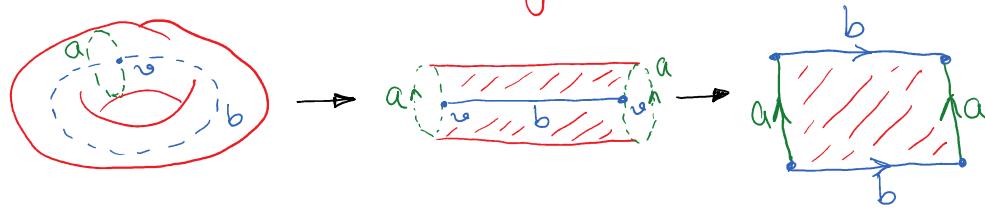
- All Compact 2-manifolds without boundary in \mathbb{R}^3 are orientable.
- Compact 2-manifolds without boundary that are non-orientable embed in \mathbb{R}^4 .



Klein bottle (non-orientable 2-manifold)

Def (Genus): All 2-manifolds are also called surfaces.

- Every 2-manifold can be cut open into a disc.
- Min # loops a surface need to be cut to make it a disc equals twice its genus.



- Every genus g surface (orientable without boundary) can be represented with a rectangle of sides $2g$, called its polygonal schema.

- Every surface (orientable, without boundary) is a genus g -surface. For $g=0$, it is sphere, otherwise g -tori.



3-tori