A Brief Primer on Inverse Procedural Modeling

CS334

Daniel G. Aliaga
Department of Computer Science
Purdue University

Recall: Procedural Modeling

- Apply algorithms for producing objects and scenes
- The rules may either be embedded into the algorithm, configurable by parameters, or externally provided

#1: Inverse Procedural Modeling by Automatic Generation of L-systems

O. Šťava, B. Beneš, R. Měch, D. Aliaga, P. Krištof*

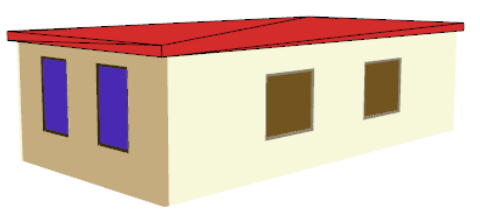
2D Vector Image → Analysis → L-system → Modifications

$$R(m) \rightarrow$$
$$A[-(\alpha)\, f(d) * (s) - (\beta) R(m-1)]$$
$$[+(\alpha')\, f\,(d') * (s') + (\beta') R(m-1)]$$

#2: Inverse 3D Procedural Buildings

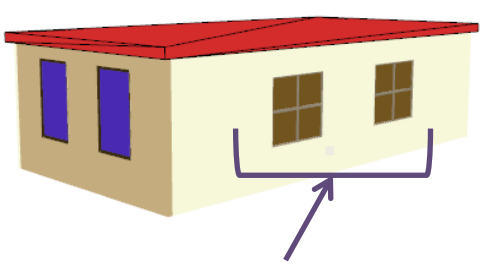
I. Demir, B. Benes, D. Aliaga

Triangle Soup



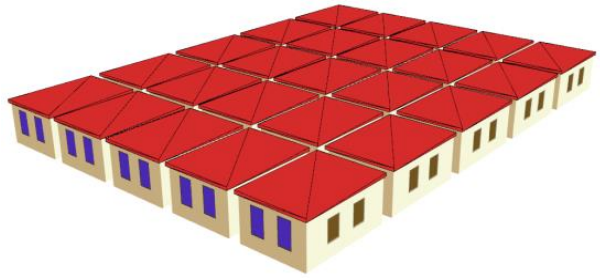
Grammar

```
Rule Building(S) = {                    // CREATE ENTIRE BUILDING
    a = split(S, 0.0, 0.0, 0.80, 4) // roof terminal
    c = split(S, 1.0, 1.0, 0.01, 5) // floor terminal
      B = split(S, 1.0, 1.0, 0.80, 5) // wall bbox
   D = split(B, 1.0, 0.1, 1.00, 5) // front wall bbox
    E = split(B, 0.0, 0.9, 0.00, 4) // back wall bbox
    F = split(B, 0.1, 1.0, 1.00, 5) // left wall bbox
   G = split(B, 0.9, 0.0, 0.00, 4) // right wall bbox
    R3(D); R3(E);                       // front/back rule
    R4(F); R4(G);                       // left/right rule
                                }
Rule R3(A) = {                          // CREATE FRONT/BACK WALL
    b = split(A, 0.0, 0.0, 0.00, 4) // wall terminal
          C = split(A, 0.4, 1.0, 0.75, 5)
   D = split(C, 0.6, 0.3, 0.00, 4) // left window bbox
          E = split(A, 0.6, 1.0, 0.75, 6)
    F = split(E, 0.3, 1.0, 0.30, 1) // right window
    R1(D); R1(F);                       // window rule
                                }
                        Rule R1(A) = {
    // perform splits for frame and window
                                }
                [...and add'l text for R2 and R4]
```

