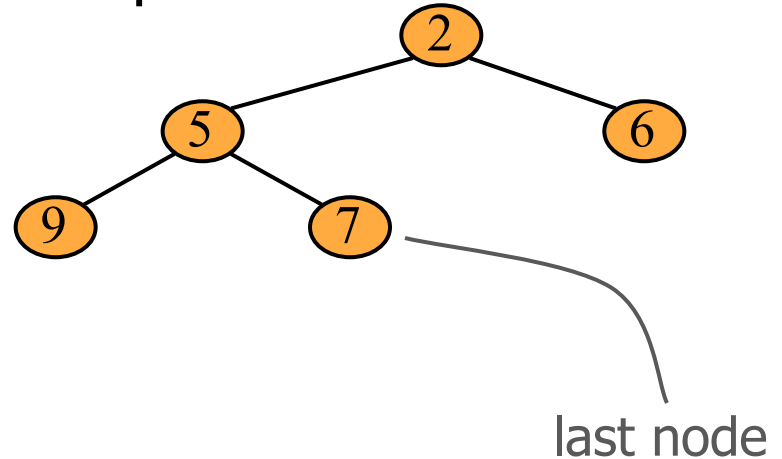


# Heaps

- A heap is a binary tree storing keys at its nodes and satisfying the following properties:
  - Heap-Order: for every internal node  $v$  other than the root,  $key(v) \geq key(parent(v))$
  - Complete Binary Tree: let  $h$  be the height of the heap
    - for  $i = 0, \dots, h - 1$ , there are  $2^i$  nodes of depth  $i$
    - at depth  $h - 1$ , the internal nodes are to the left of the external nodes

