CS 565

Programming Languages (graduate) Spring 2025

Week I4
Separation Logic

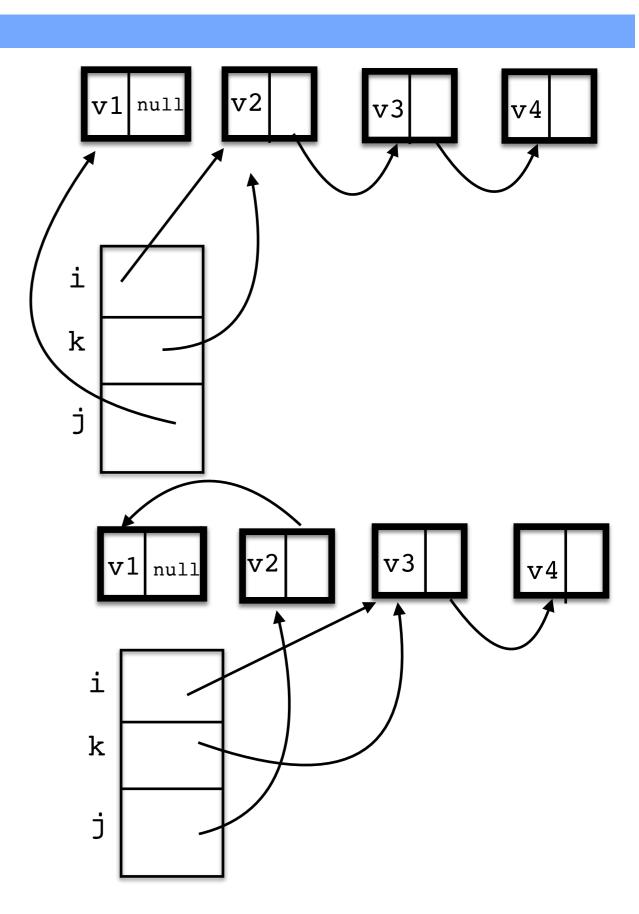
Readings

- Software Foundations, Vol. 6
- Separation Logic, O'Hearn CACM, 2/19
- Local Reasoning about Programs that Alter Data Structures, O'Hearn, Reynolds, Yang, CSL, 10/01
- Separation Logic: A Logic for Shared Mutable Data Structures, LICS, 2002

Motivation

- Hoare Logic is defined in terms of assertions on states:
 - states are maps from variables to their values
 - most programming languages also support the notion of a heap:
 - variables map to addresses
 - the contents at a given address can be shared and aliased
 - Embedding notions of sharing and mutation into the logic is problematic
- Separation Logic enables local reasoning about memory
 - It is a substructural logic that controls how memory (heaps) are constructed and used
 - In classical logical systems (e.g., Hoare logic) can:
 - add (weaken) or contract (duplicate) assumptions. Here, think of assumptions as claims we can make about resources (aka states or memory)
 - Substructural logics restrict how assumptions can be introduced:
 - can't invent extra memory to satisfy predicates
 - can't duplicate memory

```
j := null;
while i <> null do {
  k = *(i + 1);
  *(i + 1) = j;
  j = i;
  i = k;
i
k
  nil
```



```
j := nil;
while i <> nil do {
    k = *(i + 1);
    *(i + 1) = j;
    j = i;
    i = k;
}
```

Invariants:

- i and j are pointers into a list structure
- the reversal of the original list can be obtained by concatenating the reversal of the list reachable from i to the list reachable from j

The correctness of the invariant crucially relies on the assumption that there is no aliasing among list elements:

- augment invariant to assert that only nil is reachable from i and j
- What about other structures that may point into this list?

The Heap

- A heap is a partial function that maps addresses to values
 - assume addresses and values are both ints
 - thus, addresses are also values
- Two new instructions:
 - x := [e] // load the contents of the address referenced by e into x
 - [eI] := e2 // store the value of e2 into the address referenced by eI

Semantics:

- a state consists of a heap h and local memory γ

$$\frac{\gamma \vdash \mathbf{e} \Downarrow addr \quad \gamma' = \gamma[\mathbf{x} \mapsto h(addr)]}{\langle h, \gamma \rangle \vdash \mathbf{x} := [\mathbf{e}] \Rightarrow \langle h, \gamma' \rangle}$$

$$\frac{\gamma \vdash \mathtt{e1} \Downarrow addr \quad \gamma \vdash e2 \Downarrow v \quad h' = h[addr \mapsto v]}{\langle h, \gamma \rangle \vdash [\mathtt{e1}] := \mathtt{e2} \Rightarrow \langle h', \gamma \rangle}$$

Axiomatic Rules

Load

$$\{e_1 \mapsto n\}$$
 $x := [e_1]$ $\{x = n\}$

Store

$$\{\mathsf{True}\} \quad [\mathsf{e_1}] := \mathsf{v} \quad \{\mathsf{e_1} \mapsto v\}$$

Consider the following rule:

$$\{ x \mapsto z \land y \mapsto w \land z \mapsto 3 \} z := 4 \{ [[x]] \mapsto 4 \land [[y]] \neq [z]] \}$$

Is this a reasonable assertion?

