Out-of-Distribution Generalization via Risk Extrapolation "learning to define a cow"

J. Setpal

March 28, 2023



ML@P - Reading Group

Risk Extrapolation

March 28, 2023

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- 1 Task Description
- **2** Risk-Aware Optimization
- **3** Risk Extrapolation
- 4 Evaluation

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1 Task Description

2 Risk-Aware Optimization

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The objective is to maximize likelihood:

$$\mathcal{L}(\mathbf{W}, \{(x_i, y_i)\}_{i=1}^N) = \operatorname{argmax}_{\mathbf{W}} \prod_{i=1}^N p(\mathbf{y}_i | \mathbf{x}_i; \mathbf{W})$$

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This is almost *too powerful*! Most models are overparameterized, and maximum likelihood does not care about the causal basis for the data.

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	Group-1	Group-2	Group-3	Group-4
Accuracy	0.9593	0.6249	0.3157	0.2664
Loss	0.0021	0.4102	1.3457	1.7664
Proportion	0.9	0.08	0.0075	0.0025

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The prediction on an input from Group-4 is too inaccurate to be considered.

We can formalize this as a **pertubation set** of risk:

$$\mathcal{R}_{\mathcal{F}}^{\mathsf{OOD}}(\theta) = \max_{e \in \mathcal{F}} \mathcal{R}_{e}(\theta)$$

where \mathcal{F} is the set of possible test domains, & θ is our predictor.

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Risk Extrapolation uncovers **invariant relationships** between the input and outputs. A model that bases predictions on an invariant relationship is an **invariant predictor**. 1 Task Description

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$$\mathcal{J}_{\mathsf{ERM}}(heta) \doteq \operatorname{argmin}_{ heta} \frac{1}{|\mathcal{G}|} \sum_{g \in \mathcal{G}} \ell(x_i, y_i; heta)$$

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Just Train Twice (Liu, et.al; 2021) presents an interesting approach that obtains group information by multi-stage training, re-weighting the cost and subsequently re-training.

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This is phrased as a penalized loss:

$$\mathcal{J}_{\mathsf{IRM}}(heta, \mathcal{D}) \doteq \sum_{e \in \mathcal{E}} \mathcal{R}^{e}(heta \circ \mathcal{D}) + \lambda \cdot \mathbb{D}(heta, \mathcal{D}, e)$$

where $\lambda \in [0, \infty)$ is a hyper-parameter balancing prediction power and invariance, \mathbb{D} represents loss-specific risk.

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For data containing multiple domains, test distributions are assumed to be **convex combinations** of the training distribution. This is equivalent to setting $\mathcal{F} \doteq \mathcal{E}$:

$$\mathcal{R}_{\mathsf{RI}}(\theta) \doteq \max_{\sum_{e} \lambda_{e}=1, \lambda_{e} \ge 0} \sum_{e=1}^{m} \lambda_{e} \mathcal{R}_{e}(\theta) = \max_{e \in \mathcal{E}} \mathcal{R}_{e}(\theta)$$

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Minimax-REx fundamentally *extrapolates* on DRO. By setting $\lambda_e \geq \lambda_{\min}$:

$$\mathcal{R}_{\mathsf{MM-REx}}(\theta) \doteq \max_{\sum_{e} \lambda_e = 1, \ \lambda_e \ge \lambda_{\min}} \sum_{e=1}^{m} \lambda_e \mathcal{R}_e(\theta)$$

 $\doteq (1 - m\lambda_{\min}) \max_e \mathcal{R}_e(\theta) + \lambda_{\min} \sum_{e=1}^{m} \mathcal{R}_e(\theta)$

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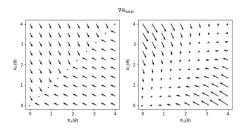
As $\lambda_{\min} \to -\infty$, it enforces equality between training risks. This is proposed as a definition of **fairness**.

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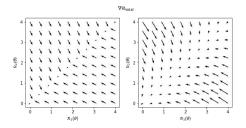
Risk Extrapolation

While MM-REx defines the extrapolation procedure very cleanly, the resultant gradient (left) is extreme:

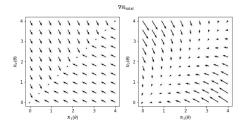


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Adding the variance-based risk regularizer, we obtain the following: $\mathcal{R}_{\text{V-REx}}(\theta) \doteq \beta \sigma^2(\{\mathcal{R}_i\}_{i=1}^m) + \sum_{e=1}^m \mathcal{R}_e(\theta)$

where $\beta \in [0,\infty)$ & $\beta \to \infty$ motivates risk equality.

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Algorithm		VLCS	PACS	OfficeHome
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IRM	51.8 ± 0.1	78.1 ± 0.0	84.4 ± 1.1	66.6 ± 1.0
V-REx	52.1 ± 0.1	77.9 ± 0.5	85.8 ± 0.6	66.7 ± 0.5

V-REx shows comparable performance on domain generalization benchmarks.

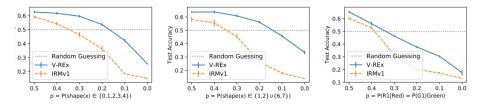
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However, when you include a *covariate shift*, V-REx **outperforms** IRM on dataset variants that include domain shift:



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Have an awesome rest of your day!

Slides: https://cs.purdue.edu/homes/jsetpal/slides/rex.pdf