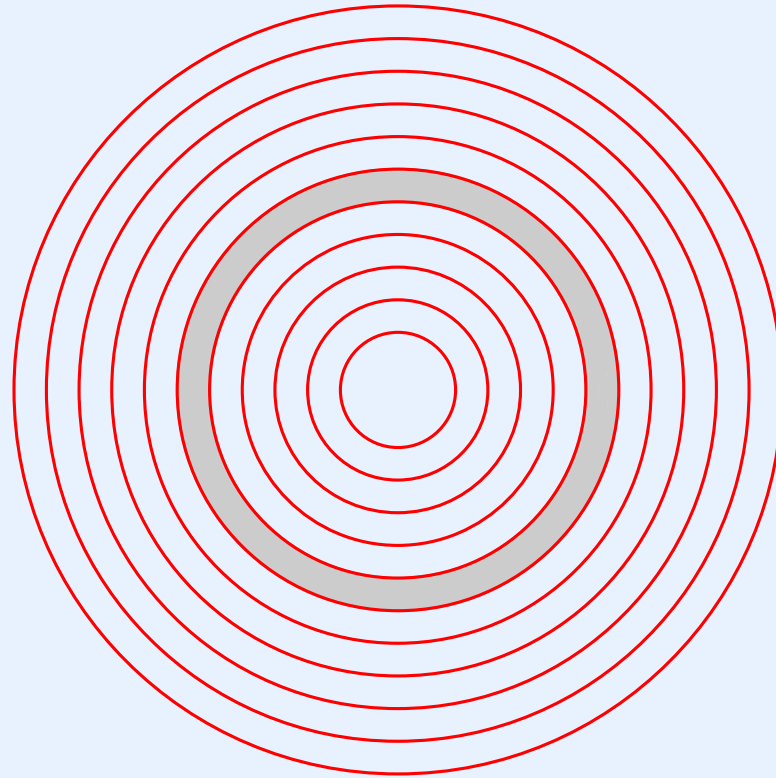


# **PART 9**

## **Clock And Timer Management**

# Location Of Clock Management In The Hierarchy



# Types Of Clocks

- CPU clock
- Time-of-day clock
- Real-time clock
- Interval timer

# CPU Clock

- Controls processor rate
- Often cited as processor speed
- Usually not visible to the OS

# Time-Of-Day Clock

- Autonomous chronometer
- Can be set or read by CPU
- Usually operates independently from processing

# Real-Time Clock

- Pulses regularly
- Rate may not be controllable by CPU
- Interrupts CPU on each pulse
- Does not count pulses
  - Interrupt lost if missed
- Consequence: CPU cannot run more than one clock tick with interrupts disabled or real-time clock is inaccurate
- Note: some real-time clock hardware has counter that records ticks, so OS can learn about missed ticks

# Interval Timer

- Hardware device that operates asynchronously
- Timeout value set by CPU (e.g., time  $T$ )
- Device
  - Interrupts  $T$  time units later
  - Remains disabled after interrupt until reset
- Advanced features available on *some* hardware
  - CPU can poll to find time remaining
  - Timer value can be reset while timer is running

# Use Of Real-Time Clock

- In theory
  - OS may need arbitrary event types
  - Events should occur at exact times (hard real-time constraints)
- In practice
  - Only two basic event types
  - Events occur near specified time (soft real-time constraints)



# Two Principle Event Types

- *Preemption event*
  - Implements timeslicing
  - Guarantees process does not run forever
  - Next preemption event scheduled during context switch
  - Cancellation important
- *Sleep event*
  - Scheduled by a process
  - Delays the process a specified time

# Time-Slicing Trade-Off

- How large should a timeslice be?
- Small granularity
  - More rescheduling overhead
  - Guarantees fairness because processes proceed at approximately equal rate
- Large granularity
  - Less rescheduling overhead
  - Unfair because one process may be far ahead of another

# Timeslicing And Conventional Applications

**Most applications are I/O bound, which means the application is likely to perform an operation that takes the process out of the current state before its timeslice expires.**

