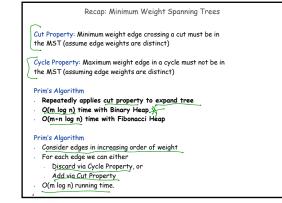
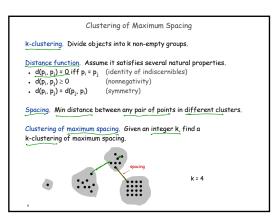
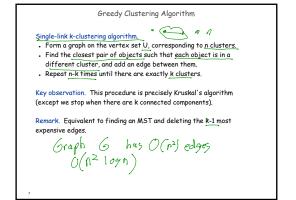
Clustering Clustering. Given a set U of n objects labeled $p_1, ..., p_n$, classify into CS 580: Algorithm Design and Analysis coherent groups. photos, documents, micro-organisms Distance function. Numeric value specifying "closeness" of two objects. Algorithms number of corresponding pixels whose intensities differ by some threshold Jeremiah Blocki Purdue University Spring 2018 Fundamental problem. Divide into clusters so that points in different clusters are far apart. . Routing in mobile ad hoc networks. . Identify patterns in gene expression. JON KLEINBERG - ÉVA TARDOS • Document categorization for web search. • Similarity searching in medical image databases • Skycat: cluster 10⁹ sky objects into stars, quasars, galaxies. Announcement: Homework 2 due on Tuesday, February 6th at 11:59PM



