CS 580: Algorithm Design and Analysis

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Purdue University
Spring 2019

Midterm Exam Tomorrow Night: Wed, Feb 20 (8PM-10PM) @ EE 170

Course Recap: (Or, What Could be On the First Midterm?)

Gale-Shapley, Stable Matching Problem

Asymptotic Analysis (e.g., Big O notation)

Recurrence Relationships

Greedy Algorithms

Graph Algorithms

Divide-And-Conquer + Recurrence Relationships

Dynamic Programming

Basic Questions about Network Flow (today)

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Midterm 1

Practice Midterm and Solutions Posted on Blackboard
- Solutions posted yesterday (Monday)

- No electronics (laptop, calculator, smart phone etc…)

- May prepare one 3x5 inch index card with any notes you want
  - No additional notes

- Exam is 2 hours (8PM to 10PM)
  - Practice exam is longer than the real midterm
  - Topics are reasonably representative of real midterm

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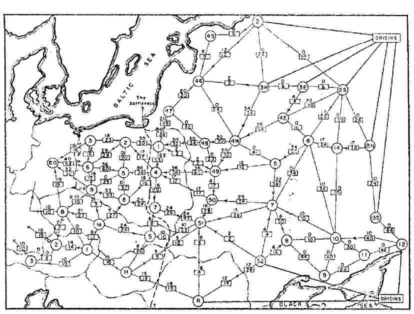
Chapter 7

Network Flow

Soviet Rail Network, 1955



Reference: *On the history of the transportation and maximum flow problems.* Alexander Schrijver in Math Programming, 91: 3, 2002.

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Maximum Flow and Minimum Cut

Max flow and min cut.
- Two very rich algorithmic problems.
- Cornerstone problems in combinatorial optimization.
- Beautiful mathematical duality.

Nontrivial applications / reductions.
- Data mining.
- Open-pit mining.
- Project selection.
- Airline scheduling.
- Bipartite matching.
- Baseball elimination.
- Image segmentation.
- Network connectivity.
- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- Security of statistical data.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Many many more …

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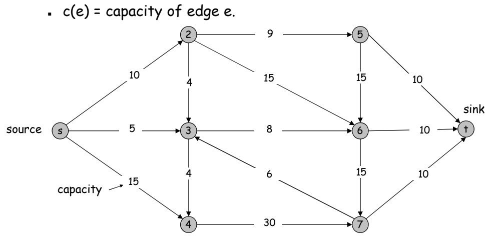
Minimum Cut Problem

Flow network.
- Abstraction for material flowing through the edges.
- G = (V, E) = directed graph, no parallel edges.
- Two distinguished nodes: s = source, t = sink.
- c(e) = capacity of edge e.



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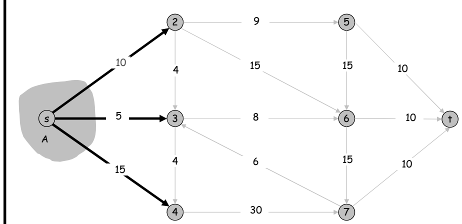
Cuts

Def. An s-t cut is a partition (A, B) of V with s ∈ A and t ∈ B.

Def. The capacity of a cut (A, B) is: $cap(A, B) = \sum_{e \text{ out of } A} c(e)$



Capacity = 10 + 5 + 15
= 30

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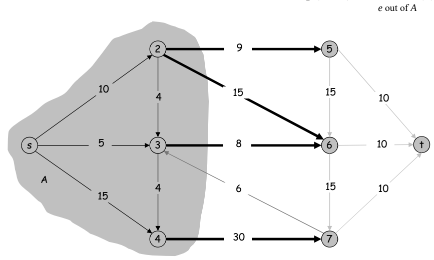

Capacity = 9 + 15 + 8 + 30
= 62

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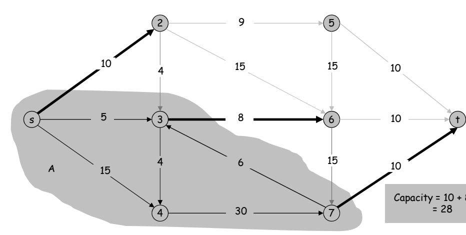
Minimum Cut Problem

Min s-t cut problem. Find an s-t cut of minimum capacity.