In general, the validity of a triple must take aliasing properties into account, either in the precondition (establish that w <> z) or in the post-condition (establish that [[y]] maybe 3 or 4)

Separation Logic

Rather than trying to explicitly reason about heap structure and aliasing within Hoare Logic, introduce new logical operators to reason about how heaps (aka resources) are used

- emp: empty heap
- $x \mapsto v$: heap has a cell at x with value v
- P * Q: separating conjunction (disjoint parts of the heap)
- P *Q: separating implication (hypothetical heap extension)

Assertions now describe heap and variable conditions

- Conjunction (*), implication (-*)
- Emp and points-to relation

Example:

$$h \models P * Q$$

means: the heap can be divided into disjoint parts, one which satisfies $P(h \models P)$ and the other which satisfies $Q(h \models Q)$

More Formally...

$$h \models P * Q$$

means

$$\exists h_1, h_2.h_1 \oplus h_2 = h \land h_1 \models P \land h_2 \models Q$$

where

$$h_1 \oplus h_2$$

means the union of the resources "owned" by h_I and the resources owned by h_2

$$h_1 \oplus h_2 = h_2 \oplus h_1$$

$$h_1 \oplus (h_2 \oplus h_3) = (h_1 \oplus h_2) \oplus h_1$$

It is expected that heaps be disjoint (resources owned by one are not also owned by the other)

Memory

- The heap consists of a collection of memory cells, each indexed by an address
- Each memory cell provides a resource
- The assertion:

$$\{ x \mapsto 2 * y \mapsto 3 \}$$

means:

the heap can be split into two disjoint regions, one that satisfies the assertion that the memory cell with address x contains 2 and the other that satisfies the assertion that the memory cell with address y contains 3

In other words, x and y are not aliases for the same cell

So, the following proof rule is sound:

$$\{x \mapsto v_1 * y \mapsto v_2\}[x] := v_3\{x \mapsto v_3 * y \mapsto v_2\}$$

Frame Rule

Note that in the rule:

$$\{\mathbf{x} \mapsto v_1 * \mathbf{y} \mapsto v_2\}[\mathbf{x}] := \mathbf{v}_3\{\mathbf{x} \mapsto v_3 * \mathbf{y} \mapsto v_2\}$$

the assertion on y is unused and provides no meaningful information relevant to the proof

$$\frac{\{\psi\} \quad \mathsf{c} \quad \{\phi\}}{\{\psi * \mathsf{F}\} \quad \mathsf{c} \quad \{\phi * \mathsf{F}\}}$$

Importantly, the following is not valid:

$$\frac{\{\psi\} \quad \mathsf{c} \quad \{\phi\}}{\{\psi \land \mathsf{F}\} \quad \mathsf{c} \quad \{\phi \land \mathsf{F}\}}$$

Frame Rule

The following is a valid inference:

$$\frac{\{\mathtt{x}\mapsto\mathtt{w}\}\quad [\mathtt{w}]:=4\quad \{[\mathtt{x}]\mapsto 4\}}{\{\mathtt{x}\mapsto\mathtt{w}\ast\mathtt{y}\mapsto\mathtt{z}\ast\mathtt{w}\mapsto 3\land [\mathtt{z}]=v\}\quad [\mathtt{w}]:=4\quad \{\mathtt{x}\mapsto\mathtt{w}\ast\mathtt{y}\mapsto\mathtt{z}\ast\mathtt{w}\mapsto 4\land [\mathtt{z}]=v\}}$$

While the following is not, because z and w may denote the same address:

$$\frac{\{\mathtt{x}\mapsto\mathtt{w}\}\quad [\mathtt{w}]:=4\quad \{[\mathtt{x}]\mapsto 4\}}{\{\mathtt{x}\mapsto\mathtt{w}\land\mathtt{y}\mapsto\mathtt{z}\land\mathtt{w}\mapsto 3\land [\mathtt{z}]=v\}\quad [\mathtt{w}]:=4\quad \{\mathtt{x}\mapsto\mathtt{w}\land\mathtt{y}\mapsto\mathtt{z}\land\mathtt{w}\mapsto 4\land [\mathtt{z}]=v\}}$$