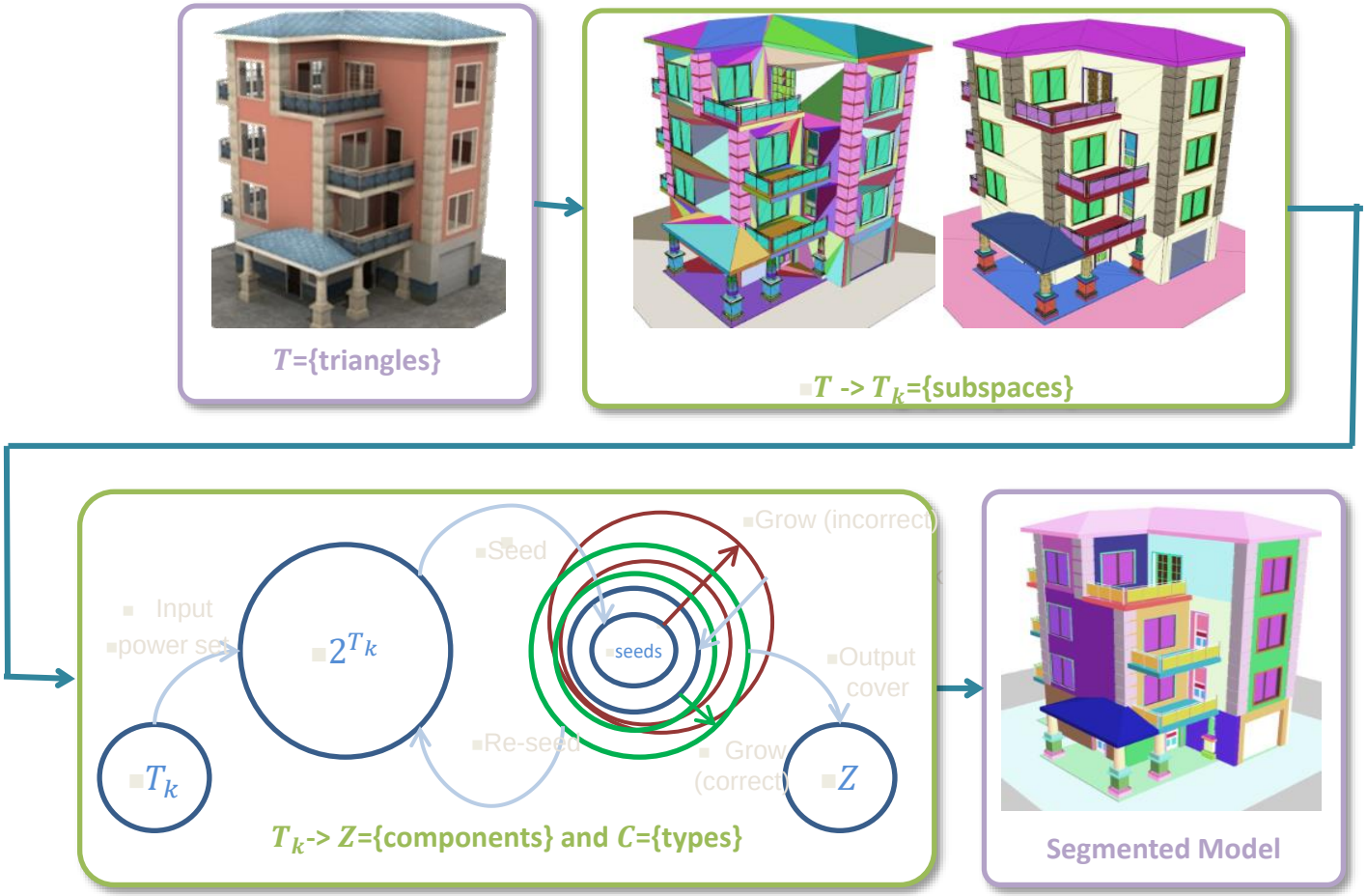


```
Rule R3(A) = {
    ...
    R1(subdivide(2,1,2,D));
    R1(subdivide(2,1,2,F));
}
```

```
Rule NewBuilding(S) = {
    Building(subdivide(5,5,1,S));
}
Rule Building(S) = {
  Z = split(S, 0.9, 0.9, 1.0, 5) // inset
  a = split(Z, 0.0, 0.0, 0.8, 4) // same
    ...
}
```

