

In this class:

- *What you need to know about iterative methods for your homework. (We'll*
- *How we can use QR to solve a least squares problem.*
- *How any computation can be wrong on a computer: ill-conditioned problems and unstable algorithms.*

October 12, 2016

## **Finish up Least Squares Iterative & Conditioning**

*Next class*

More Conditioning & Iterative methods!  
G&C – Chapter 7.4, Chapter 12.2

*Next next class*

Eigenvalues  
G&C – Chapter 12.1

# How to solve $Ax=b$ another way.

When  $A$  is super-large (1 million-by-1 million) then using GE and LU often don't work.

*But these large matrices are often very special (see handout).*

- They are **sparse**, which means they have many zeros and computing  $y = Ax$  is fast and easy
- They are **structured**, which means computing  $y = Ax$  is fast

Think about the matrices we saw for resizing images on the homework. ( $32 \times 32 \rightarrow 16 \times 16$ ) there were tons of zeros!

# The key ideas (1)

If we have a big matrix, but we also have a *program* to compute  $y = Ax$  (**matvec**) then we can still solve  **$Ax = b$** !

- We can check a potential solution  $y$  via the quantity  $r = b - Ay$  (matvec and subtract) and  $\|r\|$
- $r$  is called the **residual** and
- $\|r\| / \|b\|$  is the **relative residual**

If relative residual is small ( $10^{-8}$ ), then we have a *good enough* solution,

=> **so we can tell when to stop**

# The key ideas (2)

If we have a big matrix, but we also have a *program* to compute  $y = Ax$  (**matvec**) then we can still solve  $Ax = b$ !

- There are a variety of ways to turn  $x = A^{-1} b$  into a sequence of matvecs.
- The easiest is

$$\mathbf{A}^{-1} \mathbf{b} = \mathbf{b} + (\mathbf{I} - \mathbf{A})\mathbf{b} + (\mathbf{I} - \mathbf{A})^2 \mathbf{b} + (\mathbf{I} - \mathbf{A})^3 \mathbf{b} + \dots$$

which doesn't always work, but will for our cases.

- Evaluating  $k$  terms here only involves matvecs with  $A$ !

# The overall idea

If we have a big matrix, but we also have a *program* to compute  $y = Ax$  (**matvec**) then we can still solve  $Ax = b$ !

- Use

$$\mathbf{A}^{-1} \mathbf{b} = \mathbf{b} + (\mathbf{I} - \mathbf{A})\mathbf{b} + (\mathbf{I} - \mathbf{A})^2\mathbf{b} + (\mathbf{I} - \mathbf{A})^3\mathbf{b} + \dots$$

- Evaluate  $k$  terms, check relative residual.
- If not small enough, evaluate the next term and repeat.

This is an *iteration* and hence *iterative methods*

# The overall idea simplified

We'll work through this in class, but this idea is actually super simple once you work out the a few other facts.

```
function richardson(A,b;tol=10-8,niter=10000,omega=1.)  
x = b  
normb = norm(b)  
for k=1:niter  
    r = b - A*x  
    if norm(r)/norm(b) <= tol, break, end  
    x = x + omega*r  
end  
return x
```