Capacity = 10 + 8 + 10
= 28

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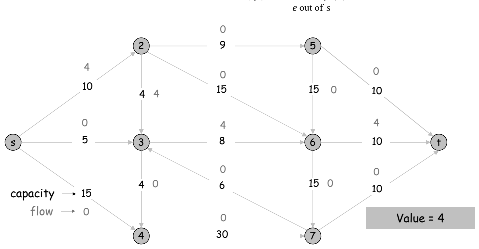
Flows

Def. An s-t flow is a function that satisfies:
- For each e ∈ E: $0 \le f(e) \le c(e)$ [capacity]
- For each v ∈ V – {s, t}: $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$ [conservation]

Def. The value of a flow f is: $v(f) = \sum_{e \text{ out of } s} f(e)$.



Value = 4

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Flows

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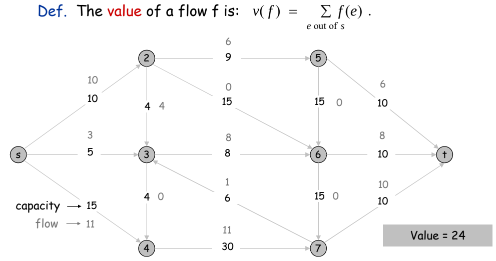

Value = 24

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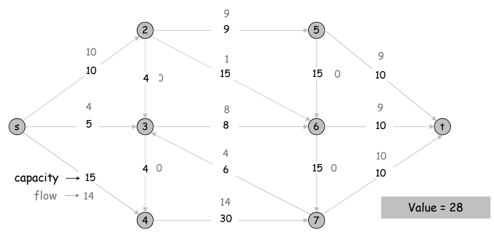
Maximum Flow Problem

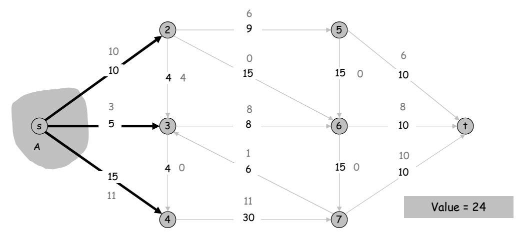
Max flow problem. Find s-t flow of maximum value.



Flows and Cuts

Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

$$\sum_{e \text{ out of } A} f(e) \;-\; \sum_{e \text{ in to } A} f(e) \;=\; v(f)$$



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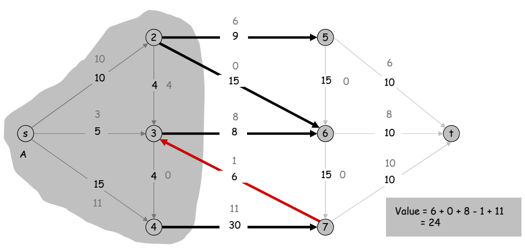

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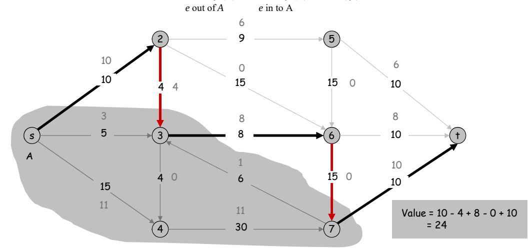


Flows and Cuts

Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$$

Pf.

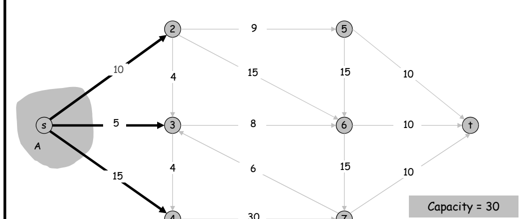
$$\begin{aligned} v(f) &= \sum_{e \text{ out of } s} f(e) \\ &= \sum_{v \in A} \left(\sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right) \\ &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e). \end{aligned}$$

by flow conservation, all terms except v = s are 0 →

Flows and Cuts

Weak duality. Let f be any flow, and let (A, B) be any s-t cut. Then the value of the flow is at most the capacity of the cut.

Cut capacity = 30 $\Rightarrow$ Flow value $\leq$ 30

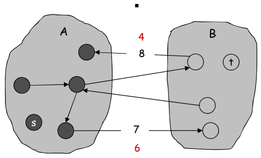


Flows and Cuts

Weak duality. Let f be any flow. Then, for any s-t cut (A, B) we have v(f) ≤ cap(A, B).

Pf.
$$\begin{aligned} v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\ &\le \sum_{e \text{ out of } A} f(e) \\ &\le \sum_{e \text{ out of } A} c(e) \\ &= \text{cap}(A,B) \end{aligned}$$

▪



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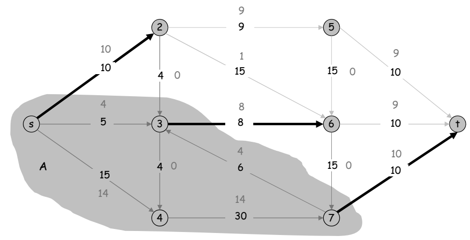
Certificate of Optimality

Corollary. Let f be any flow, and let (A, B) be any cut.
If v(f) = cap(A, B), then f is a max flow and (A, B) is a min cut.