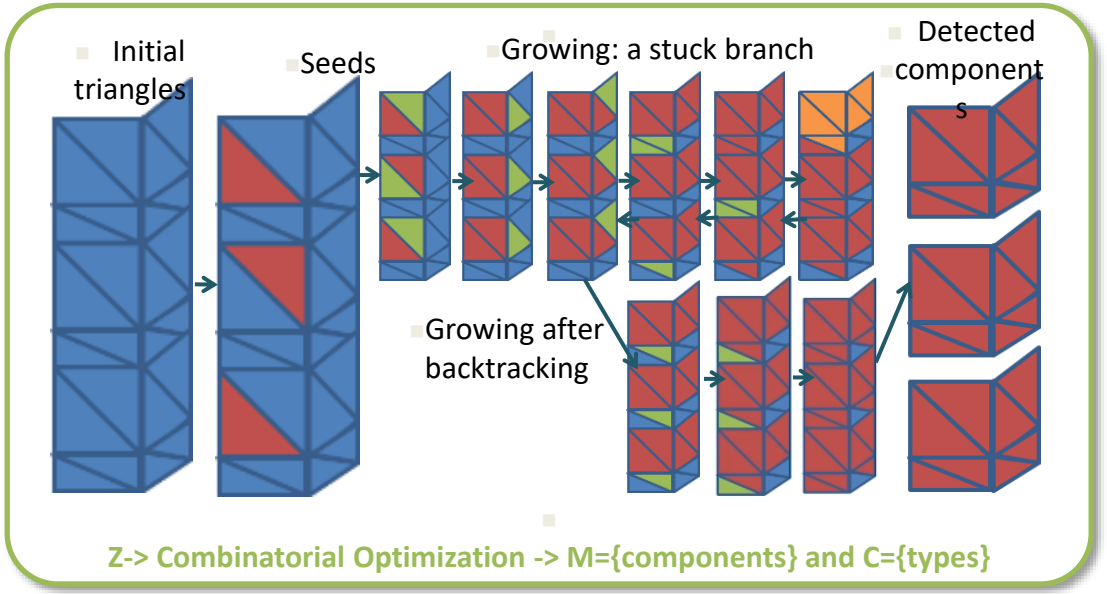


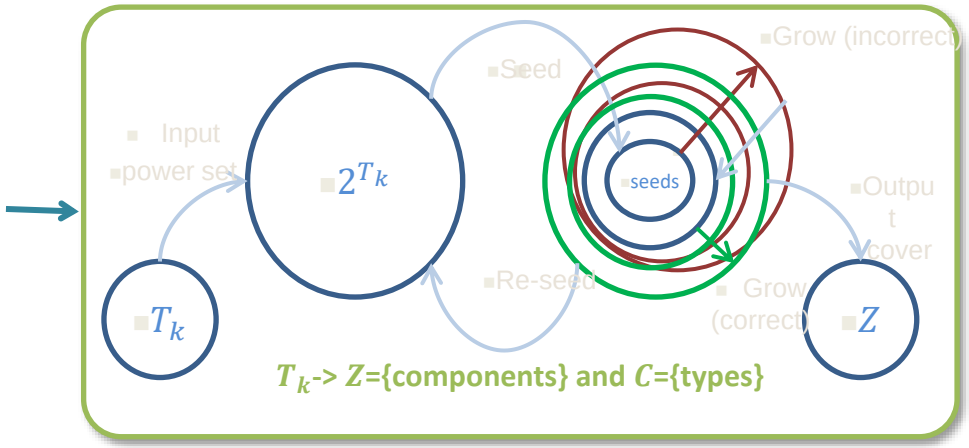
Pipeline



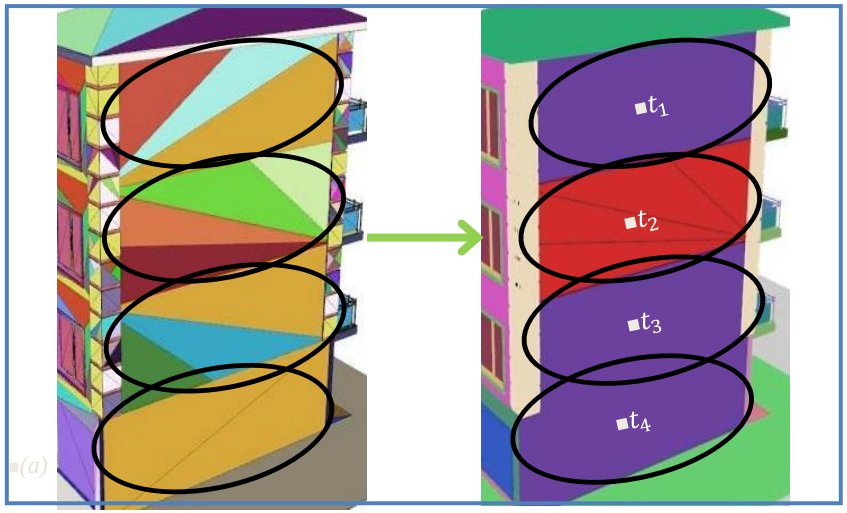
[Demir et al. 2015]

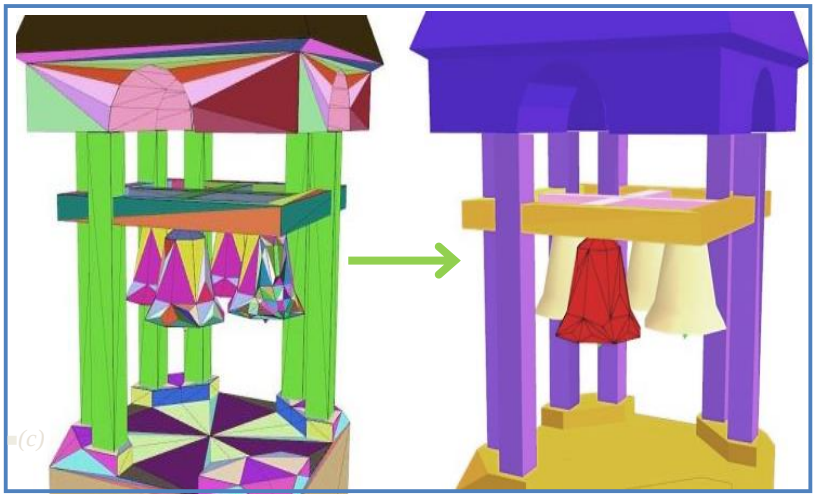
Search Process





Clustering and Components





Example Output

- Automatic

[Demir et al. 2016]

