## Interpretability Tools as Feedback Loops BoilerMake X

J. Setpal

January 21, 2023



Leveraging Machine Interpretability

Setting the Stage

**2** Baselining Interpretability

**3** Leveraging Interpretability



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#### Setting the Stage

**2** Baselining Interpretability

3 Leveraging Interpretability



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Image: A matched and A matc

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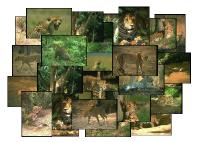
- a. We want to build a classifier (classifiers are cool).
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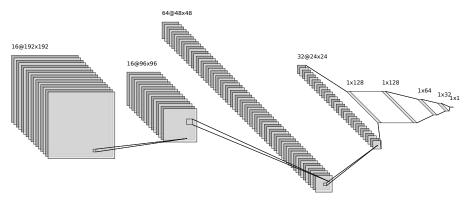


d. There are 188 leopard images and 89 orca images.



## More Scenario Stuff

#### Here's our model architecture:





We use:

- a. Optimizer: SGD
  - Learning Rate: 10<sup>-2</sup>
  - Epsilon:  $10^{-8}$
- b. Loss: BinaryCrossEntropy
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**2** Baselining Interpretability

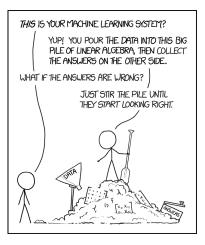
**3** Leveraging Interpretability



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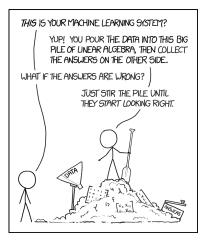
Image: A matrix and a matrix





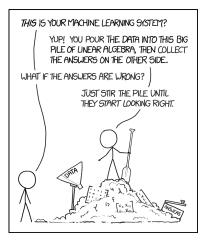
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Interpretability within Machine Learning is the **degree** to which we can understand the **cause** of a decision, and use it to consistently predict the model's prediction.

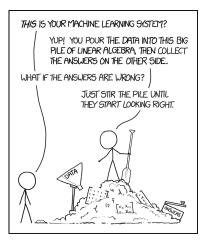




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This is easy for shallow learning. For deep learning however, it is a **lot** harder.



Let's explore: https://interaktiv.br.de/ki-bewerbung/en/

Start-up attempting to make the application process 'faster, but also more objective and fair'.



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They were not successful.



# Class Activation Mappings

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- Expose weights.
- Observe!



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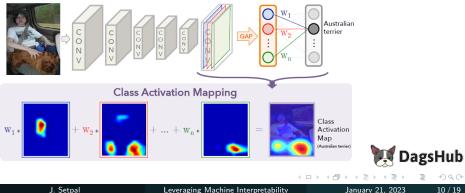
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We'll focus today's discussion on Class Activation Mappings (CAMs):



#### Building Feedback Loops

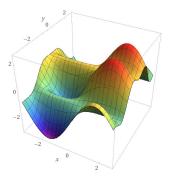
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Model Search Space

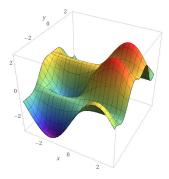


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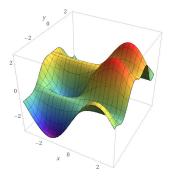


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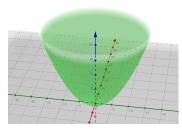
Model Search Space

So, the idea here is simple: use <u>shared knowledge</u> (+ common sense) to modify how we train our models.

We approach the challenge in the opposite direction.



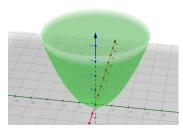




By updating our loss function to eliminate *pseudo-correctness*, we can:

Updated Search Space!



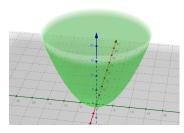


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Updated Search Space!

By updating our loss function to eliminate *pseudo-correctness*, we can:

- Make the optimal weights incredibly easy for our optimzer to find.
- Allow our generalized model to extrapolate on implicit information.



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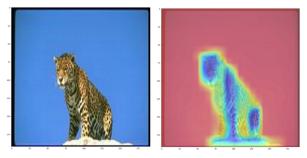
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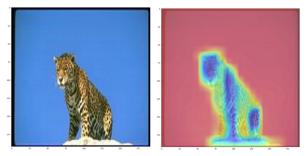


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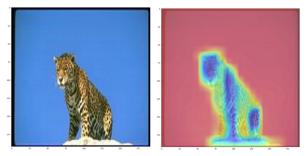
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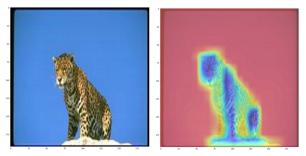


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Q: Can we exploit this?

Idea: Let's penalize our batch whenever the CAM is off-center.

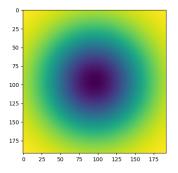


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We can achieve this by inverting a 2D Gaussian Kernel.

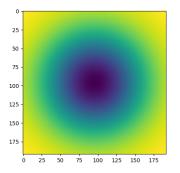


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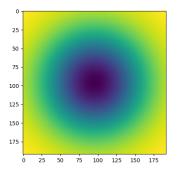
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Inverted Gaussian Kernel

Weights scale sharply as the operation approaches the image boundary.

It has to <u>not</u> be perfect, since we don't intend to overfit our model to this setup. This kernel filter is a **guideline**.



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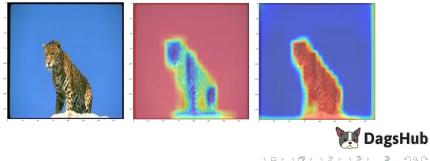


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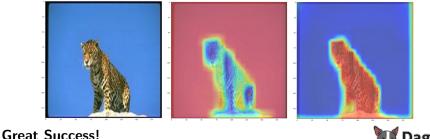
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#### If you can view this screen, I am making a mistake.



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#### Have an awesome rest of your day! Any questions for me?

#### Code, Experiments, Data, Slides: https://dagshub.com/jinensetpal/lint.git