- The last node of a heap is the rightmost node of depth  $h$



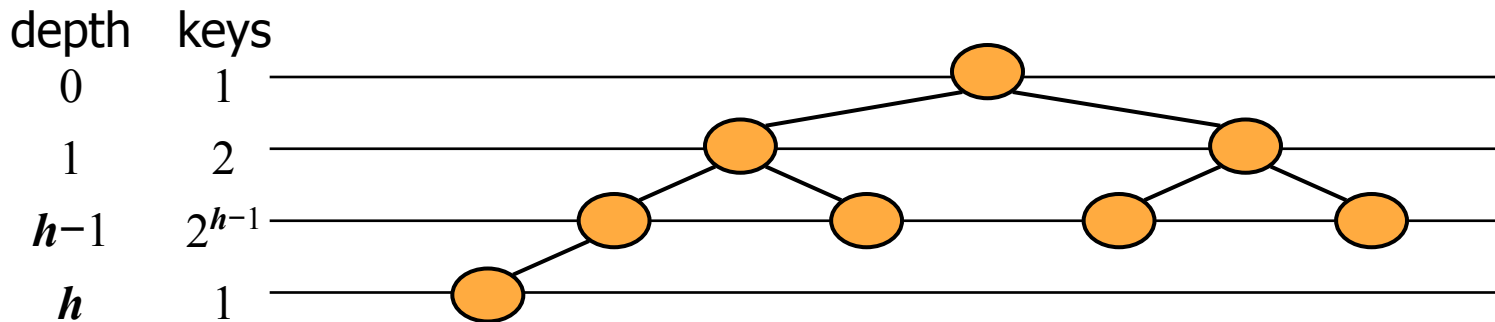
# Height of a Heap



- Theorem: A heap storing  $n$  keys has height  $O(\log n)$

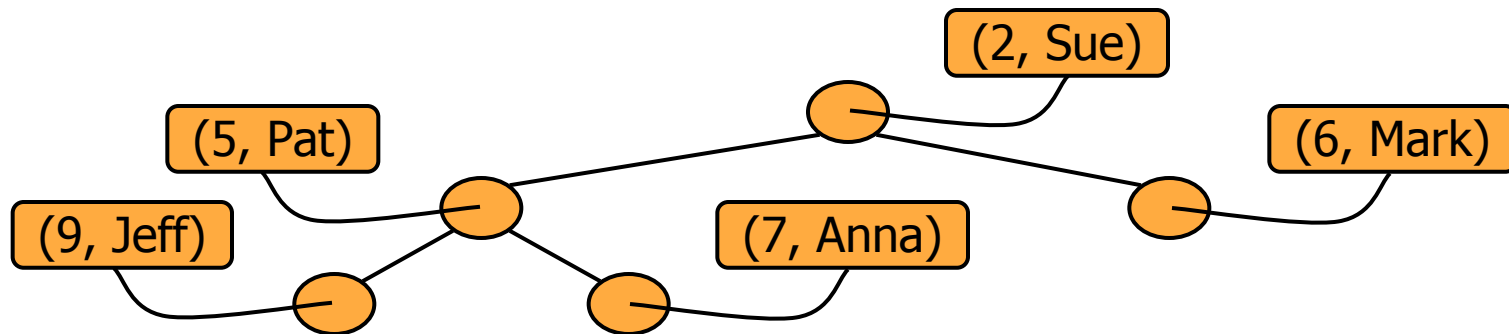
Proof: (we apply the complete binary tree property)

- Let  $h$  be the height of a heap storing  $n$  keys
- Since there are  $2^i$  keys at depth  $i = 0, \dots, h - 1$  and at least one key at depth  $h$ , we have  $n \geq 1 + 2 + 4 + \dots + 2^{h-1} + 1$
- Thus,  $n \geq 2^h$ , i.e.,  $h \leq \log n$



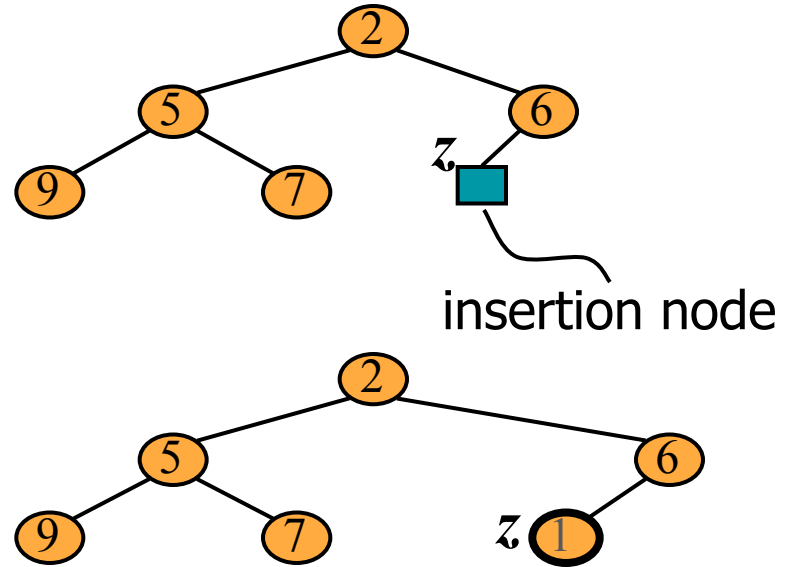
# Heaps and Priority Queues

- We can use a heap to implement a priority queue
- We store a (key, element) item at each internal node
- We keep track of the position of the last node
- For simplicity, we show only the keys in the pictures



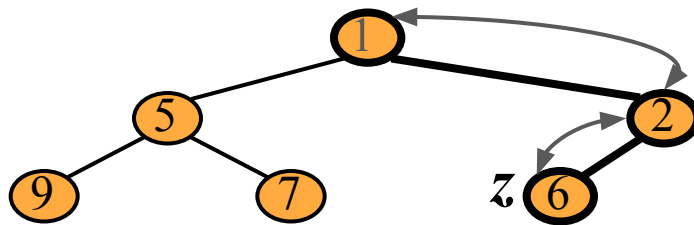
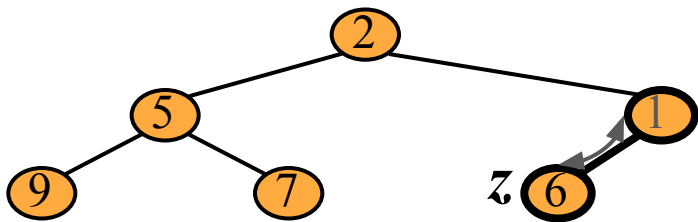
# Insertion into a Heap