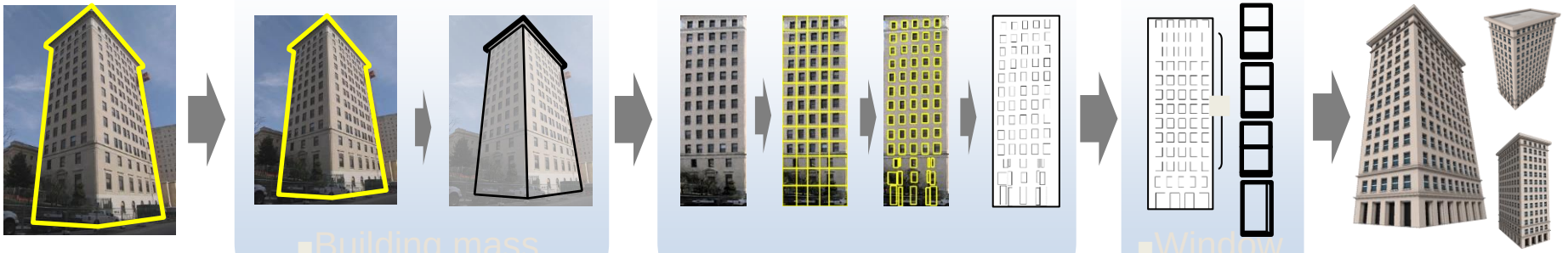
#3: Photograph to Proc. Model

G. Nishida, A. Bousseau, D. Aliaga

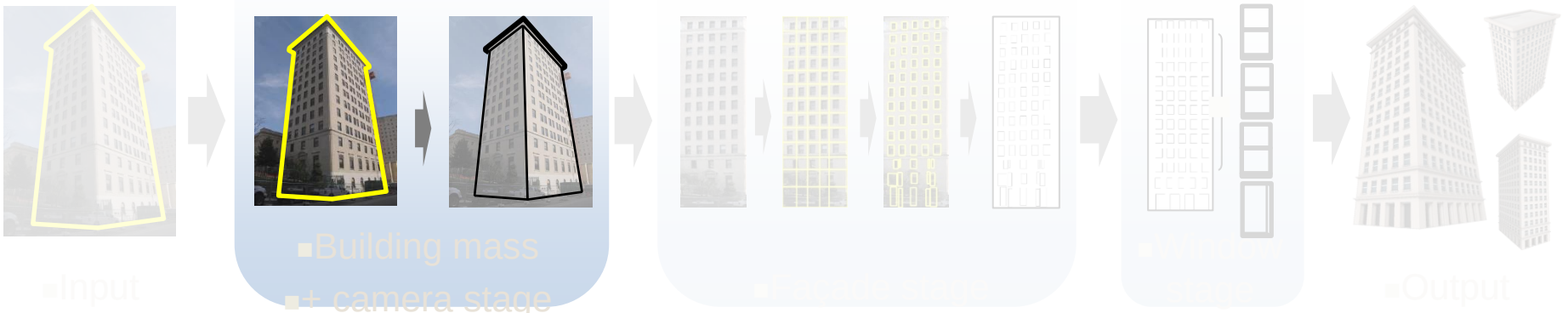
- Given an image of a building and its contour, generate a 3D procedural model similar to the input.

- [Nishida et al.

System Pipeline

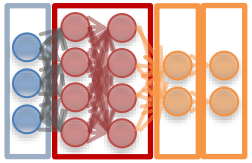


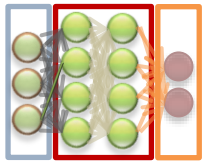
Building Mass + Camera Stage



Building Mass + Camera Stage

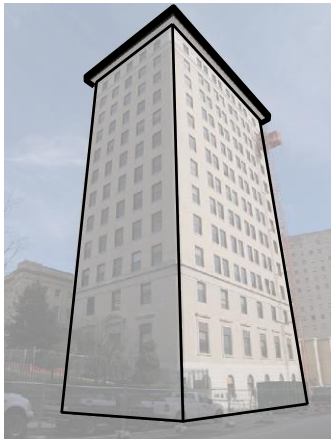
- Target Building + Silhouette





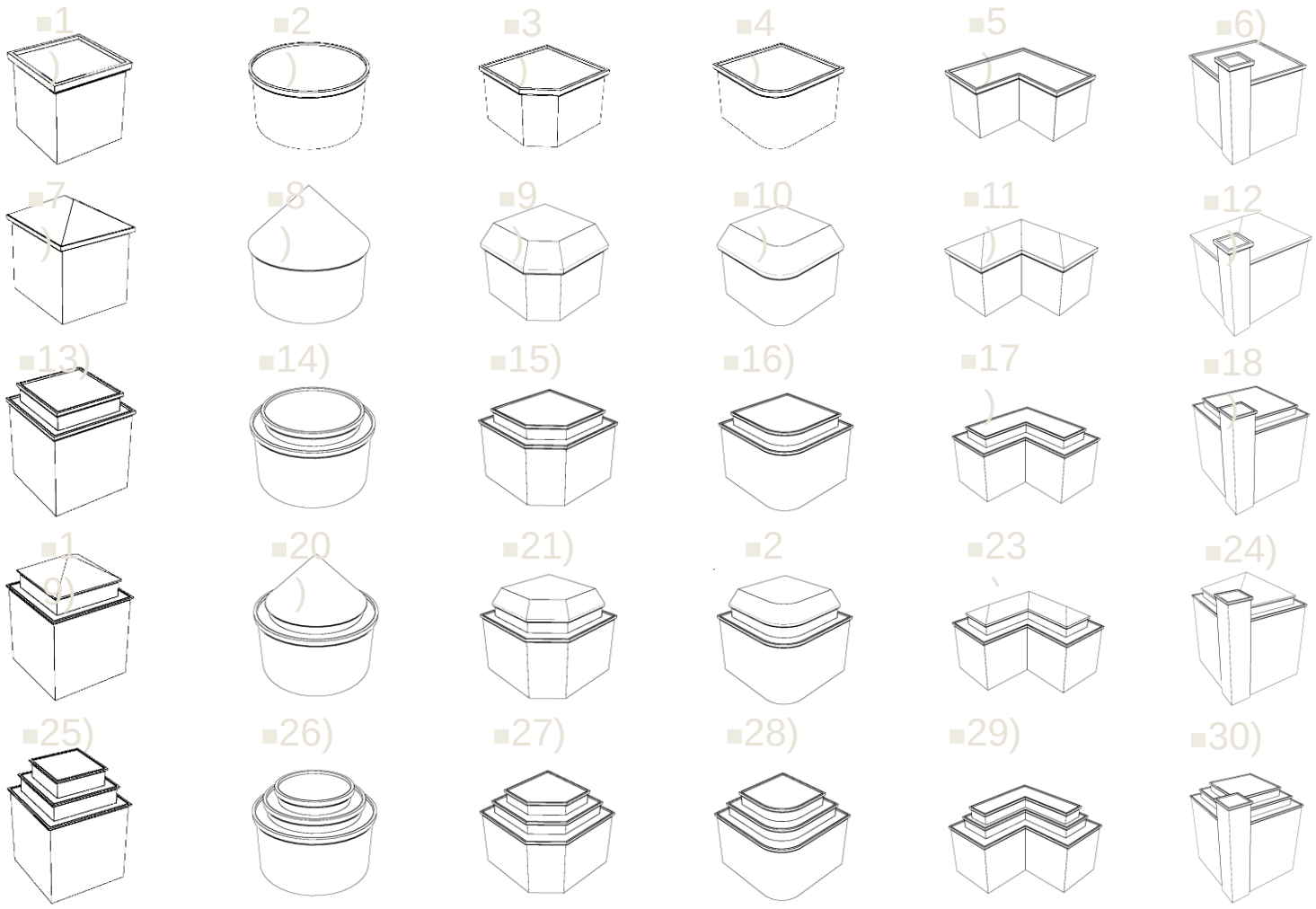
- Building mass recognition CNN
- Building mass parameter estimation CNN