# Hardware Pulses And Clock Ticks

- Real-time clock hardware
  - Has fixed *pulse rate*
  - May run off processor clock
  - Rate may not divide a second by power of ten
- Software
  - Written to use *abstract tick rate*
  - May differ from pulse rate
- Clock interrupt handler matches the two rates

# Managing Real-Time Clock Events

- Must be efficient
  - Events examined on each clock interrupt
  - Clock interrupts continuously
  - Should avoid searching a list
- Mechanism
  - Keep events on linked list
  - One item on list for each outstanding event
  - Called *event queue*

# Delta List

- List of timed events
- Ordered by time of occurrence
- For efficiency, store *relative* times
- Key in item stores difference (*delta*) between the time for event and time for previous event
- Key in first event stores time from “now”

## Delta List Example

- Assume events will occur *17*, *27*, *28*, and *32* ticks from now
- Delta keys are *17*, *10*, *1*, and *4*

# Real-Time Clock Processing In Xinu

- Clock interrupt handler
  - Decrements preemption counter
  - Reschedules if timeslice has expired
  - Processes event list
- Clock queue
  - Delta list of delayed processes
  - Each item corresponds to one process
  - Global variable *clockq* specifies head



# Keys On The Xinu Clock Queue

- Processes on *clockq* are ordered by time at which they will awaken
- Each key tells the number of clock ticks that the process must delay beyond the preceding one on the list
- Relationship must be maintained when items are inserted or deleted