- Method `insertItem` of the priority queue ADT corresponds to the insertion of a key  $k$  to the heap
- The insertion algorithm consists of three steps
  - Find the insertion node  $z$  (the new last node)
  - Store  $k$  at  $z$
  - Restore the heap-order property (discussed next)



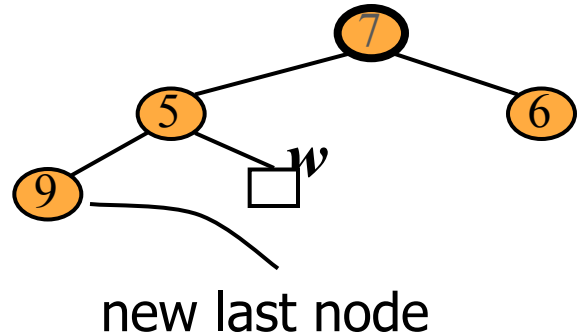
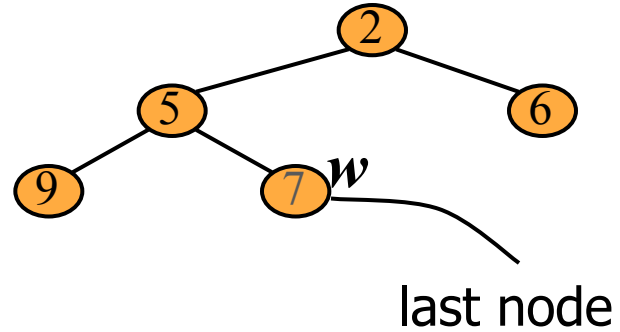
# Upheap

- After the insertion of a new key  $k$ , the heap-order property may be violated
- Algorithm upheap restores the heap-order property by swapping  $k$  along an upward path from the insertion node
- Upheap terminates when the key  $k$  reaches the root or a node whose parent has a key smaller than or equal to  $k$
- Since a heap has height  $O(\log n)$ , upheap runs in  $O(\log n)$  time



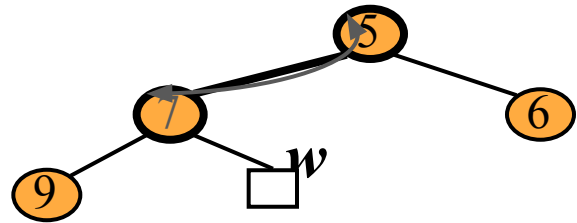
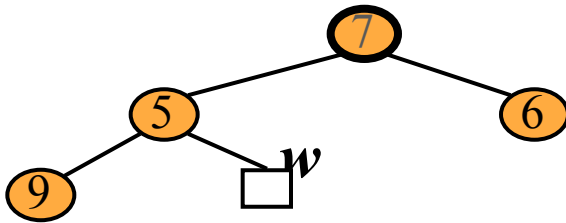
# Removal from a Heap (§ 7.3.3)

- Method `removeMin` of the priority queue ADT corresponds to the removal of the root key from the heap
- The removal algorithm consists of three steps
  - Replace the root key with the key of the last node  $w$
  - Remove  $w$
  - Restore the heap-order property (discussed next)