Points-to

What does $x \mapsto v$ mean?

$$(h, \gamma) \models x \mapsto v \equiv h(x) = v \land dom(h) = \{x\}$$

That is, the assertion holds in a singleton heap that only contains the resource at location \mathbf{x}

$$\{emp\} x = new(3) \{x \mapsto 3\}$$

 $\{x \mapsto v\} \text{ free } x \text{ } \{emp\}$

Magic Wand (Separating Implication)

$$P - Q$$

reads:

Extending a heap h with another (disjoint) heap that satisfies P, results in a new heap that satisfies Q

$$\frac{\langle h, \gamma \rangle \models P * (P - ^*Q)}{\langle h, \gamma \rangle \models Q}$$

Magic Wand Example

$$x \mapsto 1 \vdash y \mapsto 2 \quad -* \quad (x \mapsto 1 * y \mapsto 2)$$

Starting from a heap that stores 1 at address x, if we add another heap that stores 2 at address y, then we can conclude that the combined heap maps x to 1 and y to 2

$$lseg(x,y) \vdash lseg(y,z)$$
 -* $lseg(x,z)$

lseg(a,b) represents a list indexed at a upto but not including b

The formula states:

- Assuming a list whose root is at address x that does not include the node indexed at y
- If there is another (disjoint) list indexed at y that does not include the node indexed at z
- The heap containing both list segments contains a list segment from x to z (exclusive)

Concept Check

Which assertions are valid?

```
P => P * P
P * Q => P
x → 3 => x → 3 * x → 3
x → 3 => x → 3 * y → 42
x → 3 => 0 ≤ [x]
(x → - ) * (x → - )
(P → - ) * (Q → - ) => P ≠ Q
(P → 3) * (Q → 3) => P ≠ Q
```

Summary

Separation Logic is useful to verify properties of programs that make use of references (i.e., memory addresses). It can help identify errors involving:

- using memory before allocation or using it after freeing
- inadvertent use of aliased memory
- freeing memory that is not allocated
- allocation without freeing

Generalizes to any system that manipulates resources

- networks
- concurrency
- distributed programming

The frame rule enables compositional (local) reasoning

to verify a property involving the heap, we can safely ignore all parts of the heap unrelated to the parts reachable from the command being analyzed

A program that swaps the value of two memory cells

Precondition:

$$(x \mapsto v_1 * y \mapsto v_2)$$

Postcondition:

$$(x \mapsto v_2 * y \mapsto v_1)$$

```
(x \mapsto v_1 * y \mapsto v_2)
     t := [x] // local assignment, t = v_1
(x \mapsto v_1 * y \mapsto v_2)
     b := [y] // local assignment, b = v_2
(x \mapsto v_1 * y \mapsto v_2)
     [x] := b // store
(x \mapsto v_2 * y \mapsto v_2)
     [y] := t // store
(x \mapsto v_2 * y \mapsto v_1)
```

```
x := malloc();
[x] := 42
```

Precondition:

Postcondition:

$$\{ x \mapsto 42 \}$$

Proof rule for malloc:

$$\{emp\}$$
 $x := malloc()$ $\{x \mapsto -\}$

```
x := malloc();
 [x] := 42;
 free(x)
Both the pre- and post-condition should be { emp }
 { emp }
    x := malloc();
 \{ x \mapsto - \}
    [x] := 42;
 \{ x \mapsto 42 \}
    free(x);
                              Proof rule for free:
 \{ emp \}
                       \{x \mapsto v\} free(x) \{emp\}
```

Deep copy contents of one list to another:

```
p := x;
q := y
while (p != null) {
  temp1 := [p];
  temp2 := [q];
  [p] := temp2;
  [q] := temp1;
  p := [p + 1];
  q := [q + 1]
}
```

Shallow copy much simpler:

List predicate:

```
list(x, s) \equiv
x = null \land s = [] \land emp
\forall \exists v, n, s'. x \mapsto v * x + 1 \mapsto n * list(n, s') \land s = v :: s'
```

Precondition:

$$\{list(x, s_1) * list(y, s_2)\}$$
 where $|s_1| = |s_2|$

Postcondition:

$$list(x, s_2) * list(y, s_1)$$

```
p := x;
q := y
while (p != null) {
   temp1 := [p];
   temp2 := [q];
   [p] := temp2;
   [q] := temp1;
   p := [p + 1];
   q := [q + 1]
}
```

```
list\_seg(r, r, []) \equiv emp list\_seg(r, s, v :: vs) \equiv \exists n . r \mapsto v, n * list\_seg(n, s, vs) \text{ if } r \neq s
```

