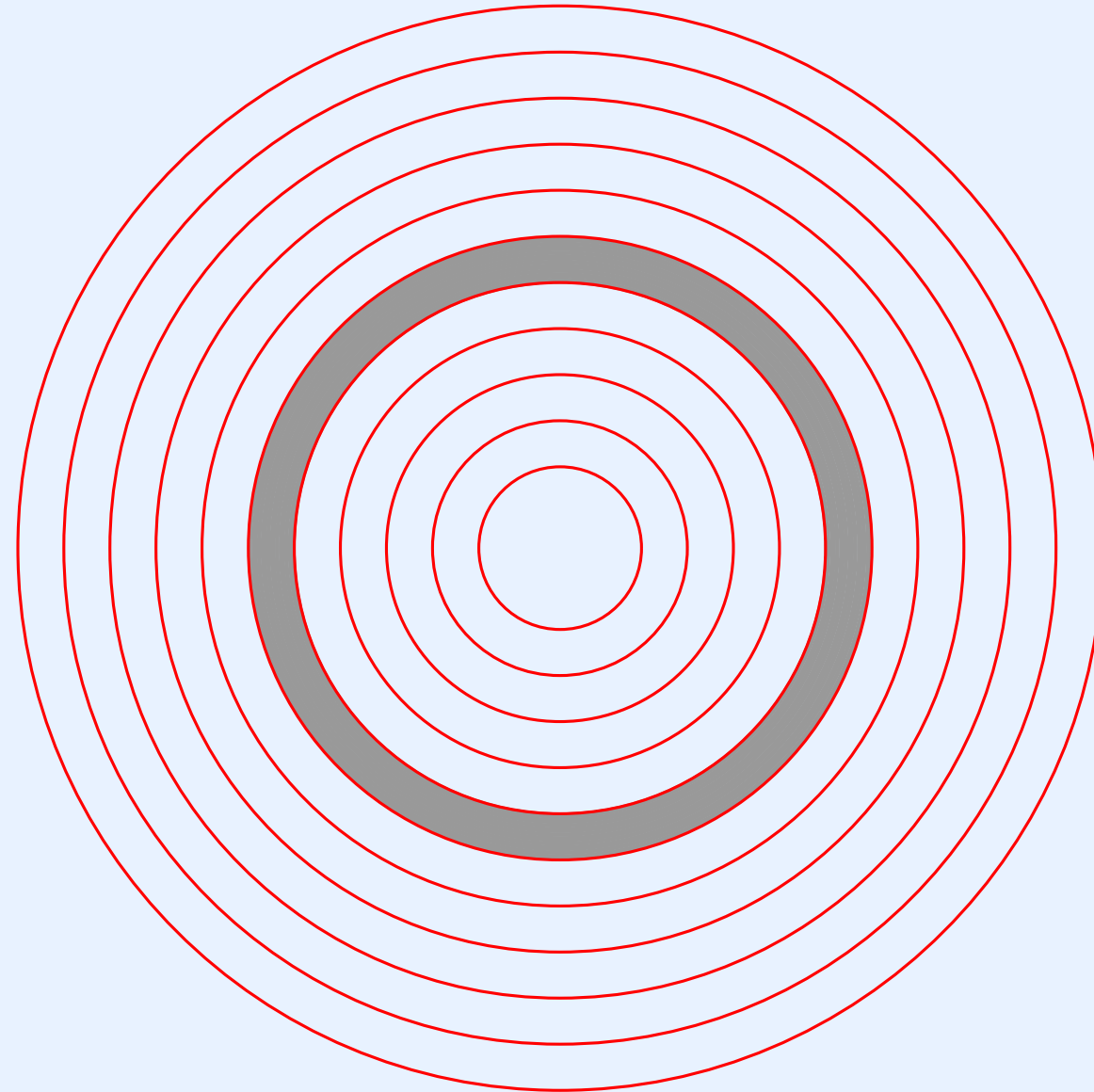


Module XIII

Real-Time Clock Management And Timed Events

Location Of Clock Management In The Hierarchy



Various Types Of Clock Hardware Exist

- Processor clock (rate at which instructions execute)
- Real-time clock
 - Pulses regularly
 - Interrupts the processor on each pulse
 - Called *programmable* if rate can be controlled by OS
- Interval timer
 - The processor sets a timeout and the device interrupts after the specified time
 - Can be used to pulse regularly
 - May have an automatic restart capability