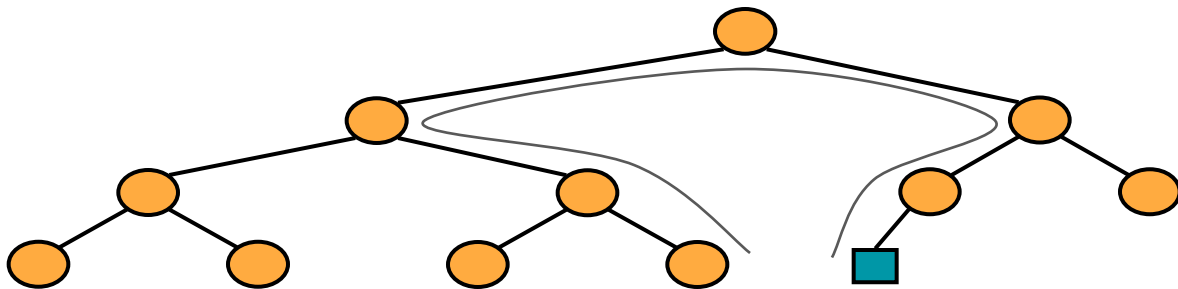
# Downheap

- After replacing the root key with the key  $k$  of the last node, the heap-order property may be violated
- Algorithm downheap restores the heap-order property by swapping key  $k$  along a downward path from the root
- Upheap terminates when key  $k$  reaches a leaf or a node whose children have keys greater than or equal to  $k$
- Since a heap has height  $O(\log n)$ , downheap runs in  $O(\log n)$  time



# Updating the Last Node

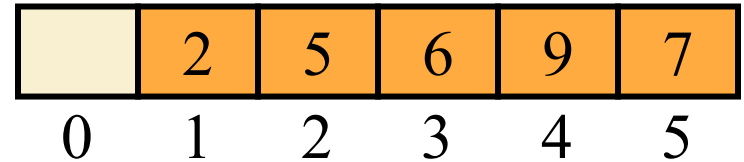
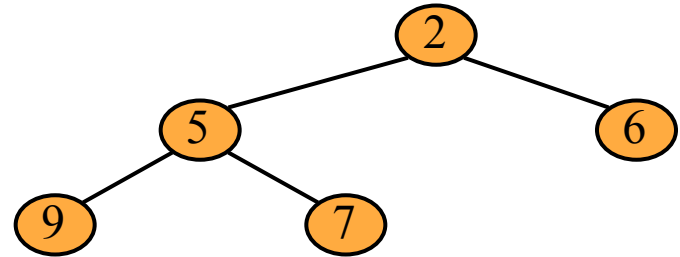
- The insertion node can be found by traversing a path of  $O(\log n)$  nodes
  - Go up until a left child or the root is reached
  - If a left child is reached, go to the right child
  - Go down left until a leaf is reached
- Similar algorithm for updating the last node after a removal





# Array-based Heap Implementation

- We can represent a heap with  $n$  keys by means of an array of length  $n + 1$
- For the node at rank  $i$ 
  - the left child is at rank  $2i$
  - the right child is at rank  $2i + 1$
- Links between nodes are not explicitly stored
- The cell of at rank 0 is not used
- Operation insert corresponds to inserting at rank  $n + 1$
- Operation removeMin corresponds to removing at rank  $n$
- Yields in-place heap-sort



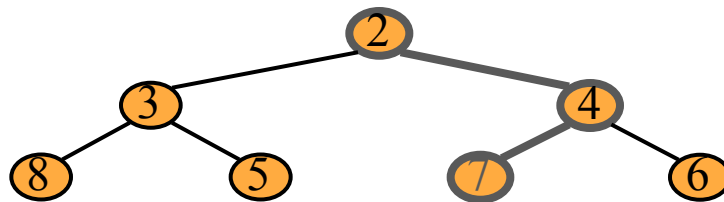
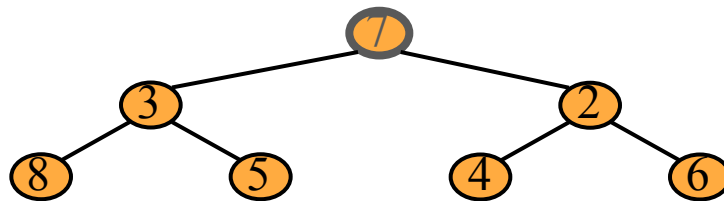
# Heap-Sort