Value of flow = 28
Cut capacity = 28 ⇒ Flow value ≤ 28



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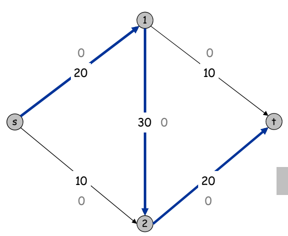
Towards a Max Flow Algorithm

Greedy algorithm.
- Start with f(e) = 0 for all edge e ∈ E.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.



Flow value = 0

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Towards a Max Flow Algorithm

Greedy algorithm.
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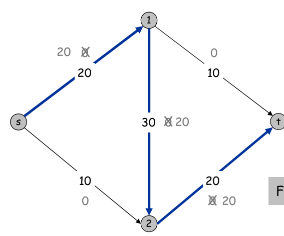

Flow value = 20

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Towards a Max Flow Algorithm

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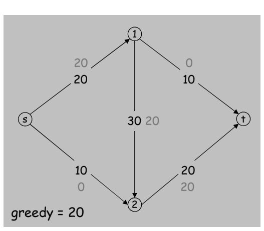
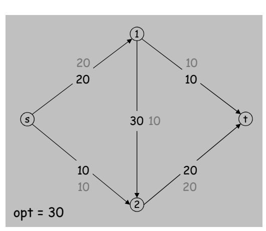
- Start with f(e) = 0 for all edge e ∈ E.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.

locally optimality ⇏ global optimality





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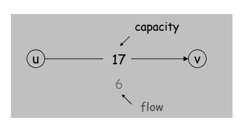
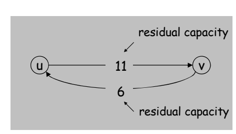
Residual Graph

Original edge: e = (u, v) ∈ E.
- Flow f(e), capacity c(e).



Residual edge.
- "Undo" flow sent.
- e = (u, v) and e^R = (v, u).
- Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$



Residual graph: $G_f = (V, E_f)$.
- Residual edges with positive residual capacity.
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}$.

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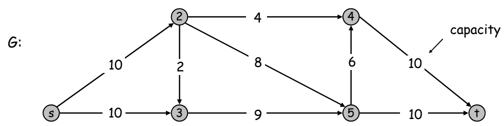
Ford-Fulkerson Algorithm



play

Augmenting Path Algorithm

```
Augment(f, c, P) {
   b ← bottleneck(P)
   foreach e ∈ P {
      if (e ∈ E) f(e) ← f(e) + b        forward edge
      else       f(eᴿ)← f(eᴿ) - b       reverse edge
   }
   return f
}
```

```
Ford-Fulkerson(G, s, t, c) {
   foreach e ∈ E  f(e) ← 0
   G_f ← residual graph

   while (there exists augmenting path P) {
      f ← Augment(f, c, P)
      update G_f
   }
   return f
}
```


Max-Flow Min-Cut Theorem

Augmenting path theorem. Flow f is a max flow iff there are no augmenting paths.

Max-flow min-cut theorem. [Elias-Feinstein-Shannon 1956, Ford-Fulkerson 1956] The value of the max flow is equal to the value of the min cut.

Pf. We prove both simultaneously by showing TFAE:
- (i) There exists a cut (A, B) such that v(f) = cap(A, B).
- (ii) Flow f is a max flow.
- (iii) There is no augmenting path relative to f.

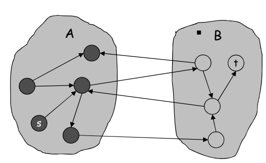
(i) ⇒ (ii) This was the corollary to weak duality lemma.

(ii) ⇒ (iii) We show contrapositive.
- Let f be a flow. If there exists an augmenting path, then we can improve f by sending flow along path.

Proof of Max-Flow Min-Cut Theorem

(iii) ⇒ (i)
- Let f be a flow with no augmenting paths.
- Let A be set of vertices reachable from s in residual graph.
- By definition of A, $s \in A$.
- By definition of f, $t \notin A$.

$$\begin{aligned} v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\ &= \sum_{e \text{ out of } A} c(e) \\ &= cap(A, B) \end{aligned}$$



original network

Running Time

Assumption. All capacities are integers between 1 and C.

Invariant. Every flow value f(e) and every residual capacity c_f (e) remains an integer throughout the algorithm.