Timed Events

- Two types of timed events are important to an operating system
- A *preemption event*
 - Known as *timeslicing*
 - Guarantees that a given process cannot run forever
 - Switches the processor to another process
- A *sleep event*
 - Is requested by a process to delay for a specified time
 - The process resumes execution after the time passes

A Note About Timeslicing

Most applications are I/O bound, which means the application is likely to perform an operation that takes the process out of the current state before its timeslice expires.

Managing Timed Events

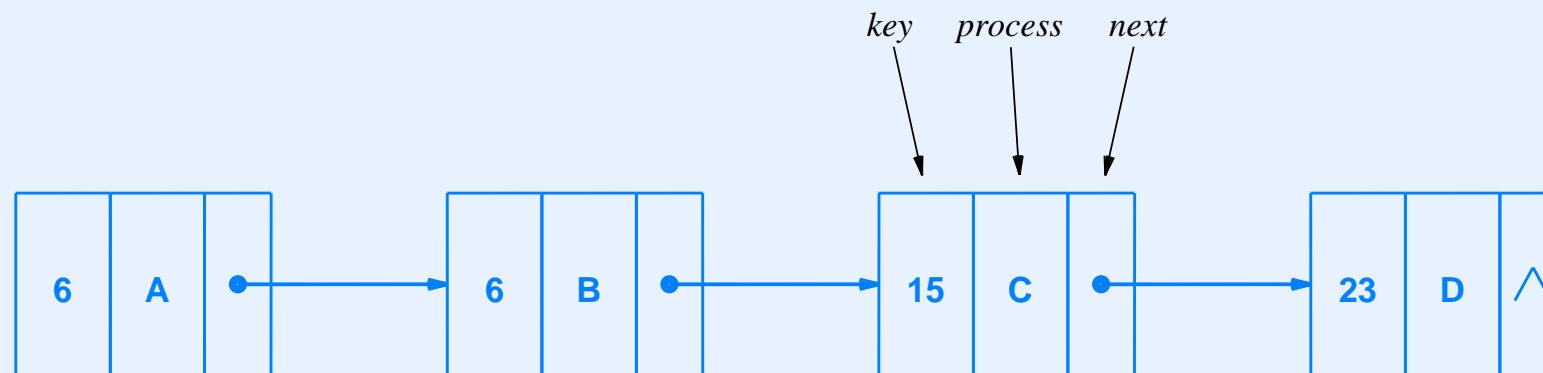
- The code must be efficient because
 - Clock interrupts occur frequently and continuously
 - More than one event may occur at a given time
 - The clock interrupt code must avoid searching a list of pending events
- An efficient mechanism
 - Keep all timed events on a list
 - Call the list an *event queue*

The Delta List

- A data structure used for timed events
- Items on a delta list are ordered by the time they will occur
- Trick to make processing efficient: use *relative* times
- Implementation: the key in an item stores the difference (*delta*) between the time for the event and time for the previous event
- The key in first event stores the delta from “now”

Delta List Example

- Assume events for processes *A* through *D* will occur 6, 12, 27, and 50 ticks from now
- The delta keys are 6, 6, 15, and 23



Real-time Clock Processing In Xinu

- The clock interrupt handler
 - Decrements the preemption counter and calls *resched* if the timeslice has expired
 - Processes the sleep queue
- The sleep queue
 - Is a delta list
 - Each item on the list is a sleeping process
- Global variable *sleepq* contains the ID of the sleep queue

Keys On The Xinu Sleep Queue

- Processes on *sleepq* are ordered by time at which they will awaken
- Each key tells the number of clock ticks that the process must delay beyond the preceding one on the list
- The relationship must be maintained whenever an item is inserted or deleted

Sleep Timer Resolution

- A process calls *sleep* to delay
- Question: what resolution should be used for sleep?
 - Humans typically think of delays in seconds or minutes
 - Some applications may need millisecond accuracy (or more, if available)
- The tradeoff: using a high resolution, such as microseconds, means long delays will overflow a 32-bit integer