- Consider a priority queue with  $n$  items implemented by means of a heap
  - the space used is  $O(n)$
  - methods `insert` and `removeMin` take  $O(\log n)$  time
  - methods `size`, `isEmpty`, and `min` take time  $O(1)$  time
- Using a heap-based priority queue, we can sort a sequence of  $n$  elements in  $O(n \log n)$  time
- The resulting algorithm is called heap-sort
- Heap-sort is much faster than quadratic sorting algorithms, such as insertion-sort and selection-sort

# Merging Two Heaps

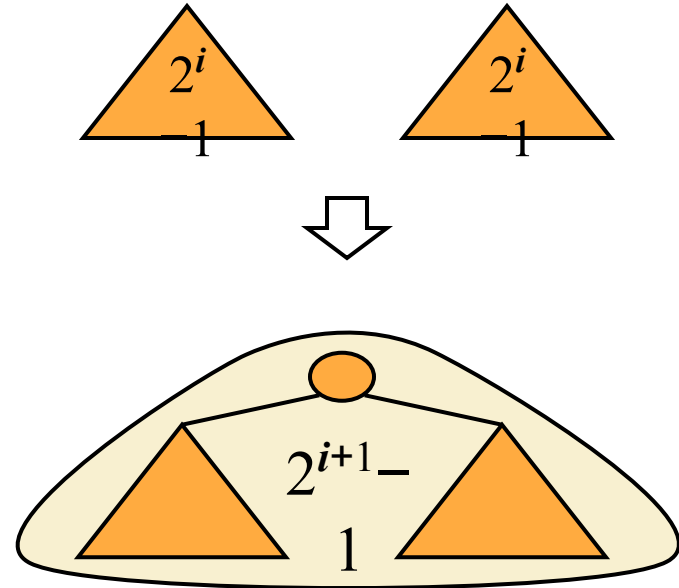
- We are given two two heaps and a key  $k$
- We create a new heap with the root node storing  $k$  and with the two heaps as subtrees
- We perform downheap to restore the heap-order property



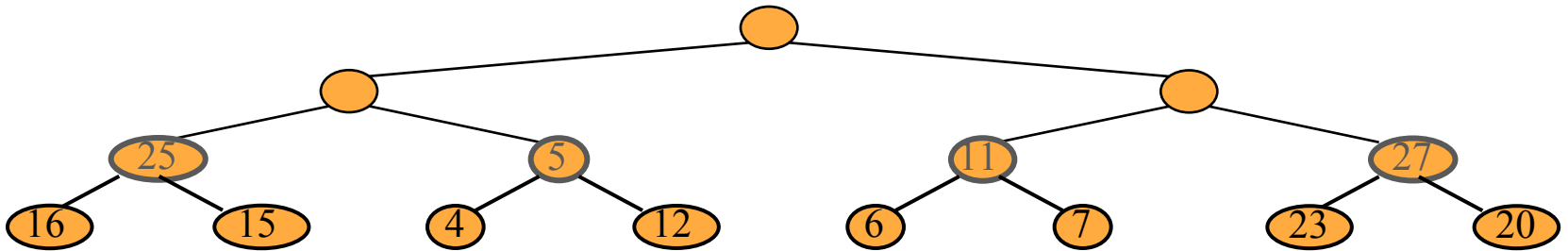
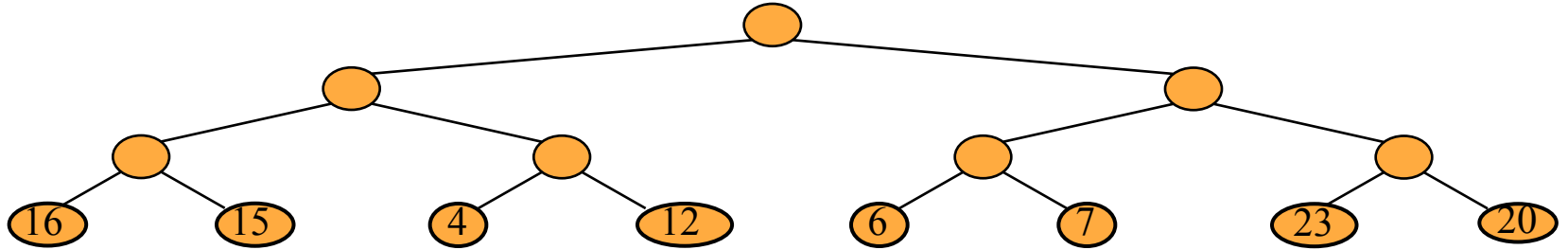
# Bottom-up Heap Construction