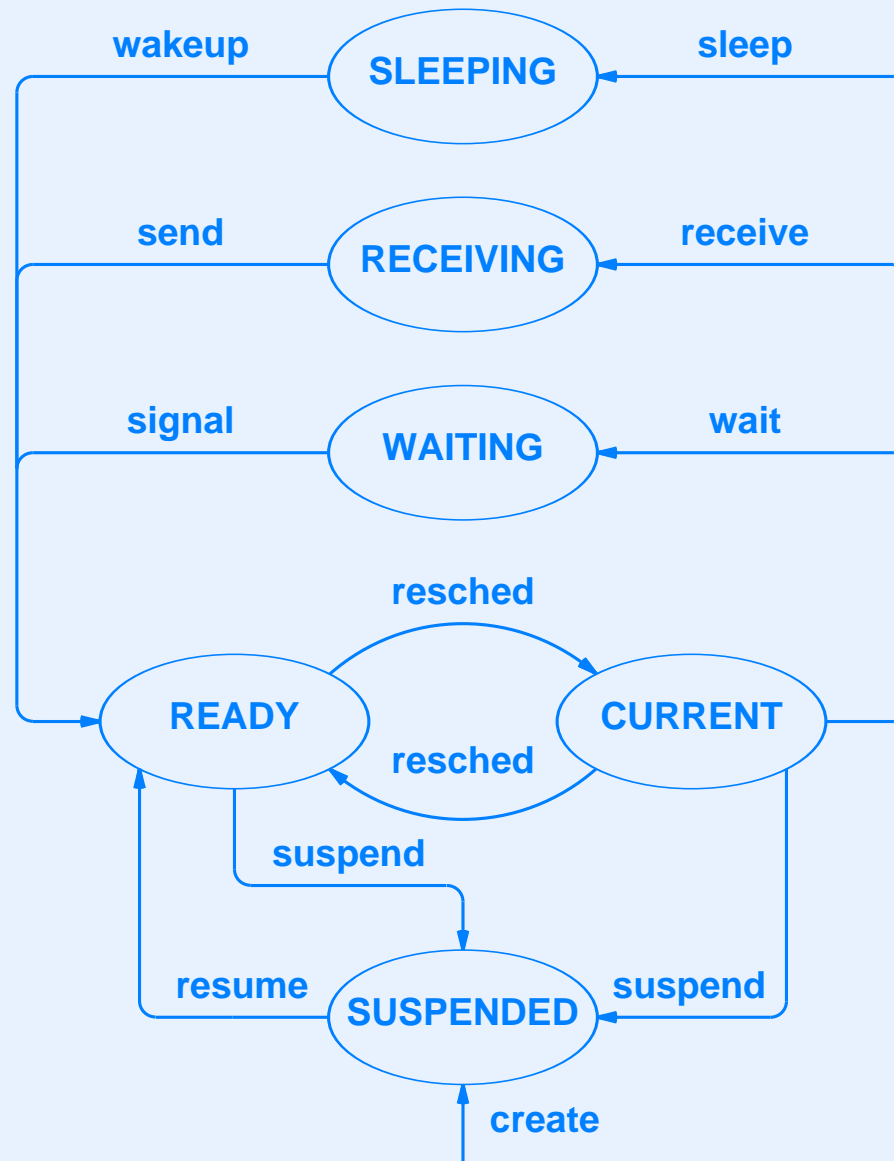
# Real-Time Delay And Clock Resolution

- Process calls *sleep* to delay for a specified time
- Original Xinu hardware used 60 Hz real-time clock
  - Sleep times were measured in seconds
  - Smallest resolution was tenths of seconds
- Modern Xinu system uses high-resolution timer hardware
  - Processes can specify delay in milliseconds
- Question: what resolution should be used for sleep?

# Xinu Sleep Primitives

- Set of primitives accommodates range of possible resolutions
- Sleep specifies delay in seconds
- Sleep10 specifies delay in tenths of seconds
- Sleep100 specifies delay in hundredths of seconds
- Sleep1000 specifies delay in milliseconds
- Given system may not support all primitives

# Process State For Delayed Processes



# Xinu Sleep Function (part 1)

```
/* sleep.c - sleep sleeps */

#include <xinu.h>

#define MAXSECONDS      4294967          /* max seconds per 32-bit msec */

/*-----
 * sleep - Delay the calling process n seconds
 *-----
 */
syscall sleep(
    uint32      delay          /* time to delay in seconds */
)
{
    if (delay > MAXSECONDS) {
        return(SYSERR);
    }
    sleeps(1000*delay);
    return OK;
}
```

## Xinu Sleep Function (part 2)

```
/* sleep.c - sleep sleeps */

#include <xinu.h>

#define MAXSECONDS      4294967          /* max seconds per 32-bit msec */

/*-----
 * sleep - Delay the calling process n seconds
 *-----
 */
syscall sleep(
    uint32      delay          /* time to delay in seconds */
)
{
    if (delay > MAXSECONDS) {
        return(SYSERR);
    }
    sleeps(1000*delay);
    return OK;
}
```

# Inserting An Item On Clockq

- Current process
  - Specifies delay in seconds
- Sleep function
  - Computes delay in milliseconds
  - Inserts current process on *clockq*
  - Calls *resched* to allow other processes to execute
- Method
  - Walk through *clockq* (assumes interrupts disabled)
  - Find place to insert the process
  - Adjust remaining keys as necessary

# Xinu Insertd (part 1)

```
/* insertd.c - insertd */

#include <xinu.h>

/*-----
 * insertd - Insert a process in delta list using delay as the key
 *-----
 */
status insertd(                                /* assumes interrupts disabled */
    pid32      pid,                            /* ID of process to insert */
    qid16      q,                             /* ID of queue to use */
    int32      key                             /* delay from "now" (in ms.) */
)
{
    int      next;                             /* runs through the delta list */
    int      prev;                             /* follows next through the list*/

    if (isbadqid(q) || isbadpid(pid)) {
        return SYSEERR;
    }
}
```



## Xinu Insertd (part 2)

```
prev = queuehead(q);
next = queuetab[queuehead(q)].qnext;
while ((next != queuetail(q)) && (queuetab[next].qkey <= key)) {
    key -= queuetab[next].qkey;
    prev = next;
    next = queuetab[next].qnext;
}

/* insert new node between prev and next nodes */

queuetab[pid].qnext = next;
queuetab[pid].qprev = prev;
queuetab[pid].qkey = key;
queuetab[prev].qnext = pid;
queuetab[next].qprev = pid;
if (next != queuetail(q)) {
    queuetab[next].qkey -= key;
}

return OK;
}
```