- **Refinement by optimization**

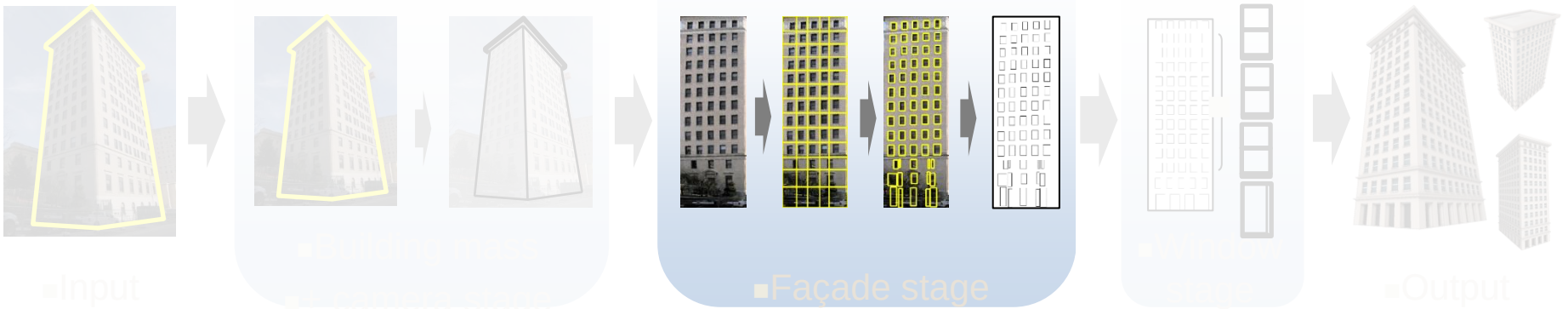


- Camera parameters
- + building mass

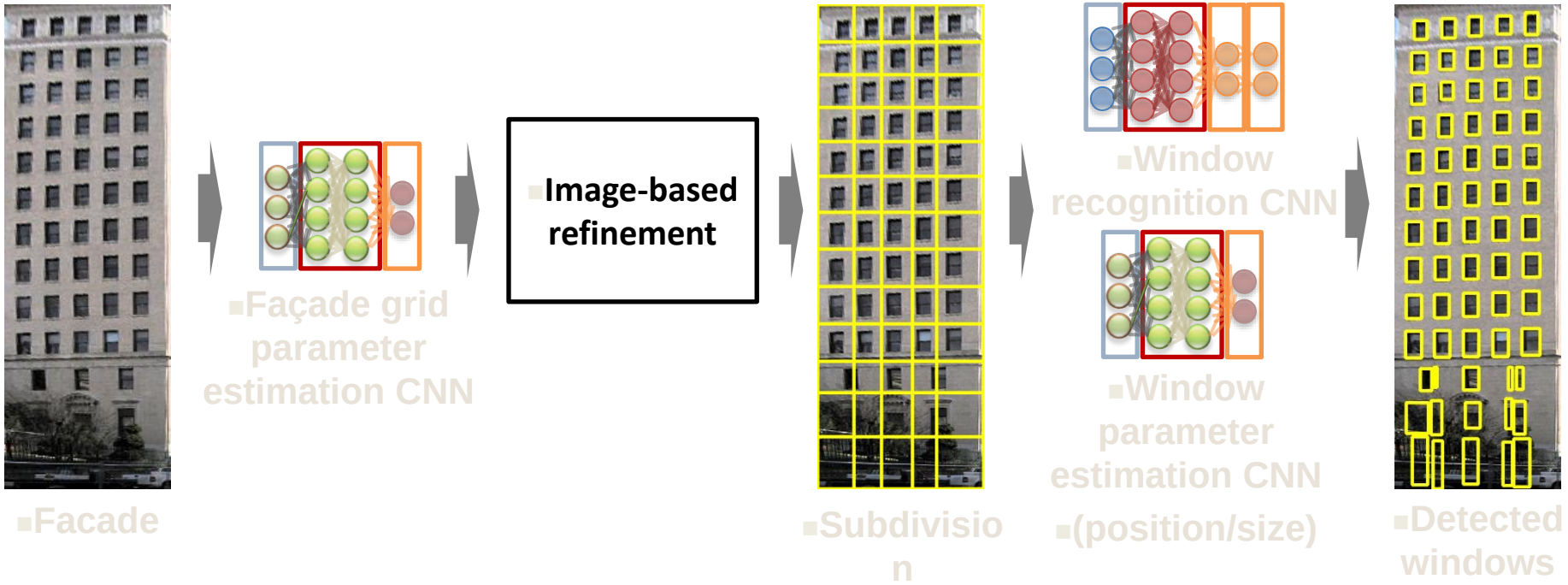
Building Mass Grammar



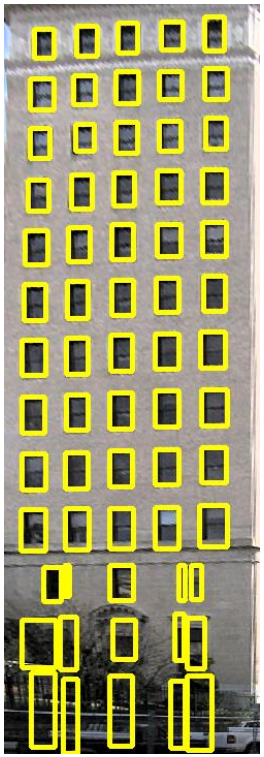
Façade Stage



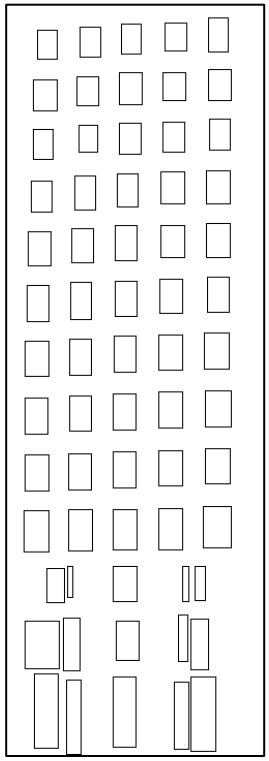