- We can construct a heap storing  $n$  given keys in using a bottom-up construction with  $\log n$  phases
- In phase  $i$ , pairs of heaps with  $2^i - 1$  keys are merged into heaps with  $2^{i+1} - 1$  keys



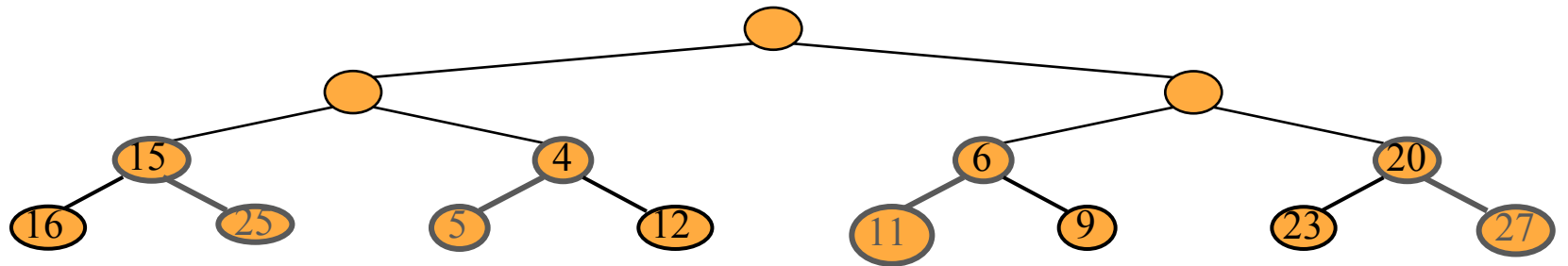
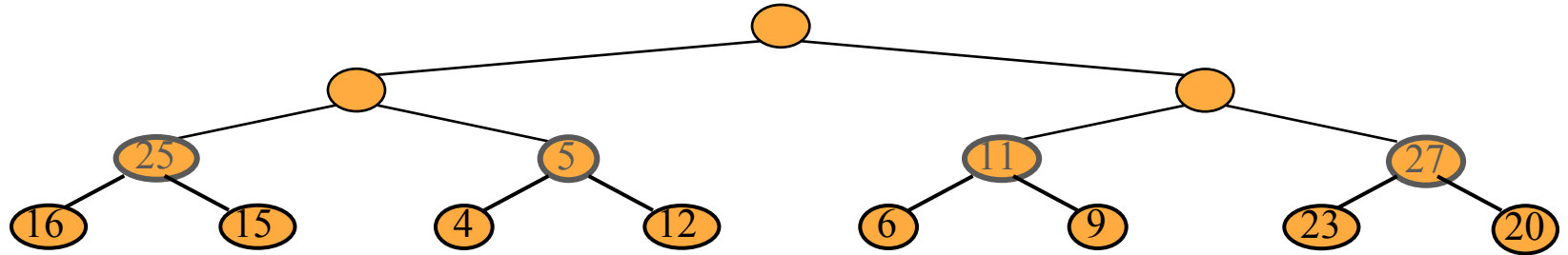
# Example