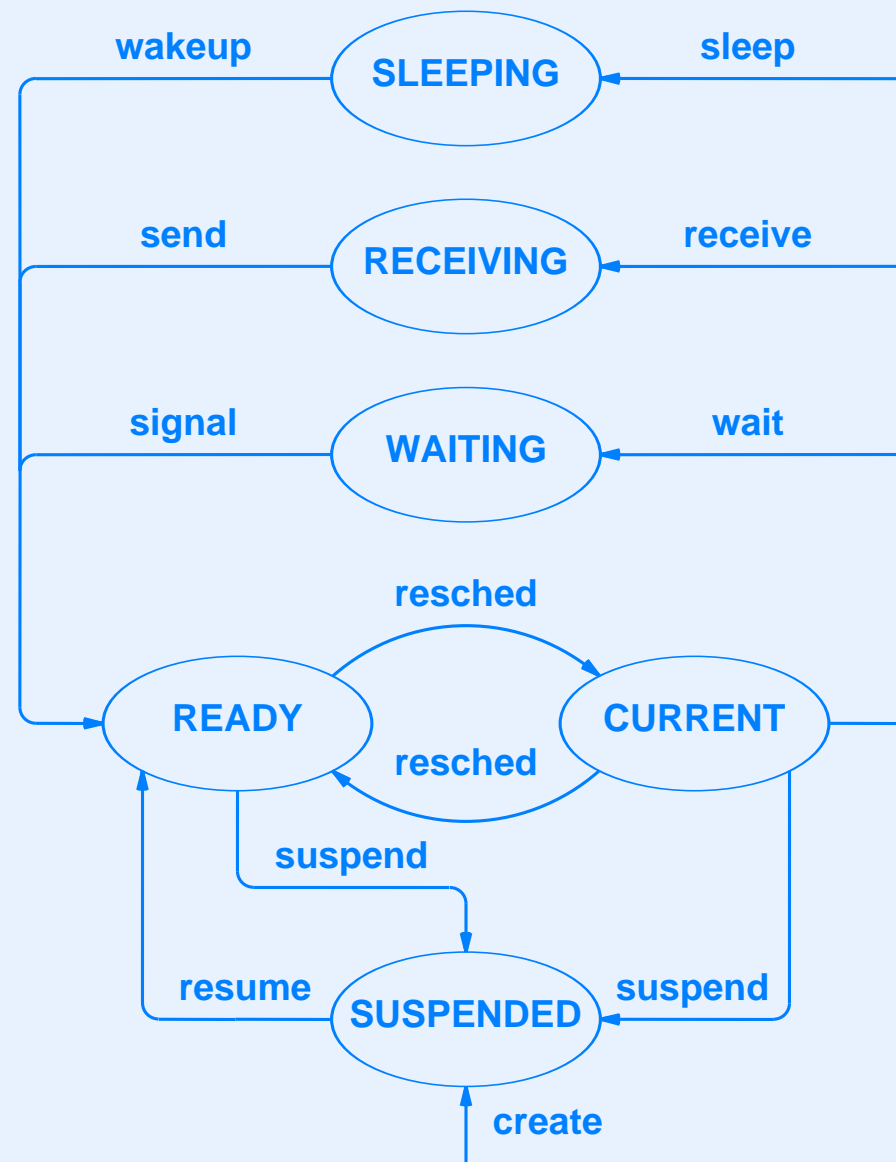
Xinu Sleep Primitives

- Xinu offers a set of functions to accommodate a range of possible resolutions
 - sleep – the delay is given in seconds
 - sleep10 – the delay is given in tenths of seconds
 - sleep100 – the delay is given in hundredths of seconds
 - sleepms – the delay is given in milliseconds
- The smallest resolution is milliseconds because the clock operates at a rate of one millisecond per tick

A New Process State For Sleeping Processes

- A sleeping process is not ready, suspended, or waiting
- A new state is required
 - The process enters the sleeping state by calling a sleep function
 - The clock interrupt handler calls *wakeup* when the delay expires

A New Process State For Sleeping Processes (continued)