Façade Simplification



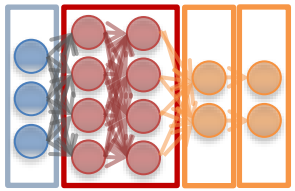
Façade Grammar Generation



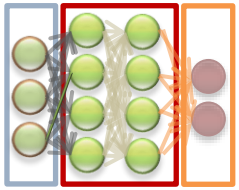
Facade



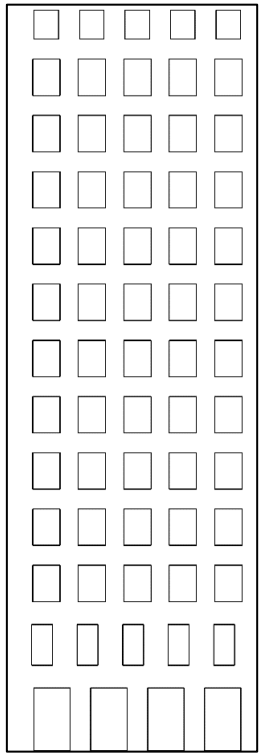
Simplified facade



Façade recognition CNN

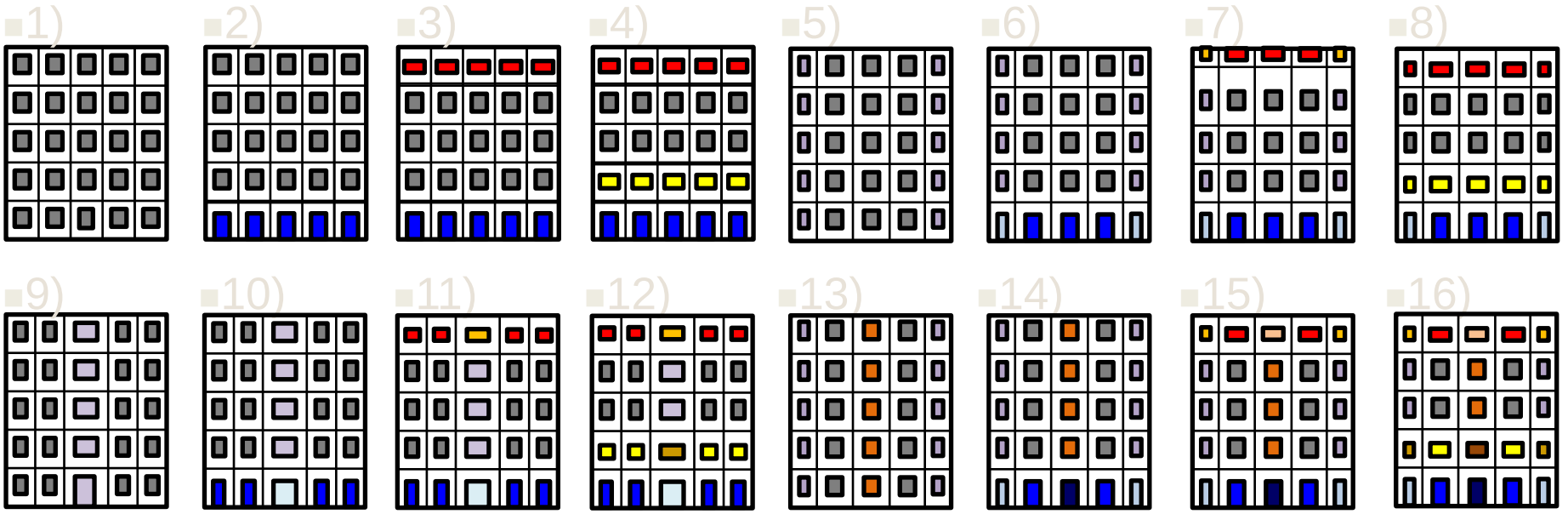


