

LINK LAYER TECHNOLOGIES

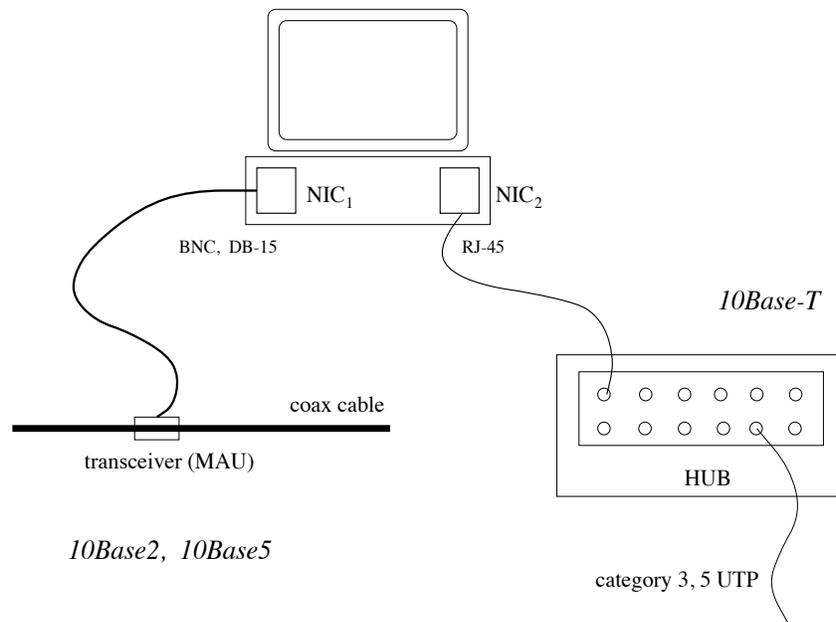
Ethernet

- CSMA/CD for backward compatibility
- switched
- copper, fiber

Recent speeds:

- 1000Base-T (GigE): 1 Gbps over copper
 - version over fiber optic
- 10, 40, 100, 200, 400 Gbps Ethernet: fiber; cat 6, 7 copper
 - IEEE 802.3z
- 800 Gbps, 1.6 Tbps
 - IEEE 802.3dj
 - fiber

Ethernet technology evolution:



→ each NIC assigned unique 48-bit address

From bus, hub to switch

→ computer with specialized hardware support

But bus technology reused in powerline networks

→ IEEE 1901 (HomePlug)

48-bit address:

→ called MAC or hardware address

→ broadcast address: all 1's

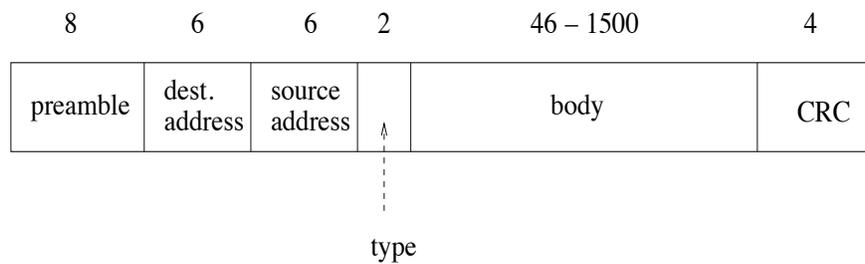
Each Ethernet frame has “From” (source) and “To” (destination) address.

→ WiFi frame has 3–4 addresses

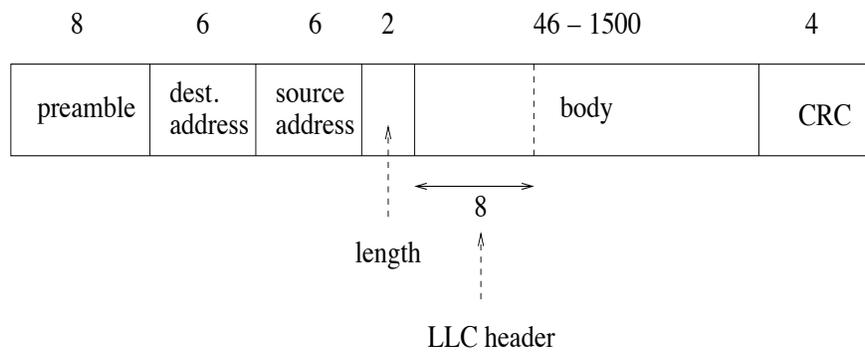
NIC at receiver: accepts frames with matching destination address