Sleep.c (sleep and sleepms) (Part 1)

```
/* sleep.c - sleep sleepms */

#include <xinu.h>

#define MAXSECONDS      2147483          /* Max seconds per 32-bit msec */

/*-----
 *  sleep  -  Delay the calling process n seconds
 *-----
 */
syscall sleep(
    int32 delay          /* Time to delay in seconds */
)
{
    if ( (delay < 0) || (delay > MAXSECONDS) ) {
        return SYSERR;
    }
    return sleepms(1000*delay);
}
```

Sleep.c (sleep and sleepms) (Part 2)

```
/*-----
 * sleepms - Delay the calling process n milliseconds
 *-----
 */
syscall sleepms(
    int32 delay          /* Time to delay in msec.          */
)
{
    intmask mask;        /* Saved interrupt mask          */

    if (delay < 0) {
        return SYSERR;
    }

    if (delay == 0) {
        yield();
        return OK;
    }
}
```


Sleep.c (sleep and sleepms) (Part 3)

```
/* Delay calling process */

mask = disable();
if (insertd(currpid, sleepq, delay) == SYSERR) {
    restore(mask);
    return SYSERR;
}

proctab[currpid].prstate = PR_SLEEP;
resched();
restore(mask);
return OK;
}
```

Inserting An Item On Sleepq

- The current process calls *sleepms* or *sleep* to request a delay
- *Sleepms*
 - The underlying function that takes action
 - Inserts current process on *sleepq*
 - Calls *resched* to allow other processes to execute
- Method
 - Walk through *sleepq* (with interrupts disabled)
 - Find the place to insert the process
 - Adjust remaining keys as necessary

Invariant For Insertion On sleepq

- The key of the first process on a delta list specifies the number of clock ticks a process must delay beyond the current time
- The key of each other process on a delta list specifies the number of clock ticks the process must delay beyond the preceding process on the list.
- When inserting a new delay on the list, the code adheres to the following invariant:

At any time during the search, both key and queuetab[next].qkey specify a delay relative to the time at which the predecessor of the “next” process awakens.

Xinu Insertd (Part 1)

```
/* insertd.c - insertd */

#include <xinu.h>

/*-----
 * insertd - Insert a process in delta list using delay as the key
 *-----
 */
status insertd(                /* Assumes interrupts disabled */
    pid32          pid,        /* ID of process to insert */
    qid16          q,          /* ID of queue to use */
    int32          key         /* Delay from "now" (in ms.) */
)
{
    int32  next;                /* Runs through the delta list */
    int32  prev;                /* Follows next through the list*/

    if (isbadqid(q) || isbadpid(pid)) {
        return SYSERR;
    }
}
```

Xinu Insertd (Part 2)

```
prev = queuehead(q);
next = queuestab[queuehead(q)].qnext;
while ((next != queuestab[q]) && (queuestab[next].qkey <= key)) {
    key -= queuestab[next].qkey;
    prev = next;
    next = queuestab[next].qnext;
}

/* Insert new node between prev and next nodes */

queuestab[pid].qnext = next;
queuestab[pid].qprev = prev;
queuestab[pid].qkey = key;
queuestab[prev].qnext = pid;
queuestab[next].qprev = pid;
if (next != queuestab[q]) {
    queuestab[next].qkey -= key;
}

return OK;
}
```

A Clock Interrupt Handler

- Updates the time-of-day (which counts seconds)
- Handles sleeping processes
 - Decrements the key of the first process on the sleep queue
 - Calls *wakeup* if the counter reaches zero
- Handles preemption
 - Decrements the preemption counter
 - Calls *resched* if the counter reaches zero

A Clock Interrupt Handler

(continued)

- When sleeping processes awaken
 - More than one process may awaken at a given time
 - The processes may not have the same priority
 - If the clock interrupt handler starts a process running immediately, a higher priority process may remain on the sleep queue, even if its time has expired
- Solution: *wakeup* awakens *all* processes that have zero time remaining before allowing any of them to run

Xinu Wakeup

```
/* wakeup.c - wakeup */

#include <xinu.h>

/*-----
 * wakeup - Called by clock interrupt handler to awaken processes
 *-----
 */
void wakeup(void)
{
    /* Awaken all processes that have no more time to sleep */

    resched_cntl(DEFER_START);
    while (nonempty(sleepq) && (firstkey(sleepq) <= 0)) {
        ready(dequeue(sleepq));
    }

    resched_cntl(DEFER_STOP);
    return;
}
```