Façade parameter estimation CNN



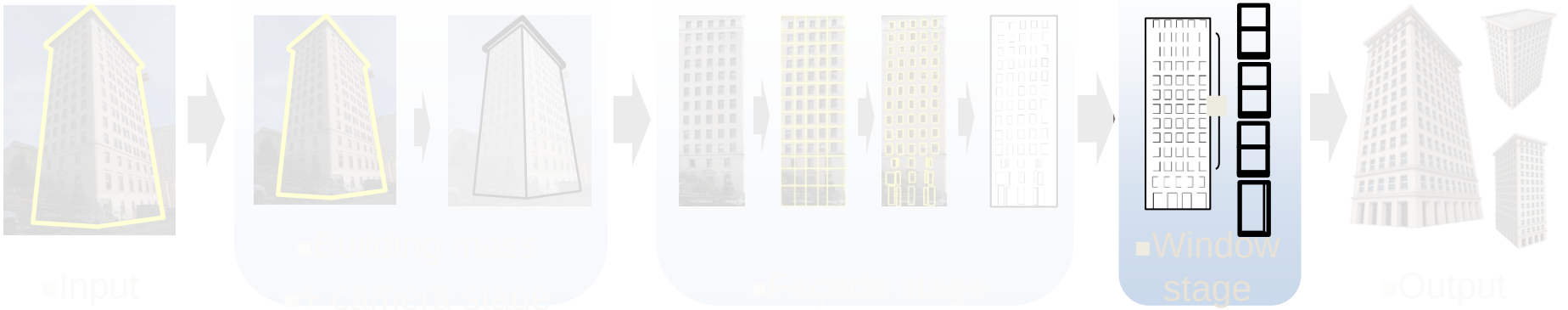
Generated Facade

Façade Grammar

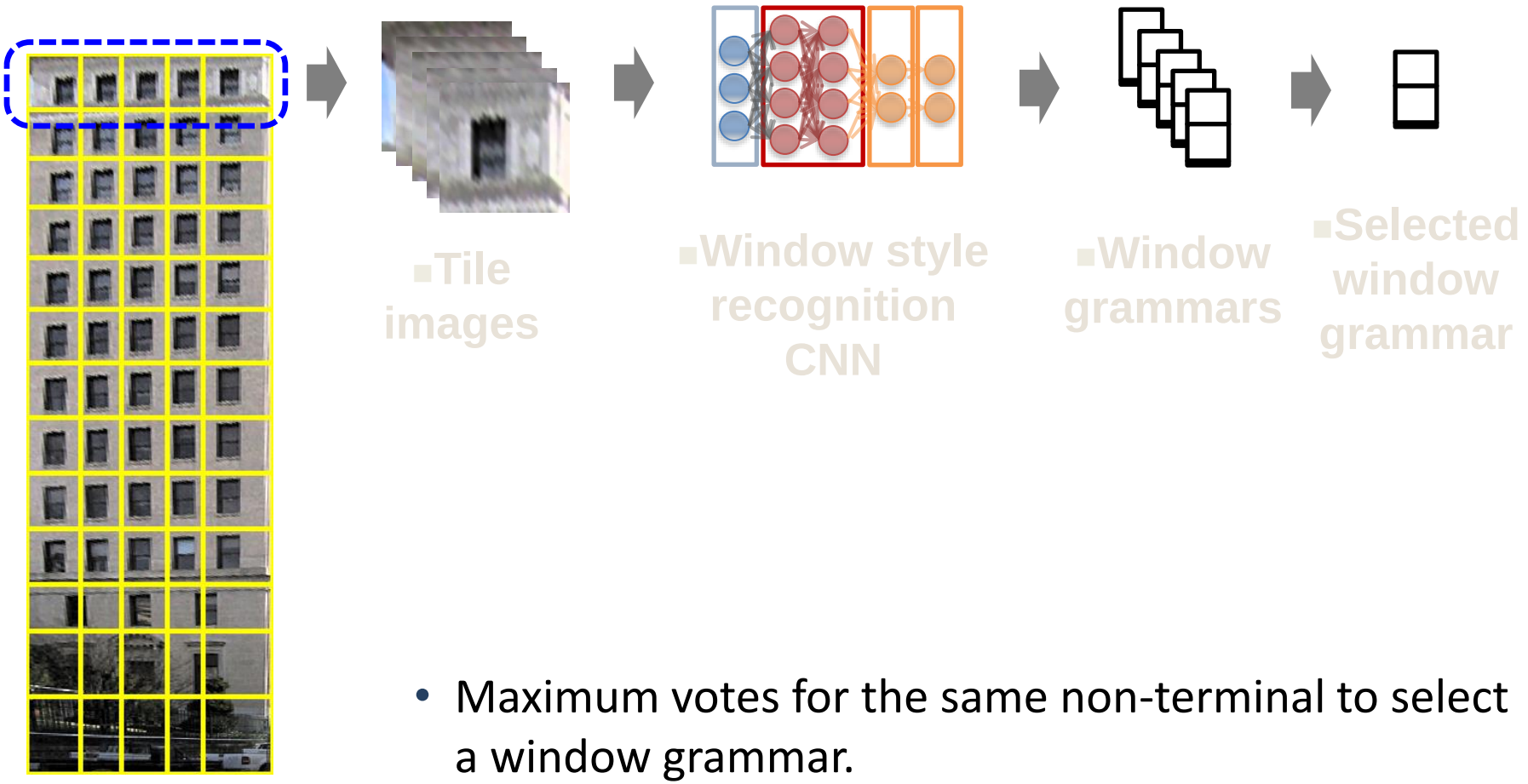


- The same color denotes the same non-terminal.

Window Stage



Window Style Recognition