# Invariant During Clockq Insertion

**At any time during the search, both *key* and *queuetab[next].qkey* specify a delay relative to the time at which the predecessor of the “next” process awakens.**

# Clock Initialization

- Clock hardware can be optional
- If optional, OS must test for presence of a clock
  - Initialize clock interrupt vector
  - Enable interrupts
  - Loop long enough
  - If interrupt occurs, declare clock present
  - Otherwise, declare no clock present and disable *sleep*

# Clock Interrupt Handler

- Highly optimized (assembly code)
- Decrements preemption counter
  - Calls *resched* if counter reaches zero
- Decrements count of the first element on clock queue
  - Calls *wakeup* if counter reaches zero
- Important notes
  - More than one process may awaken at the same time
  - *Wakeup* must awaken all processes that have zero time remaining before allowing any of them to run

# Xinu Wakeup

```
/* wakeup.c - wakeup */

#include <xinu.h>

/*-----
 * wakeup - Called by clock interrupt handler to awaken processes
 *-----
 */
void wakeup(void)
{
    /* awaken all processes that have no more time to sleep */

    while (nonempty(sleepq) && (firstkey(sleepq) <= 0)) {
        ready(dequeue(sleepq), RESCHED_NO);
    }
    resched();
    return;
}
```

- Rescheduling is deferred until all processes are awakened

# Operation Timeout

- Many operating systems facilities need “timeout” feature
- Especially useful in building communication protocols
- Possible approaches
  - Add timeout feature to each system call (difficult)
  - Provide a single facility for timeout
- Xinu uses latter approach with timed message reception

# Timed Message Reception

- Implemented with *recvtime()*
- Argument specifies maximum delay
- A call to *recvtime()* returns
  - If a message arrives before the specified timeout
  - After the specified timeout if no message has arrived
- Value *TIMEOUT* returned if time expires
- Note: timer is cancelled if message arrives

# Xinu Recvtime (part 1)

```
/* recvtime.c - recvtime */
#include <xinu.h>

/*-----
 *  recvtime  -  wait specified time to receive a message and return
 *-----
 */
umsg32  recvtime(
    int32          maxwait          /* ticks to wait before timeout */
)
{
    intmask mask;                  /* saved interrupt mask          */
    struct procent *prptr; /* table entry of current process*/
    umsg32  msg;                   /* message to return          */

    if (maxwait < 0) {
        return SYSEERR;
    }
    mask = disable();
}
```



## Xinu Recvtime (part 2)

```
/* schedule wakeup and place process in timed-receive state */

prptr = &proctab[currpid];
if (prptr->prhasmsg == FALSE) { /* if message waiting, no delay */
    if (insertd(currpid,sleepq,maxwait) == SYSERR) {
        restore(mask);
        return SYSERR;
    }
    prptr->prstate = PR_RECTIM;
    resched();
}

/* Either message arrived or timer expired */

if (prptr->prhasmsg) {
    msg = prptr->prmsg; /* retrieve message */
    prptr->prhasmsg = FALSE; /* reset message indicator */
} else {
    msg = TIMEOUT;
}
restore(mask);
return msg;
}
```

# Summary

- Computer can contain several types of clocks
  - CPU
  - Time of day
  - Interval timer
  - Real-time
- Real-time clock or interval timer used for
  - Preemption
  - Process delay
- OS may need to convert hardware pulse rate to appropriate tick rate

## Summary (continued)

- List of sleeping processes stored in a delta list
- Only the key of the first item on the list needs to be updated on each clock tick
- Multiple processes may awaken at the same time; rescheduling is deferred until all have been made ready
- *Recvtime* allows a process to wait a specified time for a message to arrive