Heaps

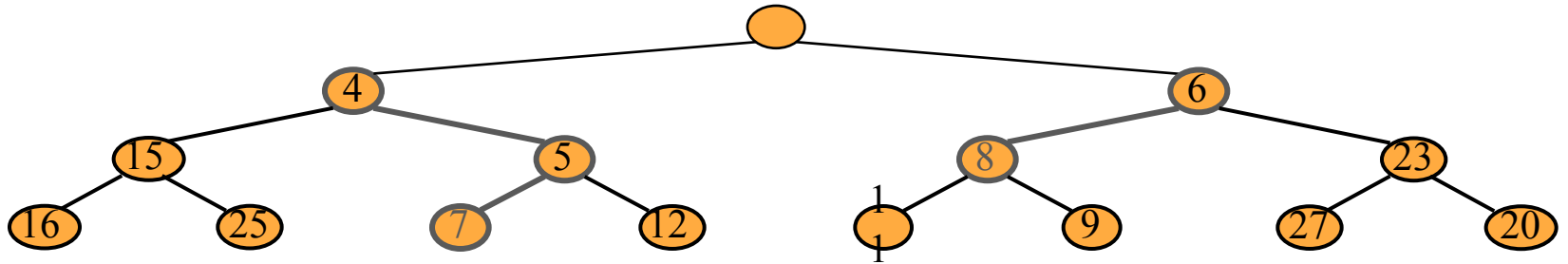
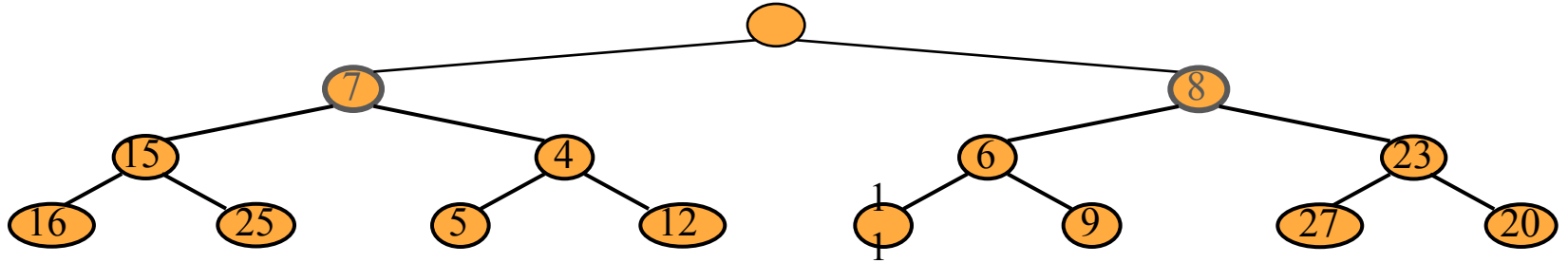
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# Example (contd.)



Heaps

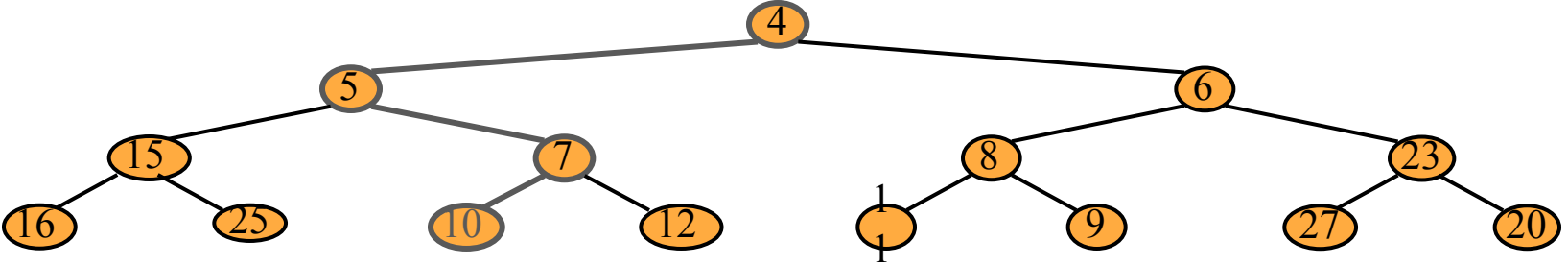
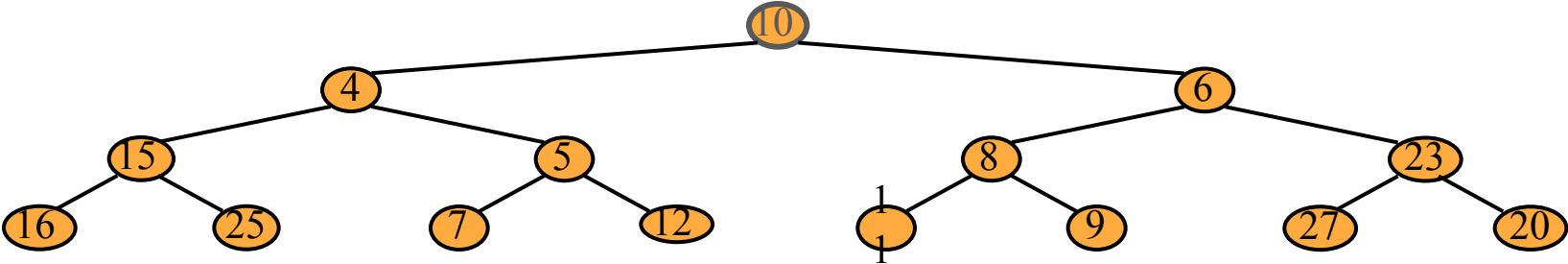
# Example (contd.)