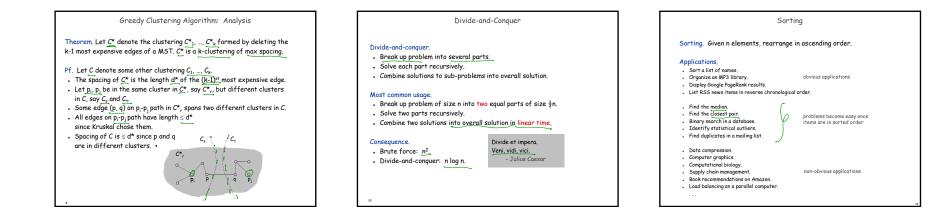


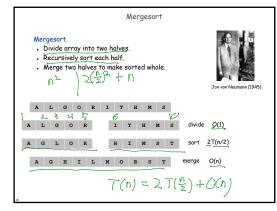


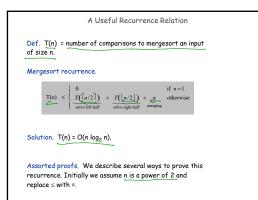


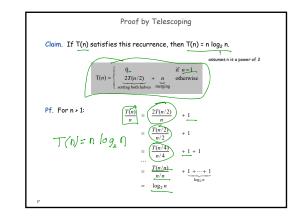


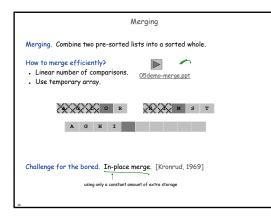
5.1 Mergesort

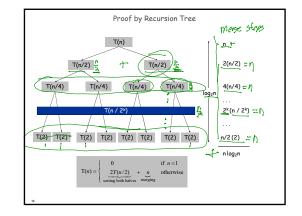


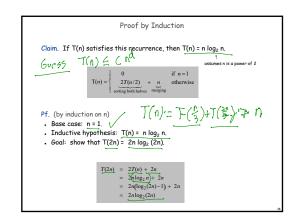


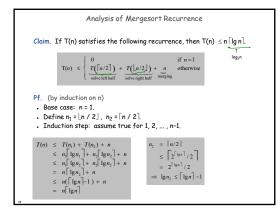


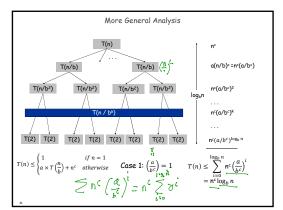


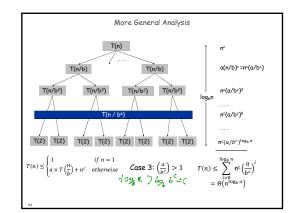


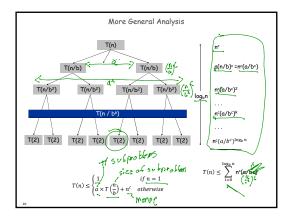


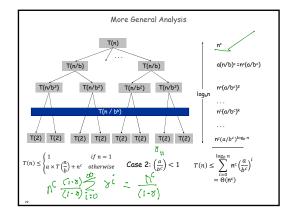


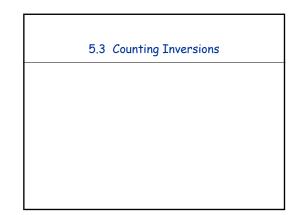


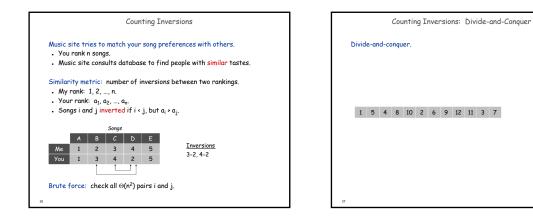




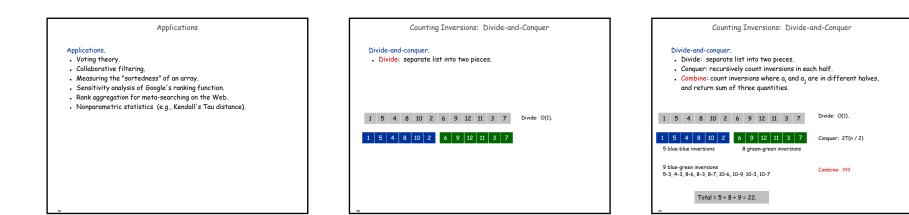


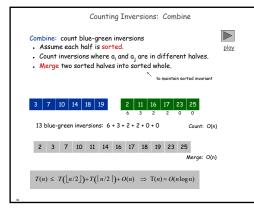


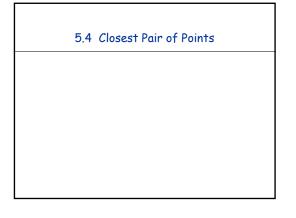


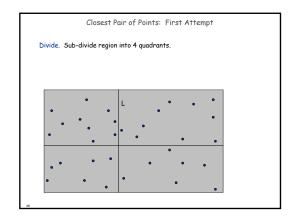


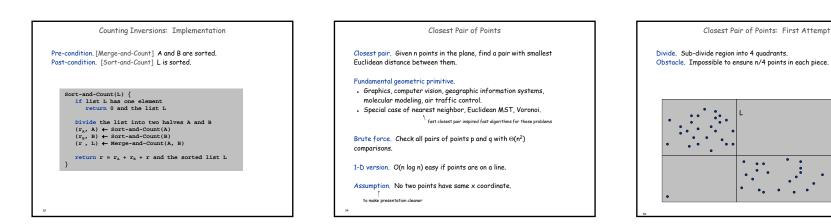
Counting Inversions: Divide-and-Conquer				
 Divide-and-conquer. Divide: separate list into two pieces. Conquer: recursively count inversions in each half. 				
1 5 4 8 10 2 6 9 12 11 3 7 Divide: O(1).				
1 5 4 8 10 2 6 9 12 11 3 7 Conquer: 2T(n / 2)				
5 blue-blue inversions 8 green-green inversions				
5-4, 5-2, 4-2, 8-2, 10-2 6-3, 9-3, 9-7, 12-3, 12-7, 12-11, 11-3, 11-7				
2				

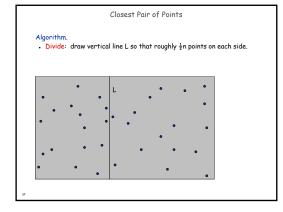


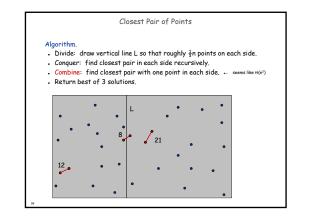


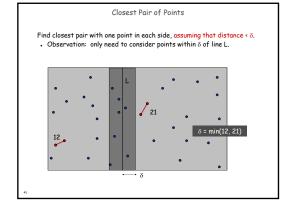


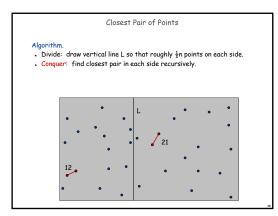


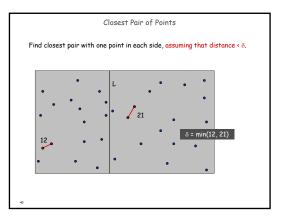


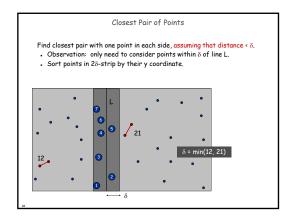


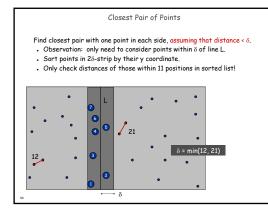












Closest Pair Algorithm			
$\label{eq:closest-Pair(p_1,, p_n) } \Big\{ $$ Compute separation line L such that half the points are on one side and half on the other side. $$$	O(n log n)		
$ \begin{array}{l} \delta_1 = \texttt{Closest-Pair(left half)} \\ \delta_2 = \texttt{Closest-Pair(right half)} \\ \delta = \min(\delta_1, \ \delta_2) \end{array} $	2T(n / 2)		
Delete all points further than $\boldsymbol{\delta}$ from separation line L	O(n)		
Sort remaining points by y-coordinate.	O(n log n)		
Scan points in y-order and compare distance between each point and next 11 neighbors. If any of these distances is less than $\delta,$ update $\delta.$	O(n)		
return δ. }			

MST Algorithms: Theory		
$\begin{array}{l} \mbox{Deterministic comparis}\\ & O(m \log n)\\ & O(m \log \log n).\\ & O(m \beta(m,n)).\\ & O(m \log \beta(m,n)).\\ & O(m \log \beta(m,n)).\\ & O(m \alpha (m,n)). \end{array}$	[Jarník, ^P rim, Dijkstra, Kruskal, Boruvka] [Cheriton-Tarjan 1976, Yao 1975] [Fredman-Tarjan 1987]	
Holy grail. O(m).		
Notable. • O(m) randomized. • O(m) verification.		
Euclidean. • 2-d: O(n log n). • k-d: O(k n²).	compute MST of edges in Delaunay dense Prim	

