

**CS 580: Algorithm Design and Analysis**

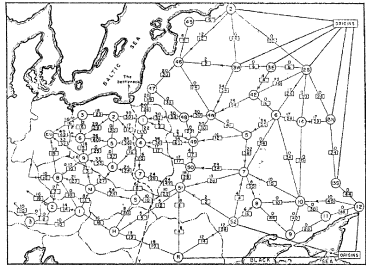
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Spring 2018

Midterm Exam Tomorrow Night: Wed, Feb 21 (8PM-10PM) @ MTHW 210

Midterm 1

- Practice Midterm and Solutions Posted on Blackboard
  - Solutions posted yesterday (Monday)
- No electronics (laptop, calculator, smart phone etc...)
- *May prepare one 3x5 inch index card with any notes you want*
  - No additional notes
- Exam is 2 hours (8PM to 10PM)
  - Practice exam is longer than the real midterm
  - Topics are reasonably representative of real midterm

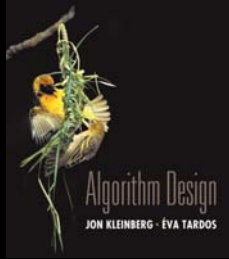
Soviet Rail Network, 1955



Reference: On the history of the transportation and maximum flow problems.  
Alexander Schrijver in Math Programming, 91: 3, 2002.

Course Recap: (Or, What Could be On the First Midterm?)

- Gale-Shapley, Stable Matching Problem
- Asymptotic Analysis (e.g., Big O notation)
- Recurrence Relationships
- Greedy Algorithms
- Graph Algorithms
- Divide-And-Conquer + Recurrence Relationships
- Dynamic Programming
- Basic Questions about Network Flow (today)



**Chapter 7**  
Network Flow

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Maximum Flow and Minimum Cut

*Max flow and min cut.*

- Two very rich algorithmic problems.
- Cornerstone problems in combinatorial optimization.
- Beautiful mathematical duality.

*Nontrivial applications / reductions.*

- Data mining.
- Open-pit mining.
- Project selection.
- Airline scheduling.
- Bipartite matching.
- Baseball elimination.
- Image segmentation.
- Network connectivity.
- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- Security of statistical data.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Many many more ...

### Minimum Cut Problem

**Flow network.**

- Abstraction for material **flowing** through the edges.
- $G = (V, E)$  = directed graph, no parallel edges.
- Two distinguished nodes:  $s$  = source,  $t$  = sink.
- $c(e)$  = capacity of edge  $e$ .

### Cuts

**Def.** An  $s$ - $t$  cut is a partition  $(A, B)$  of  $V$  with  $s \in A$  and  $t \in B$ .

**Def.** The **capacity** of a cut  $(A, B)$  is:  $cap(A, B) = \sum_{e \text{ out of } A} c(e)$

### Flows

**Def.** An  $s$ - $t$  flow is a function that satisfies:

- For each  $e \in E$ :  $0 \leq f(e) \leq c(e)$  [capacity]
- For each  $v \in V - \{s, t\}$ :  $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$  [conservation]