- Note that rescheduling is deferred until all processes are awakened

Timed Message Reception

- Many operating system components offer a “timeout” on operations
- Timeout is especially useful in building communication protocols
- A Xinu example: receive with timeout
 - Operates like *receive*, but includes a timeout argument
 - If a message arrives before the timer expires, the message is returned
 - If the timer expires before a message arrives, the value *TIMEOUT* is returned
 - Implemented with *recvtime*
- Recvtime uses the same queue and wakeup mechanism as sleeping processes

Xinu Recvtime (Part 1)

```
/* recvtime.c - recvtime */

#include <xinu.h>

/*-----
 *  recvtime  -  Wait specified time to receive a message and return
 *-----
 */
umsg32  recvtime(
        int32          maxwait          /* Ticks to wait before timeout */
)
{
    intmask mask;          /* Saved interrupt mask */
    struct procent *prptr; /* Tbl entry of current process */
    umsg32  msg;           /* Message to return */

    if (maxwait < 0) {
        return SYSERR;
    }
    mask = disable();
```

Xinu Recvtime (Part 2)

```
/* Schedule wakeup and place process in timed-receive state */

prptr = &proctab[currpid];
if (prptr->prhasmsg == FALSE) { /* Delay if no message waiting */
    if (insertd(currpid,sleepq,maxwait) == SYSERR) {
        restore(mask);
        return SYSERR;
    }
    prptr->prstate = PR_RECTIM;
    resched();
}

/* Either message arrived or timer expired */

if (prptr->prhasmsg) {
    msg = prptr->prmsg; /* Retrieve message */
    prptr->prhasmsg = FALSE; /* Reset message indicator */
} else {
    msg = TIMEOUT;
}
restore(mask);
return msg;
}
```

When A Process Sends A Message

- The target process could be in
 - The receiving state, PR_RECV
 - The receive-with-timeout state, PR_RECTIM
- A call to *send* handles both cases

Look Again At Send.c (Part 1)

```
/* send.c - send */

#include <xinu.h>

/*-----
 * send - Pass a message to a process and start recipient if waiting
 *-----
 */
syscall send(
    pid32      pid,      /* ID of recipient process */
    umsg32     msg,      /* Contents of message */
)
{
    intmask mask;        /* Saved interrupt mask */
    struct procent *prptr; /* Ptr to process's table entry */

    mask = disable();
    if (isbadpid(pid)) {
        restore(mask);
        return SYSERR;
    }
}
```

Look Again At Send.c (Part 2)

```
prptr->prmsg = msg;                /* Deliver message */
prptr->prhasmsg = TRUE;             /* Indicate message is waiting */

/* If recipient waiting or in timed-wait make it ready */

if (prptr->prstate == PR_RECV) {
    ready(pid);
} else if (prptr->prstate == PR_RECTIM) {
    unsleep(pid);
    ready(pid);
}
restore(mask);                     /* Restore interrupts */
return OK;
}
```

Unsleep - Remove A Sleeping Process (Part 1)

```
/* unsleep.c - unsleep */

#include <xinu.h>

/*-----
 *  unsleep  -  Internal function to remove a process from the sleep
 *              queue prematurely.  The caller must adjust the delay
 *              of successive processes.
 *-----
 */
status  unsleep(
        pid32      pid          /* ID of process to remove */
)
{
    intmask mask;                /* Saved interrupt mask */
    struct procent *prptr;       /* Ptr to process's table entry */

    pid32  pidnext;              /* ID of process on sleep queue */
                                /* that follows the process */
                                /* which is being removed */

    mask = disable();
```

Unsleep - Remove A Sleeping Process (Part 2)

```
if (isbadpid(pid)) {
    restore(mask);
    return SYSERR;
}

/* Verify that candidate process is on the sleep queue */

prptr = &proctab[pid];
if ((prptr->prstate!=PR_SLEEP) && (prptr->prstate!=PR_RECTIM)) {
    restore(mask);
    return SYSERR;
}

/* Increment delay of next process if such a process exists */

pidnext = queuestab[pid].qnext;
if (pidnext < NPROC) {
    queuestab[pidnext].qkey += queuestab[pid].qkey;
}

getitem(pid);                                /* Unlink process from queue */
restore(mask);
return OK;
}
```