Loop invariant (spatial):

```
\exists s_{1_a}, s_{1_b}, s_{2_a}, s_{2_b}. \texttt{list\_seg}(\texttt{x}, \texttt{p}, \texttt{s}_{1_a}) * \texttt{list}(\texttt{p}, s_{1_b}) * \texttt{list\_seg}(\texttt{y}, \texttt{q}, s_{2_a}) * \texttt{list}(\texttt{q}, s_{2_b})
```

Loop invariant (content):

$$|s_{1_a}| = |s_{2_a}| \land \forall i < |s_{1_a}[i] \cdot s_{1_a}[i] = \text{old}(s_{2_a}[i]) \land s_{2_a}[i] = \text{old}(s_{1_a}[i])$$

```
list(\mathbf{x},\mathbf{s}) \equiv
\mathbf{j} := \text{null};
\mathbf{while} \ \mathbf{i} \neq \text{null} \ \mathbf{do} \ \{ \\ \mathbf{k} := [\mathbf{i} + 1]; \\ [\mathbf{i} + 1] := \mathbf{j}; \\ \mathbf{i} := \mathbf{k}; \\ \}
Precondition:
\{list(\mathbf{j}, rev(s_0))\}
```

Loop invariant:

$$\exists s_1, s_2 . list(i, s_1) * list(j, s_2) \land s_0 = rev(s_2) + s_1$$

```
j := null;
while i ≠ null do {
    k := [i + 1];
    [i + 1] := j;
    j := i;
    i := k;
}
```

```
list(i, s_0) from precondition

j = null \Rightarrow list(j, [])

s_1 = s_0, s_2 = []
```

Invariant holds

$$\exists s_1, s_2 . list(i, s_1) * list(j, s_2) \land s_0 = rev(s_2) + s_1$$

```
j := null;
while i ≠ null do {
    k := [i + 1];
    [i + 1] := j;
    j := i;
    i := k;
}
```

invariant:

$$\exists s_1, s_2 . list(i, s_1) * list(j, s_2) \land s_0 = rev(s_2) + s_1$$
list:

 $\exists v, n, s'. x \mapsto v * x + 1 \mapsto n * list(n, s') \land s = v :: s'$

```
list(i, s'): unreversed list remaining list(j, v :: s_2): reversed list extend by head node (justified by assignment - j := i rev(v :: s_2) = rev(s_2) + [v] - s_0 = rev(s_2) + (v :: s') = rev(v :: s_2) + s' list(i, s') * list(j, v :: s_2) \land s_0 = rev(v :: s_2) + s'
```

```
j := null;
while i ≠ null do {
    k := [i + 1];
    [i + 1] := j;
    i := i;
    i := k;
}
```

invariant:

$$\exists s_1, s_2 . list(i, s_1) * list(j, s_2) \land s_0 = rev(s_2) + s_1$$

When
$$i = null$$
,
 $s_1 = [], list(i, []) = emp$

$$list(j, s_2) \land s_0 = rev(s_2) \Rightarrow list(j, rev(s_0))$$

Bi-Abduction

A logical proof typically asserts the validity of statements of the form: $A \vdash B$ which states that B holds assuming A is true

To infer properties of problems in Separation Logic, an alternative proof inference technique called Bi-abduction is used:

 $A*antiFrame \vdash B*frame$

Here, the anti-frame refers to missing part of the heap that may be accessed, while the frame is the part of the heap that is implied by the original heap that is valid after B is satisfied

A bi-abduction inference procedure enables modular inter-procedural reasoning

Anti-frame

Current heap (Pre): $x \mapsto I$

Wish to call a function f whose specification requires: $(x \mapsto _ * y \mapsto *)$

Add an anti-frame to the caller's heap that includes y

A function invokes a method (free_list) to deallocate a list

```
Spec for free_list: { list(x) } free_list(x) {emp}
where
 list(x) \equiv (x = null \land emp) \lor (\existsy.x \mapsto y* list(y))
```

Suppose the heap state prior to the call is determined to be:

Pre
$$\equiv$$
 (x.next \mapsto y * y.next \mapsto z)

Is the call to free_list safe?

Can we extend Pre with a heap A such that Pre $*A \vdash list(x)$

- Infer an anti-frame that z is a list in the heap:

$$\equiv$$
 (x.next \mapsto y * y.next \mapsto z) * list(z)

Suppose the client expects a post-condition: $\{a \mapsto v\}$

- But, free_list's post-condition is { emp }. Infer a frame that represents the portion of the heap consistent with the heap returned by free_list and the post-condition:

$$\{emp * a \mapsto v\}$$