**Def.** The **value** of a flow  $f$  is:  $v(f) = \sum_{e \text{ out of } s} f(e)$ .

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### Minimum Cut Problem

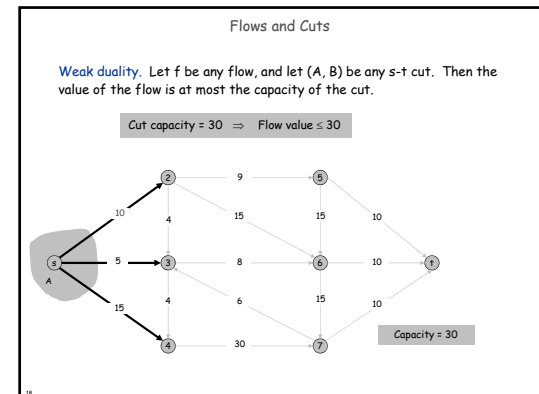
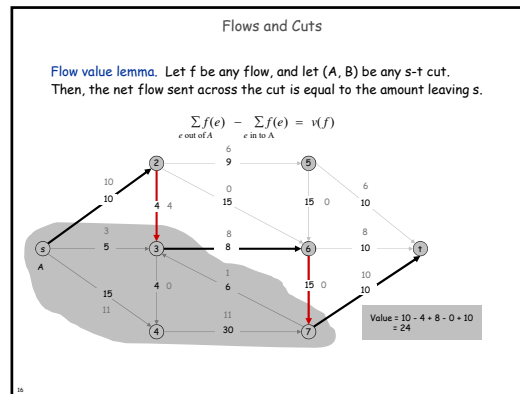
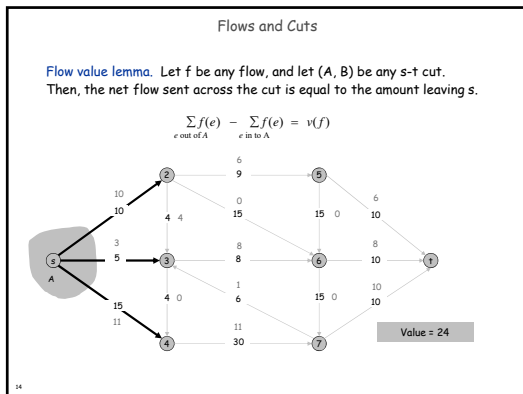
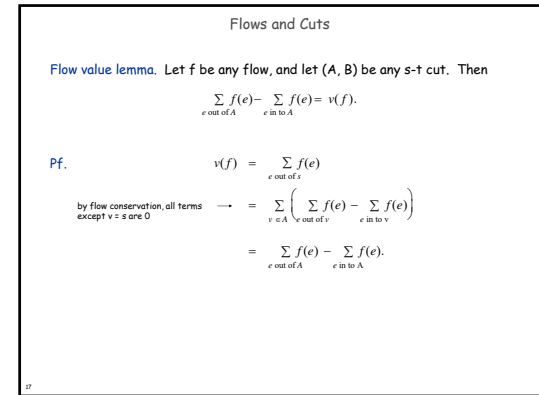
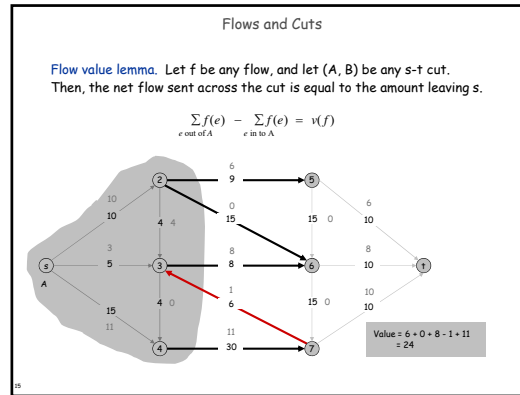
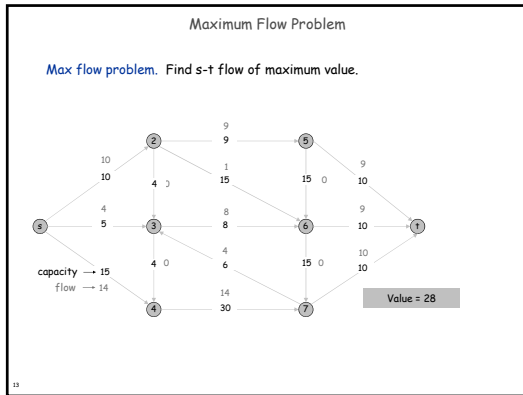
**Min s-t cut problem.** Find an  $s$ - $t$  cut of minimum capacity.

### Flows

**Def.** An  $s$ - $t$  flow is a function that satisfies:

- For each  $e \in E$ :  $0 \leq f(e) \leq c(e)$  [capacity]
- For each  $v \in V - \{s, t\}$ :  $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$  [conservation]

**Def.** The **value** of a flow  $f$  is:  $v(f) = \sum_{e \text{ out of } s} f(e)$ .



### Flows and Cuts

**Weak duality.** Let  $f$  be any flow. Then, for any  $s$ - $t$  cut  $(A, B)$  we have  $v(f) \leq \text{cap}(A, B)$ .