Heaps

15

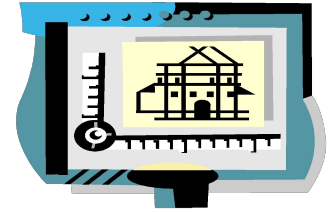
# Example (end)



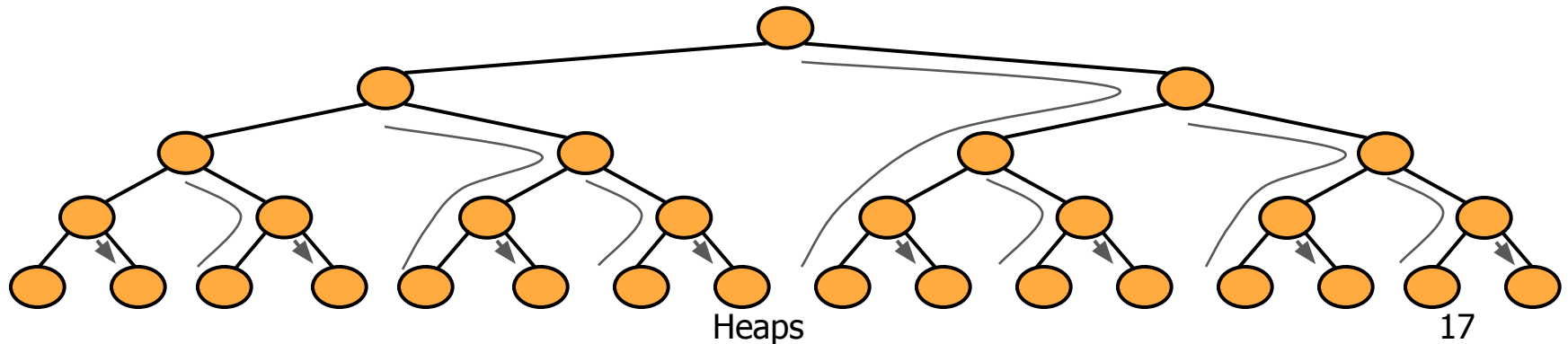
Heaps



# Analysis



- We visualize the worst-case time of a downheap with a proxy path that goes first right and then repeatedly goes left until the bottom of the heap (this path may differ from the actual downheap path)
- Since each node is traversed by at most two proxy paths, the total number of nodes of the proxy paths is  $O(n)$
- Thus, bottom-up heap construction runs in  $O(n)$  time
- Bottom-up heap construction is faster than  $n$  successive insertions and speeds up the first phase of heap-sort



# Exercises

- Take another look at Prim's, Kruskals, Dijkstra's
- Question: Can we do even better?
- Yes, an interesting type of heap called a Fibonacci heap