Theorem. The algorithm terminates in at most $v(f^*) \le nC$ iterations.
Pf. Each augmentation increase value by at least 1. ▪

Corollary. If C = 1, Ford-Fulkerson runs in O(mn) time.

Integrality theorem. If all capacities are integers, then there exists a max flow f for which every flow value f(e) is an integer.
Pf. Since algorithm terminates, theorem follows from invariant. ▪

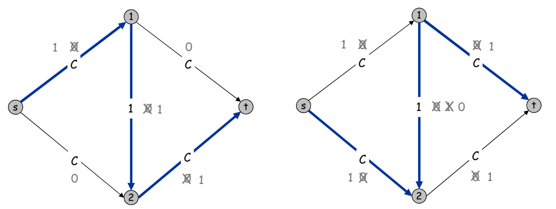
7.3 Choosing Good Augmenting Paths

Ford-Fulkerson: Exponential Number of Augmentations

Q. Is generic Ford-Fulkerson algorithm polynomial in input size?

m, n, and log C

A. No. If max capacity is C, then algorithm can take C iterations.



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Choosing Good Augmenting Paths

Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

Goal: choose augmenting paths so that:

- Can find augmenting paths efficiently.
- Few iterations.

Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]

- Max bottleneck capacity.
- Sufficiently large bottleneck capacity.
- Fewest number of edges.

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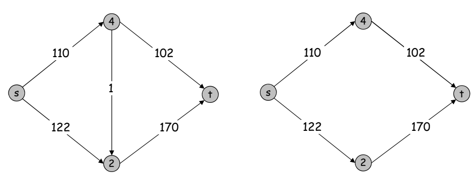
Capacity Scaling

Intuition. Choosing path with highest bottleneck capacity increases flow by max possible amount.

- Don't worry about finding exact highest bottleneck path.
- Maintain scaling parameter Δ.
- Let $G_f(\Delta)$ be the subgraph of the residual graph consisting of only arcs with capacity at least Δ.



G_f $\qquad$ $G_f(100)$

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Capacity Scaling

```
Scaling-Max-Flow(G, s, t, c) {
   foreach e ∈ E  f(e) ← 0
   Δ ← smallest power of 2 greater than or equal to C
   Gf ← residual graph

   while (Δ ≥ 1) {
      Gf(Δ) ← Δ-residual graph
      while (there exists augmenting path P in Gf(Δ)) {
         f ← augment(f, c, P)
         update Gf(Δ)
      }
      Δ ← Δ / 2
   }
   return f
}
```

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Capacity Scaling: Correctness

Assumption. All edge capacities are integers between 1 and C.

Integrality invariant. All flow and residual capacity values are integral.

Correctness. If the algorithm terminates, then f is a max flow.

Pf.

- By integrality invariant, when $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$.
- Upon termination of $\Delta = 1$ phase, there are no augmenting paths. ▪

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Capacity Scaling: Running Time

Lemma 1. The outer while loop repeats $1 + \lceil \log_2 C \rceil$ times.

Pf. Initially $C \le \Delta < 2C$. Δ decreases by a factor of 2 each iteration. ▪

Lemma 2. Let f be the flow at the end of a Δ-scaling phase. Then the value of the maximum flow is at most $v(f) + m\,\Delta$. ← proof on next slide

Lemma 3. There are at most 2m augmentations per scaling phase.

- Let f be the flow at the end of the previous scaling phase.
- L2 $\Rightarrow$ $v(f^*) \le v(f) + m\,(2\Delta)$.
- Each augmentation in a Δ-phase increases v(f) by at least Δ. ▪

Theorem. The scaling max-flow algorithm finds a max flow in O(m log C) augmentations. It can be implemented to run in O(m^2 log C) time. ▪

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Capacity Scaling: Running Time

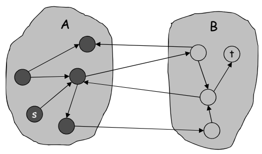
Lemma 2. Let f be the flow at the end of a Δ-scaling phase. Then value of the maximum flow is at most $v(f) + m\,\Delta$.

Pf. (almost identical to proof of max-flow min-cut theorem)

- We show that at the end of a Δ-phase, there exists a cut (A, B) such that $cap(A, B) \leq v(f) + m\,\Delta$.
- Choose A to be the set of nodes reachable from s in $G_f(\Delta)$.
- By definition of A, $s \in A$.
- By definition of f, $t \notin A$.

$$\begin{aligned} v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\ &\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta \\ &= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta \\ &\geq cap(A, B) - m\Delta \end{aligned}$$

▪



original network

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