**Pf.**

$$\begin{aligned}
 v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\
 &\leq \sum_{e \text{ out of } A} f(e) \\
 &\leq \sum_{e \text{ out of } A} c(e) \\
 &= \text{cap}(A, B)
 \end{aligned}$$

### Towards a Max Flow Algorithm

**Greedy algorithm.**

- Start with  $f(e) = 0$  for all edge  $e \in E$ .
- Find an  $s$ - $t$  path  $P$  where each edge has  $f(e) < c(e)$ .
- Augment flow along path  $P$ .
- Repeat until you get stuck.

### Towards a Max Flow Algorithm

**Greedy algorithm.**

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- Find an  $s$ - $t$  path  $P$  where each edge has  $f(e) < c(e)$ .
- Augment flow along path  $P$ .
- Repeat until you get **stuck**.

locally optimality  $\neq$  global optimality

### Certificate of Optimality

**Corollary.** Let  $f$  be any flow, and let  $(A, B)$  be any cut. If  $v(f) = \text{cap}(A, B)$ , then  $f$  is a max flow and  $(A, B)$  is a min cut.

Value of flow = 28  
Cut capacity = 28  $\Rightarrow$  Flow value  $\leq$  28

### Towards a Max Flow Algorithm

**Greedy algorithm.**

- Start with  $f(e) = 0$  for all edge  $e \in E$ .
- Find an  $s$ - $t$  path  $P$  where each edge has  $f(e) < c(e)$ .
- Augment flow along path  $P$ .
- Repeat until you get stuck.

### Residual Graph

**Original edge:**  $e = (u, v) \in E$ .

- Flow  $f(e)$ , capacity  $c(e)$ .

**Residual edge.**

- "Undo" flow sent.
- $e = (u, v)$  and  $e^R = (v, u)$ .
- Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$

**Residual graph:**  $G_f = (V, E_f)$ .

- Residual edges with positive residual capacity.
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}$ .

### Ford-Fulkerson Algorithm

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### Max-Flow Min-Cut Theorem

**Augmenting path theorem.** Flow  $f$  is a max flow iff there are no augmenting paths.

**Max-flow min-cut theorem.** [Elias-Feinstein-Shannon 1956, Ford-Fulkerson 1956]  
The value of the max flow is equal to the value of the min cut.

**Pf.** We prove both simultaneously by showing TFAE:

- (i) There exists a cut  $(A, B)$  such that  $v(f) = \text{cap}(A, B)$ .
- (ii) Flow  $f$  is a max flow.
- (iii) There is no augmenting path relative to  $f$ .

(i)  $\Rightarrow$  (ii) This was the corollary to weak duality lemma.

(ii)  $\Rightarrow$  (iii) We show contrapositive.

- Let  $f$  be a flow. If there exists an augmenting path, then we can improve  $f$  by sending flow along path.

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### Running Time

**Assumption.** All capacities are integers between 1 and  $C$ .

**Invariant.** Every flow value  $f(e)$  and every residual capacity  $c_f(e)$  remains an integer throughout the algorithm.

**Theorem.** The algorithm terminates in at most  $v(f^*) \leq nC$  iterations.

**Pf.** Each augmentation increase value by at least 1. •

**Corollary.** If  $C = 1$ , Ford-Fulkerson runs in  $O(mn)$  time.

**Integrity theorem.** If all capacities are integers, then there exists a max flow  $f$  for which every flow value  $f(e)$  is an integer.

**Pf.** Since algorithm terminates, theorem follows from invariant. •

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### Augmenting Path Algorithm

```

Augment(f, c, P) {
  b ← bottleneck(P)
  foreach e ∈ P {
    if (e ∈ E) f(e) ← f(e) + b    forward edge
    else      f(e*) ← f(e*) - b   reverse edge
  }
  return f
}

Ford-Fulkerson(G, s, t, c) {
  foreach e ∈ E f(e) ← 0
  Gr ← residual graph
  while (there exists augmenting path P) {
    f ← Augment(f, c, P)
    update Gr
  }
  return f
}
    
```

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### Proof of Max-Flow Min-Cut Theorem

(iii)  $\Rightarrow$  (i)

