Let us begin by introducing basic notation for matrices and vectors.

# Matrices

We'll use  $\mathbb R$  to denote the set of real-numbers and  $\mathbb C$  to denote the set of complex numbers.

We write the space of all  $m \times n$  real-valued matrices as  $\mathbb{R}^{m \times n}$ . Each

$$A \in \mathbb{R}^{m \times n}$$
 is  $\begin{bmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{bmatrix}$  where  $A_{i,j} \in \mathbb{R}$ .

Sometimes, I'll write:

$$\begin{bmatrix} a_{1,1} & \cdots & a_{1,n} \\ \vdots & & \vdots \\ a_{m,1} & \cdots & a_{m,n} \end{bmatrix}$$

instead. With only a few exceptions, matrices are written as *bold*, *capital* letters. Sometimes, we'll use a capital greek letter. Matrix elements are written as subscripted, *unbold* letters.

When clear from context,

$$A_{i,j}$$
 is written  $A_{ij}$ 

instead, e.g.  $A_{11}$  instead of  $A_{1,1}$ .

**In class** I'll usually write matrices with just upper-case letters. If you are unsure if something is a matrix or an element, raise your hand and ask, or *quietly* ask a neighbor.

Another notation for  $\boldsymbol{A} \in \mathbb{R}^{m \times n}$  is

$$\boldsymbol{A}:n imes n.$$

Sometimes this is nicer to write on the board.

#### Vectors

We write the set of length-*n* real-valued vectors as  $\mathbb{R}^n$ . Each

$$\mathbf{x} \in \mathbb{R}^n$$
 is  $\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$  where  $x_i \in \mathbb{R}$ .

Vectors are denoted by *lowercase*, *bold* letters. As with matrices, elements are sub-scripted, *unbold* letters. Sometimes, we'll write vector elements as

$$x_i$$
 or  $[x]_i$  or  $x(i)$ .

Usually, this choice is motivated by a particular application. *Throughout the class, vectors are column vectors.* 

**In class** I'll usually write vectors with just lower-case letters and *will try* to follow the convention of underlining them.

#### Scalars

Lower-case greek letters are scalars.

### Quick test

Identify the following:

$$\mathbf{f}, z_1, \mathbf{x}_1, \alpha, \beta, \boldsymbol{C}, \boldsymbol{C}_1, \boldsymbol{\Sigma}, B_{i,j}, \mathbf{b}_{i,j}$$

## Operations

**Transpose** Let  $\boldsymbol{A}: m \times n$ , then

$$\boldsymbol{B}: n \times m = \boldsymbol{A}^T$$
 has  $B_{i,j} = A_{j,i}$ .

Example  $\mathbf{A} = \begin{bmatrix} 2 & 3 \\ 1 & 4 \\ 3 & -1 \end{bmatrix} \quad \mathbf{A}^T = \begin{bmatrix} 2 & 1 & 3 \\ 3 & 4 & -1 \end{bmatrix}$ 

**Hermitian** (Also called conjugate transpose) Let  $A \in \mathbb{C}^{m \times n}$ , then

$$\boldsymbol{B} \in \mathbb{C}^{n \times m} = \boldsymbol{A}^* = \boldsymbol{A}^H$$
 has  $B_{i,j} = \overline{A}_{j,i}$ .

Example  $\mathbf{A} = \begin{bmatrix} 2 & 3 \\ i & 4 \\ 3 & -i \end{bmatrix}$   $\mathbf{A}^* = \begin{bmatrix} 2 & -i & 3 \\ 3 & 4 & i \end{bmatrix}$ 

Addition Let  $\boldsymbol{A}: m \times n$  and  $\boldsymbol{B}: m \times n$ , then

$$C: m \times n = A + B \implies C_{i,j} = A_{i,j} + B_{i,j}$$

Example  $\mathbf{A} = \begin{bmatrix} 2 & 3 \\ 1 & 4 \\ 3 & -1 \end{bmatrix}, \mathbf{B} = \begin{bmatrix} 1 & -1 \\ 2 & 3 \\ -1 & 1 \end{bmatrix} \mathbf{A} + \mathbf{B} = \begin{bmatrix} 3 & -2 \\ 3 & 2 \\ 2 & 0 \end{bmatrix}.$ 