- default
- can accept all frames
 - promiscuous mode
 - requires root privilege
 - useful for traffic monitoring/sniffing

DIX Ethernet frame:



IEEE 802.3 Ethernet frame:



→ type: e.g., 0x0800 for IPv4

→ DIX dominant: incorporated into IEEE standard

Ethernet MAC protocol: CSMA/CD

- MA (Multiple Access): multiple nodes are allowed simultaneous access
 - just send
- CS (Carrier Sense): can detect if some other node is using the link
 - rule: if busy, wait until channel is not busy
- CD (Collision Detection): can detect frame collision stemming from simultaneous transmissions
 - rule: if collision, try later

Collision detection mechanism:

- while sending monitor link
- if other signal/activity is detected: collision

If collision occurs:

- failure to decode bits carried by arriving signal
- same holds at other end

Frame retransmitted when collision detected

- stop-and-wait with negative ACK
- collision event acts as negative ACK
- not through timeout

How to guarantee collision detection?

Through standard specification: 10 Mbps Ethernet specification

→ link cannot be longer than 2500 m

→ measured RTT: $51.2 \mu\text{s}$

To ensure collision is detected:

→ sender must stay active for 51.2μ

→ worst-case collision scenario

For 10 Mbps Ethernet

→ frame size must be at least 512 bits

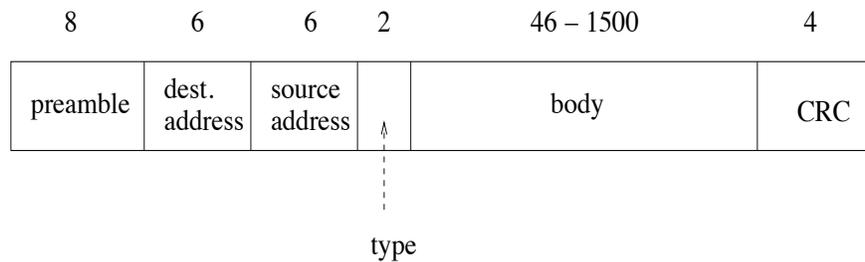
→ i.e., $512 \text{ bits} = 10 \text{ Mbps} \times 51.2 \mu\text{s}$

→ use padding if data is less than 64 bytes

Transmit at least 512 bits for CD:

$$\rightarrow 6 + 6 + 2 + 46 + 4 = 64 \text{ B} = 512 \text{ bits}$$

\rightarrow minimum payload size of Ethernet frame



To achieve collision detection (CD) in 100 Mbps Ethernet:

\rightarrow length restriction (250 m)

Too restrictive

\rightarrow not needed in switched Ethernet

\rightarrow two Ethernet switches connected via full-duplex link
disable CD (and CS)

Upon collision: when attempt retransmission?

→ try to avoid repeat collision

→ randomize attempt period

→ increase attempt period if collision repeats

Retransmission protocol: exponential backoff

1. Wait for random $0 \leq X \leq 51.2 \mu\text{s}$ before 1st retry

2. Two consecutive collisions: wait for random $0 \leq X \leq 102.4 \mu\text{s}$ before 2nd retry

3. Three consecutive collisions: wait for random $0 \leq X \leq 204.8 \mu\text{s}$ before 3rd retry

4. i consecutive collisions: wait for $0 \leq X \leq 2^{i-1} 51.2 \mu\text{s}$ before next attempt

5. Give up if $i > 16$

→ why exponential backoff?

Today: switched Ethernet with full-duplex links

- not shared bus anymore
 - every device connected by point-to-point link to switch
 - sender/receiver cannot collide
- switch: computer
 - with special hardware support to speed up packet handling
- arriving Ethernet frames subject to scheduling
 - e.g., FIFO, priority, fair queueing
 - finite buffers
 - frame losses due to buffer overflow, not collision