- Let  $f$  be a flow with no augmenting paths.
- Let  $A$  be set of vertices reachable from  $s$  in residual graph.
- By definition of  $A$ ,  $s \in A$ .
- By definition of  $f$ ,  $t \notin A$ .

$$\begin{aligned}
 v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\
 &= \sum_{e \text{ out of } A} c(e) \\
 &= \text{cap}(A, B)
 \end{aligned}$$

original network

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## 7.3 Choosing Good Augmenting Paths

Ford-Fulkerson: Exponential Number of Augmentations

Q. Is generic Ford-Fulkerson algorithm polynomial in input size?  
 $m, n,$  and  $\log C$

A. No. If max capacity is  $C$ , then algorithm can take  $C$  iterations.

Capacity Scaling

Intuition. Choosing path with highest bottleneck capacity increases flow by max possible amount.

- Don't worry about finding exact highest bottleneck path.
- Maintain scaling parameter  $\Delta$ .
- Let  $G_f(\Delta)$  be the subgraph of the residual graph consisting of only arcs with capacity at least  $\Delta$ .

Capacity Scaling: Correctness

Assumption. All edge capacities are integers between 1 and  $C$ .

Integrity invariant. All flow and residual capacity values are integral.

Correctness. If the algorithm terminates, then  $f$  is a max flow.

Pf.

- By integrity invariant, when  $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$ .
- Upon termination of  $\Delta = 1$  phase, there are no augmenting paths. •

Choosing Good Augmenting Paths

Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

Goal: choose augmenting paths so that:

- Can find augmenting paths efficiently.
- Few iterations.

Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]

- Max bottleneck capacity.
- Sufficiently large bottleneck capacity.
- Fewest number of edges.

Capacity Scaling

```

Scaling-Max-Flow( $G, s, t, c$ ) {
  foreach  $e \in E$   $f(e) \leftarrow 0$ 
   $\Delta \leftarrow$  smallest power of 2 greater than or equal to  $C$ 
   $G_r \leftarrow$  residual graph
  while ( $\Delta \geq 1$ ) {
     $G_r(\Delta) \leftarrow \Delta$ -residual graph
    while (there exists augmenting path  $P$  in  $G_r(\Delta)$ ) {
       $f \leftarrow$  augment( $f, c, P$ )
      update  $G_r(\Delta)$ 
    }
     $\Delta \leftarrow \Delta / 2$ 
  }
  return  $f$ 
}
    
```

Capacity Scaling: Running Time

Lemma 1. The outer while loop repeats  $1 + \lceil \log_2 C \rceil$  times.

Pf. Initially  $C \leq \Delta < 2C$ .  $\Delta$  decreases by a factor of 2 each iteration. •

Lemma 2. Let  $f$  be the flow at the end of a  $\Delta$ -scaling phase. Then the value of the maximum flow is at most  $v(f) + m \Delta$ . — proof on next slide

Lemma 3. There are at most  $2m$  augmentations per scaling phase.

- Let  $f$  be the flow at the end of the previous scaling phase.
- $L2 \Rightarrow v(f^*) \leq v(f) + m(2\Delta)$ .
- Each augmentation in a  $\Delta$ -phase increases  $v(f)$  by at least  $\Delta$ . •

Theorem. The scaling max-flow algorithm finds a max flow in  $O(m \log C)$  augmentations. It can be implemented to run in  $O(m^3 \log C)$  time. •

Capacity Scaling: Running Time

**Lemma 2.** Let  $f$  be the flow at the end of a  $\Delta$ -scaling phase. Then value of the maximum flow is at most  $v(f) + m \Delta$ .

*Pf.* (almost identical to proof of max-flow min-cut theorem)

- We show that at the end of a  $\Delta$ -phase, there exists a cut  $(A, B)$  such that  $\text{cap}(A, B) \leq v(f) + m \Delta$ .
- Choose  $A$  to be the set of nodes reachable from  $s$  in  $G_f(\Delta)$ .
- By definition of  $A$ ,  $s \in A$ .
- By definition of  $f$ ,  $t \notin A$ .

$$\begin{aligned}
 v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\
 &\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta \\
 &= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta \\
 &\geq \text{cap}(A, B) - m\Delta \quad \blacksquare
 \end{aligned}$$