**Scalar Multiplication** Let  $\boldsymbol{A} : m \times n$  and  $\alpha \in \mathbb{R}$ , then

$$C: m \times n = \alpha A + B \implies C_{i,j} = \alpha A_{i,j}.$$

Example  $\mathbf{A} = \begin{bmatrix} 2 & 3 \\ 1 & 4 \\ 3 & -1 \end{bmatrix}$ ,  $5\mathbf{A} = \begin{bmatrix} 10 & 15 \\ 5 & 20 \\ 15 & -5 \end{bmatrix}$ 

Matrix Multiplication Let  $\boldsymbol{A}: m \times n$  and  $\boldsymbol{B}: n \times k$ , then

$$\boldsymbol{C}: m \times k = \boldsymbol{A}\boldsymbol{B} \implies C_{i,j} = \sum_{r=1}^{n} A_{i,r} B_{r,j}.$$

Matrix-vector Multiplication Let  $\mathbf{A} : m \times n$  and  $\mathbf{x} \in \mathbb{R}^n$ , then

$$\mathbf{c} \in \mathbb{R}^m = A\mathbf{x} \implies c_i = \sum_{j=1}^n A_{i,j} x_j.$$

This operation is just a special case of matrix multiplication that follows from treating **x** and **c** as  $n \times 1$  and  $m \times 1$  matrices, respectively.

Vector addition, Scalar vector multiplication These are just special cases of matrix addition and scalar matrix multiplication where vectors are viewed as  $n \times 1$  matrices.

# Partitioning

It is often useful to represent a matrix as a collection of vectors. In this case, we write

$$\boldsymbol{A}:m imes n=\begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix}$$

where each  $\mathbf{a}_j \in \mathbb{R}^m$ . This form corresponds to a partition into columns.

Alternatively, we may wish to partition a matrix into rows.

$$\boldsymbol{A}: m \times n = \begin{bmatrix} \boldsymbol{\mathrm{r}}_1^T \\ \boldsymbol{\mathrm{r}}_2^T \\ \vdots \\ \boldsymbol{\mathrm{r}}_m^T \end{bmatrix}.$$

Here, each  $\mathbf{r}_i \in \mathbb{R}^n$ .

Using the column partitioning:

$$\mathbf{A}\mathbf{x} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \sum_j x_j \mathbf{a}_j.$$

And with the row partitioning:

$$oldsymbol{A} \mathbf{x} = egin{bmatrix} \mathbf{r}_1^T \ \mathbf{r}_2^T \ dots \ \mathbf{r}_m^T \end{bmatrix} \mathbf{x} = egin{bmatrix} \mathbf{r}_1^T \mathbf{x} \ \mathbf{r}_2^T \mathbf{x} \ dots \ \mathbf{r}_m^T \mathbf{x} \end{bmatrix}.$$

Another useful partitioned representation of a matrix is into blocks:

$$oldsymbol{A} = egin{bmatrix} oldsymbol{A}_{1,1} & oldsymbol{A}_{1,2} \ oldsymbol{A}_{2,1} & oldsymbol{A}_{2,2} \end{bmatrix}$$

or

$$m{A} = egin{bmatrix} m{A}_{1,1} & m{A}_{1,2} & m{A}_{1,3} \ m{A}_{2,1} & m{A}_{2,2} & m{A}_{2,3} \ m{A}_{3,1} & m{A}_{3,2} & m{A}_{3,3} \end{bmatrix}.$$

Here, the sizes "just have to work out" in the vernacular. Formally, all  $A_{i,\cdot}$  must have the same number of rows and all  $A_{\cdot,j}$  must have the same number of columns.