The Clock Hardware Interface

- The clock interface follows the pattern used by all devices
- The system uses a memory-mapped interaction
 - Some high bus addresses correspond to the clock device, not memory
 - When the processor stores data to one of the special addresses, the data being stored goes to the clock device
 - When the processor fetches from the special addresses, the clock device answers the request and sends information to the processor
 - Typically, the processor sends commands to a device
- A device driver defines a structure that specifies the layout of special addresses and their meaning as well as constants used (usually called *control and status registers*)

ARM Clock Definitions (Part 1)

```
/* clock.h */
```

```
extern uint32 clktime;          /* current time in secs since boot */
extern uint32 count1000;       /* ms since last clock tick */

extern qid16 sleepq;           /* queue for sleeping processes */
extern int32 slnonempty;       /* nonzero if sleepq is nonempty */
extern int32 *sltop;           /* ptr to key in first item on sleepq */
extern uint32 preempt;         /* preemption counter */

struct am335x_timer1ms {
    uint32 tidr;                /* Identification register */
    uint32 res1[3];             /* Reserved */
    uint32 tiocp_cfg;           /* OCP Interface register */
    uint32 tistat;              /* Status register */
    uint32 tistr;               /* Interrupt status register */
    uint32 tier;                 /* Interrupt enable register */
    uint32 twer;                 /* Wakeup enable register */
    uint32 tclr;                /* Optional features */
    uint32 tcrr;                /* Internal counter value */
    uint32 tlldr;               /* Timer load value */
    uint32 ttgr;                /* Trigger register */
    uint32 twps;                /* Write posting register */
    uint32 tmar;                /* Match register */
}
```

ARM Clock Definitions (Part 2)

```
uint32  tcar1;          /* Capture register 1          */
uint32  tsicr;          /* Synchronous interface control*/
uint32  tcar2;          /* Capture register 2          */
uint32  tpir;           /* Positive increment register  */
uint32  tnir;           /* Negative increment register  */
uint32  tcvr;           /* lms control register         */
uint32  tocr;           /* Overflow mask register       */
uint32  towr;           /* no. of overflows            */
};

#define AM335X_TIMER1MS_ADDR 0x44E31000
#define AM335X_TIMER1MS_IRQ 67

#define AM335X_TIMER1MS_TIOCP_CFG_SOFTRESET 0x00000002
#define AM335X_TIMER1MS_TISTAT_RESETDONE 0x00000001

#define AM335X_TIMER1MS_TISR_MAT_IT_FLAG 0x00000001
#define AM335X_TIMER1MS_TISR_OVF_IT_FLAG 0x00000002
#define AM335X_TIMER1MS_TISR_TCAR_IT_FLAG 0x00000004

#define AM335X_TIMER1MS_TIER_MAT_IT_ENA 0x00000001
#define AM335X_TIMER1MS_TIER_OVF_IT_ENA 0x00000002
#define AM335X_TIMER1MS_TIER_TCAR_IT_ENA 0x00000004
```

ARM Clock Definitions (Part 3)

```
#define AM335X_TIMER1MS_TCLR_ST      0x00000001
#define AM335X_TIMER1MS_TCLR_AR      0x00000002

#define AM335X_TIMER1MS_CLKCTRL_ADDR 0x44E004C4
#define AM335X_TIMER1MS_CLKCTRL_EN   0x00000002
```

Clock Interrupt Handler Code (Part 1)

```
/* clkhandler.c - clkhandler */

#include <xinu.h>

/*-----
 * clkhandler - high level clock interrupt handler
 *-----
 */
void clkhandler()
{

    volatile struct am335x_timer1ms *csrptr =
        (struct am335x_timer1ms *)0x44E31000;
        /* Set csrptr to address of timer CSR */

    /* If there is no interrupt, return */

    if((csrptr->tisr & AM335X_TIMER1MS_TISR_OVF_IT_FLAG) == 0) {
        return;
    }
}
```

