	HOMEWORK
PURDUE UNIVERSITY · CS 31400	David F. Gleich
NUMERICAL ANALYSIS	April 30, 2021

Please answer the following questions in complete sentences in a typed manuscript and submit the solution on Gradescope by - April 30th at 5am if you want it graded before the final - May 3rd at noon if you want it graded after the final. (No penalty, just no feedback before the exam.)

Problem 0: Homework checklist

- Please identify anyone, whether or not they are in the class, with whom you discussed your homework. This problem is worth 1 point, but on a multiplicative scale.
- Make sure you have included your source-code and prepared your solution according to the most recent Piazza note on homework submissions.

Problem 1: (Ascher and Greif, Problem 16.5)

Consider the ODE

$$\frac{d\mathbf{y}}{dt} = \mathbf{f}(t, \mathbf{y}), 0 \le t \le b$$

with $b \gg 1$.

1. Apply the stretching transformation $t = \tau b$ to obtain the equivalent ODE

$$\frac{d\mathbf{z}}{d\tau} = b\mathbf{f}(\tau b, \mathbf{z}), 0 \le \tau \le 1.$$

And show the relationship between $\mathbf{y}(t)$ and $\mathbf{z}(\tau)$.

2. Show that applying the forward Euler method to the ODE for \mathbf{y} in t with step size h_t is equivalent to applying the same method to the ODE for \mathbf{z} in τ with step size h_{τ} that satisfies $h_t = bh_{\tau}$.

Problem 2: (Ascher and Greif, Example 16.20)

Consider the following system that describes the behavior of two masses in the presence of a third mass of (small) size. The masses are $\mu = 0.012277471$ and $\hat{\mu} = 1 - \mu$ (earth and sun):

$$u_1'' = u_1 + 2u_2' - \hat{\mu} \frac{u_1 + \mu}{D_1} - \mu \frac{u_1 - \hat{\mu}}{D_2},$$

$$u_2'' = u_2 - 2u_1' - \hat{\mu} \frac{u_2}{D_1} - \mu \frac{u_2}{D_2},$$

$$D_1 = ((u_1 + \mu)^2 + u_2^2)^{3/2},$$

$$D_2 = ((u_1 - \hat{\mu})^2 + u_2^2)^{3/2}.$$

The initial conditions are

$$u_1(0) = 0.994, u_2(0) = 0,$$

$$u_1'(0) = 0, u_2'(0) = -2.00158510637908252240537862224.$$

Let T = 17.1.

1. Implement a 4th order RK method for this problem.

- 2. Show what happens for 1000, 5000 and 10000, 50000, 100000 steps. Discuss any interesting observations.
- 3. Use a standard integration software package such as ode45 or one of the Julia ODE packages or an equivalent tool to study this problem.

Problem 3: (Gautschi Machine Exercise 5.5)

Newton's equations for the motion of a particle on a planar orbit (with eccentricity ε , $0 < \varepsilon < 1$) are

$$\begin{aligned} x'' &= -\frac{x}{r^3}, x(0) = 1 - \varepsilon, x'(0) = 0, \\ y'' &= -\frac{y}{r^3}, y(0) = 0, y'(0) = \sqrt{\frac{1 + \varepsilon}{1 - \varepsilon}}, \\ r^2 &= x^2 + y^2, \\ 0 &\le t \le 1. \end{aligned}$$

1. Verify that the solution can be written in the form of

$$\begin{split} x(t) &= \cos u(t) - \varepsilon, \\ y(t) &= \sqrt{1 - \varepsilon^2} \sin u(t), \\ u(t) - \varepsilon \sin u(t) - t = 0. \end{split}$$

- 2. Write a program to solve the nonlinear equation at each step using Newton's method and plot the exact solution for $\varepsilon = 0.3, 0.5, 0.7$.
- 3. Write a forward and backwards Euler solver for this problem.
- 4. Evaluate the error with N = 50, 120, 200, 500, and 1000 time-steps using the same values of ε .

Problem 4: Raptors redux

Recall the Raptor problem from the midterm.

```
function simulate_raptors(angle)
    vhuman=6.0
    vraptor0=10.0 # the slow raptor velocity in m/s
    vraptor=15.0 #
    raptor_distance = 20.0
    raptor_min_distance = 0.2 # a raptor within 20 cm can attack
    tmax=10.0 # the maximum time in seconds
    nsteps=1000
    # initial positions
    h = [0.0, 0.0]
    r0 = [1.0, 0.0] * raptor_distance
    r1 = [-0.5, sqrt(3.)/2.] * raptor_distance
    r2 = [-0.5, -sqrt(3.)/2.] * raptor_distance
    # how much time el
    dt = tmax/nsteps
    t = 0.0
    hhist = zeros(2,nsteps+1)
    rOhist = zeros(2,nsteps+1)
```

```
r1hist = zeros(2,nsteps+2)
r2hist = zeros(2,nsteps+2)
hhist[:,1] = h
r0hist[:,1] = r0
r1hist[:,1] = r1
r2hist[:,1] = r2
tend = tmax
.....
This function will compute the derivatives of the
positions of the human and the raptors
.....
function compute_derivatives(angle,h,r0,r1,r2)
    dh = [cos(angle), sin(angle)] * vhuman
    dr0 = (h-r0)/norm(h-r0)*vraptor0
    dr1 = (h-r1)/norm(h-r1)*vraptor
    dr2 = (h-r2)/norm(h-r2)*vraptor
    return dh, dr0, dr1, dr2
end
for i=1:nsteps
    dh, dr0, dr1, dr2 = compute_derivatives(angle,h,r0,r1,r2)
    h += dh*dt
    r0 += dr0*dt
    r1 += dr1*dt
    r2 += dr2*dt
    t += dt
    hhist[:,i+1] = h
    rOhist[:,i+1] = rO
    r1hist[:,i+1] = r1
    r2hist[:,i+1] = r2
    if norm(r0-h) <= raptor min distance ||
        norm(r1-h) <= raptor_min_distance ||</pre>
        norm(r2-h) <= raptor_min_distance</pre>
        # truncate the history
        hhist = hhist[:,1:i+1]
        r0hist = r0hist[:,1:i+1]
        r1hist = r1hist[:,1:i+1]
        r2hist = r2hist[:,1:i+1]
        tend = t
        break
    end
end
return tend
```

end

- 1. Modify this code to use Heun's method instead of forward Euler and comment on how the results change with angle.
- 2. Not assigned in the end (Tentative, not currently assigned.) Something using Backward Euler. This involves solving the nonlinear system which is more like the previous problem.