

Other types of methods for large-scale optimization

Computational Methods in Optimization
CS 520, Purdue

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ALTERNATING OPTIMIZATION

Non-negative matrix factorization

$$\begin{aligned} &\text{minimize} && \| \mathbf{A} - \mathbf{X}\mathbf{Y}^T \| \\ &\text{subject to} && \mathbf{X} \in \mathbb{R}^{m \times k} \geq 0, \mathbf{Y} \in \mathbb{R}^{n \times k} \\ &&& \mathbf{X} \geq 0, \mathbf{Y} \geq 0 \end{aligned}$$

Fix X , solve for Y

Fix Y , solve for X

...

Does it converge?

Block coordinate descent

Gauss-Seidel

Alternating direction

Lots of activity among machine learning,
compressed sensing, sparse 1-norm folks,
too.

Bertsekas, Nonlinear programming

Suppose f is continuous, differentiable

$f = f(x_1, \dots, x_N)$ where x_i is in a convex domain.

“Think of each x_i as a block of variables.”

If

$$\underset{\mathbf{y} \in X_i}{\text{minimize}} f(\mathbf{x}_1, \dots, \mathbf{y}, \dots, \mathbf{x}_N)$$

is uniquely attained, then the sequence of subproblems converges to a stationary point.

Suppose there are just two blocks

[Grippio & Sciandrone]

Then we don't need a unique minimizer any more and we can treat more general convex problems.

STOCHASTIC GRADIENT DESCENT

SGD

Given $f(\mathbf{x}) = \sum_{i=1}^L f_i(\mathbf{x})$.

Note that $\mathbf{g}(\mathbf{x}) = \sum_{i=1}^L \nabla f_i(\mathbf{x})$

Consider $\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} - \alpha \nabla f_{i \sim U}(\mathbf{x})$

Here, $\nabla f_{i \sim U}(\mathbf{x})$ is just a random term in the gradient (“i drawn from uniform U”)

Stochastic Gradient Descent

$$\text{minimize } \|\mathbf{Ax} - \mathbf{b}\|^2$$

$$\text{minimize } \sum_i \left(\sum_j A_{ij} x_j - b_i \right)^2$$

$$\text{minimize } \sum_i \ell_i(\mathbf{x})$$
$$\ell_i(\mathbf{x}) = \left(\sum_j A_{ij} x_j - b_i \right)^2$$

$$\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} - \alpha \mathbf{g}_{\ell_i}(\mathbf{x}^{(k)})$$

Repeatedly
draw i at
random.

$$= \mathbf{x}^{(k)} - \alpha 2 \left(\sum_j A_{ij} x_j - b_i \right) \begin{bmatrix} A_{i,1} \\ \vdots \\ A_{i,n} \end{bmatrix}$$