Clock Interrupt Handler Code (Part 2)

```
/* Acknowledge the interrupt */  
  
csrptr->tisr = AM335X_TIMER1MS_TISR_OVF_IT_FLAG;  
  
/* Increment 1000ms counter */  
  
count1000++;  
  
/* After 1 sec, increment clktime */  
  
if(count1000 >= 1000) {  
    clktime++;  
    count1000 = 0;  
}
```

Clock Interrupt Handler Code (Part 3)

```
/* check if sleep queue is empty */

if(!isempty(sleepq)) {

    /* sleepq nonempty, decrement the key of */
    /* topmost process on sleepq             */

    if((--queuetab[firstid(sleepq)].qkey) == 0) {

        wakeup();
    }
}

/* Decrement the preemption counter */
/* Reschedule if necessary           */

if((--preempt) == 0) {
    preempt = QUANTUM;
    resched();
}
}
```

Clock Initialization (Part 1)

```
/* clkinit.c - clkinit (BeagleBone Black) */

#include <xinu.h>

uint32  clktime;           /* Seconds since boot          */
uint32  count1000;        /* ms since last clock tick   */
qid16   sleepq;           /* Queue of sleeping processes */
uint32  preempt;          /* Preemption counter          */

/*-----
 * clkinit - Initialize the clock and sleep queue at startup
 *-----
 */
void    clkinit(void)
{
    volatile struct am335x_timer1ms *csrptr =
        (volatile struct am335x_timer1ms *)AM335X_TIMER1MS_ADDR;
        /* Pointer to timer CSR in BBoneBlack */
    volatile uint32 *clkctrl =
        (volatile uint32 *)AM335X_TIMER1MS_CLKCTRL_ADDR;

    *clkctrl = AM335X_TIMER1MS_CLKCTRL_EN;
    while((*clkctrl) != 0x2) /* Do nothing */ ;
}
```


Clock Initialization (Part 2)

```
/* Reset the timer module */

csrptr->tiocp_cfg |= AM335X_TIMER1MS_TIOCP_CFG_SOFTRESET;

/* Wait until the reset is complete */

while((csrptr->tistat & AM335X_TIMER1MS_TISTAT_RESETDONE) == 0)
    /* Do nothing */ ;

/* Set interrupt vector for clock to invoke clkint */

set_evec(AM335X_TIMER1MS_IRQ, (uint32)clkhandler);

sleepq = newqueue();      /* Allocate a queue to hold the delta    */
                          /* list of sleeping processes          */

preempt = QUANTUM;        /* Set the preemption time      */

clktime = 0;              /* Start counting seconds       */
count1000 = 0;
/* The following values are calculated for a          */
/* timer that generates 1ms tick rate                 */

csrptr->tpir = 1000000;
csrptr->tnir = 0;
csrptr->tldr = 0xFFFFFFFF - 26000;
```

Clock Initialization (Part 3)

```
/* Set the timer to auto reload */  
  
csrptr->tclr = AM335X_TIMER1MS_TCLR_AR;  
  
/* Start the timer */  
  
csrptr->tclr |= AM335X_TIMER1MS_TCLR_ST;  
  
/* Enable overflow interrupt which will generate */  
/*   an interrupt every 1 ms                      */  
  
csrptr->tier = AM335X_TIMER1MS_TIER_OVF_IT_ENA;  
  
/* Kickstart the timer */  
  
csrptr->ttgr = 1;  
  
return;  
}
```

Notes About Device Hardware Interfaces

- Hardware is incredibly low level
- The interface to a hardware device is tedious
- Hardware defines
 - Many registers that each have some special meaning
 - Special constants that must be used
- A programmer must deal with
 - Silly details
 - A lack of concepts and principles
 - Multiple commands to perform a simple task

Summary

- Two types of timed events are especially important in an operating system
 - Preemption
 - Process delay (sleep)
- A delta list provides an elegant and efficient data structure to store a set of sleeping processes
- If multiple processes awaken at the same time, rescheduling must be deferred until all have been made ready
- *Recvtime* allows a process to specify a maximum time to wait for a message to arrive



Questions?