

Lecture 01: Mathematical Basics (Probability and Bound on Summations)

- Sample Space (Ω): Set of values (finite, infinite, discrete, continuous)
- Random Variable (\mathbb{X}): Assigns probability to entities in the sample space
- Probability: $\mathbb{P}[\mathbb{X} = x]$ represents the probability that the random variable \mathbb{X} outputs $x \in \Omega$

Joint Distribution and Conditional Distribution

- (\mathbb{X}, \mathbb{Y}) is a joint distribution over the sample space $\Omega_{\mathbb{X}} \times \Omega_{\mathbb{Y}}$, i.e. for $(x, y) \in \Omega_{\mathbb{X}} \times \Omega_{\mathbb{Y}}$ the random variable (\mathbb{X}, \mathbb{Y}) assigns probability to (x, y)
- Joint Distribution $\mathbb{P}[\mathbb{X} = x, \mathbb{Y} = y]$
- Marginal Distribution $\mathbb{P}[\mathbb{X} = x] = \sum_{y \in \Omega_{\mathbb{Y}}} \mathbb{P}[\mathbb{X} = x, \mathbb{Y} = y]$
- Conditional Distribution $(\mathbb{X}|\mathbb{Y} = y)$ is the probability distribution over $\Omega_{\mathbb{X}}$ such that the probability

$$\mathbb{P}[\mathbb{X} = x | \mathbb{Y} = y] := \frac{\mathbb{P}[\mathbb{X} = x, \mathbb{Y} = y]}{\sum_{x \in \Omega_{\mathbb{X}}} \mathbb{P}[\mathbb{X} = x, \mathbb{Y} = y]} = \frac{\mathbb{P}[\mathbb{X} = x, \mathbb{Y} = y]}{\mathbb{P}[\mathbb{Y} = y]}$$

Theorem (Bayes' Theorem)

For a joint distribution (X, Y) over $\Omega_X \times \Omega_Y$ and $\mathbb{P}(Y = y) > 0$, we have

$$\mathbb{P}[X = x|Y = y] = \frac{\mathbb{P}[(Y = y|X = x)] \mathbb{P}[X = x]}{\mathbb{P}[Y = y]}$$

Proof: Cross-multiply and use the definition of conditional probability

Theorem (Chain Rule)

For a joint distribution $(\mathbb{X}_1, \dots, \mathbb{X}_n)$ over $\Omega_{\mathbb{X}_1} \times \dots \times \Omega_{\mathbb{X}_n}$ the following holds

$$\mathbb{P}[\mathbb{X}_1 = x_1, \dots, \mathbb{X}_n = x_n] = \prod_{i=1}^n \mathbb{P}[\mathbb{X}_i = x_i | \mathbb{X}_1 = x_1, \dots, \mathbb{X}_{i-1} = x_{i-1}]$$

Intuition: The probability of (x_1, \dots, x_n) occurring is equal to the following probabilities

- Probability $\mathbb{X}_1 = x_1$ happens .
- Conditioned on $\mathbb{X}_1 = x_1$ happening, $\mathbb{X}_2 = x_2$ happens
- Conditioned on $(\mathbb{X}_1 = x_1, \dots, \mathbb{X}_{i-1} = x_{i-1})$ happening, $\mathbb{X}_i = x_i$ happens
- And so on ...

Proof: Use Induction on n

- Let \mathbb{X} be a random variable over the sample space Ω
- Let $S \subseteq \Omega$
- The probability a sample drawn according to \mathbb{X} being in S is defined to be

$$\mathbb{X}(S) := \sum_{x \in S} \mathbb{P}[\mathbb{X} = x]$$

Functions applied on Random Variables

- Let \mathbb{X} be a random variable over the sample space Ω
- Let $f: \Omega \rightarrow \Omega'$ be a function
- By $f(\mathbb{X})$ we denote the random variable over Ω' such that the probability of sampling $y \in \Omega'$ is given by

$$\sum_{x \in \Omega: f(x)=y} \mathbb{P}[\mathbb{X} = x]$$

- Intuition: $f(\mathbb{X})$ is a random variable such that $f(\mathbb{X})(y)$, i.e. the probability of outputting $y \in \Omega'$, is the probability that $x \in \Omega$ is sampled by \mathbb{X} such that $f(x) = y$
- Alternately, $f(\mathbb{X})$ is the probability distribution that samples $y \in \Omega'$ with probability

$$\mathbb{X}(f^{-1}(y)),$$

where $f^{-1}(y) \subseteq \Omega$ represents the pre-image of y under f

Expected Outcome

- Let $\Omega \subseteq \mathbb{R}$
- The expected outcome (or, the average) of a random variable \mathbb{X} over Ω is defined to be

$$\mathbb{E}[\mathbb{X}] := \sum_{x \in \Omega} \mathbb{P}[\mathbb{X} = x] \cdot x$$

Prove the following result

Theorem (Linearity of Expectation)

Let (\mathbb{X}, \mathbb{Y}) be a joint distribution. Prove that

$$\mathbb{E}[\mathbb{X} + \mathbb{Y}] = \mathbb{E}[\mathbb{X}] + \mathbb{E}[\mathbb{Y}]$$

Summations: Quick and Dirty

Theorem

Let f be an increasing function over $[1, n]$, then the following holds

$$f(1) + \int_1^n f(x) dx \leq \sum_{i=1}^n f(i) \leq \int_1^n f(x) dx + f(n)$$

Proof: Area under the curve.

Think: Bounds on $H_n := \sum_{i=1}^n \frac{1}{i}$

Think: Better bounds for convex upward/downward functions and new approximations