- Maximum votes for the same non-terminal to select a window grammar.

Window Grammar

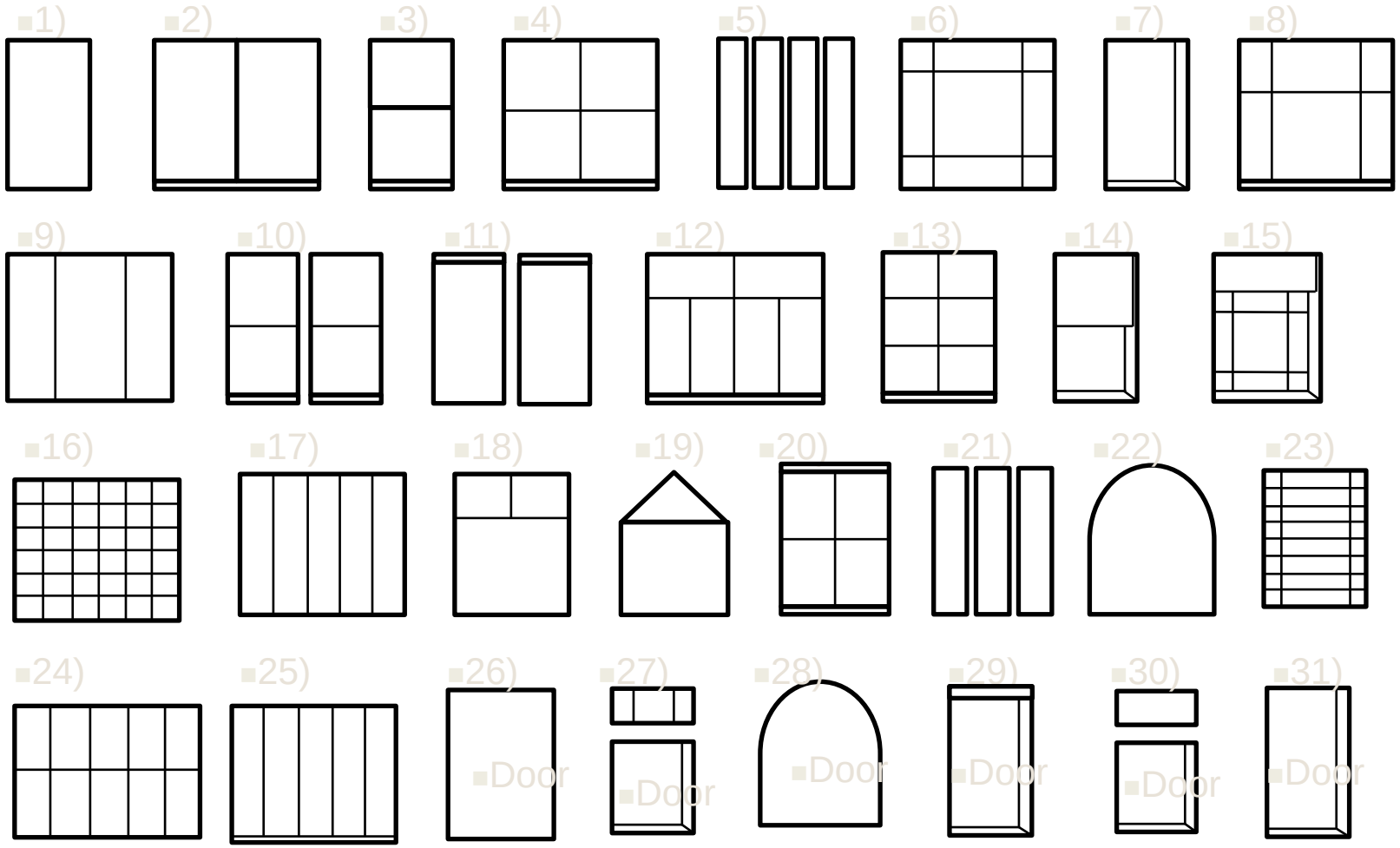


Photo to 3D Results

Aerial Images

- Still works but camera parameter estimation is less accurate due to the weaker perspective of the images.