



## Lag Camera: Separating Foreground and Background Motion

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Feb 24th, 2006

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## Goals



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- Reconstruct the background in the presence of moving objects.
- Foreground object cutout from video.

## Applications

- Capture and reconstruct busy environment.
- Enable compositing novel image sequences.

## Related Work I

- Scene Acquisition
  - Image-based rendering  
only static scenes
  - Spatial-temporal IBR  
does not reconstruct background

## Related Work II

- Motion segmentation
  - Image segmentation  
uses static images
  - Video object cut and paste
  - Interactive object cutout  
uses video from a static camera

## Challenges



- Reconstructing background with a moving camera.
- Video object cutout is only known for static cameras.

## Our solution



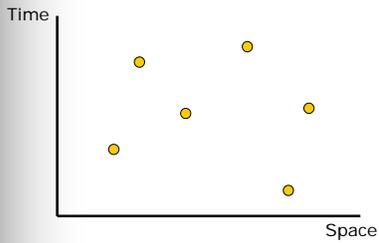
- Lag camera - a moving camera array.



## Still Camera



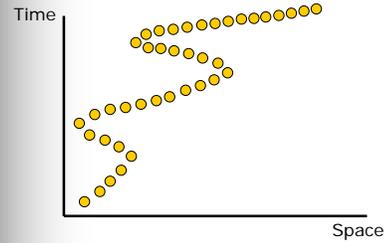
sparse and disjoint samples



## Video Camera



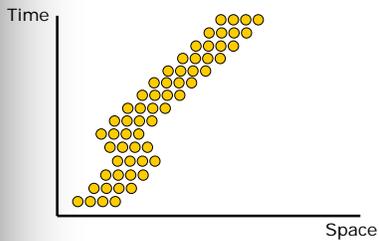
dense and continuous samples over space



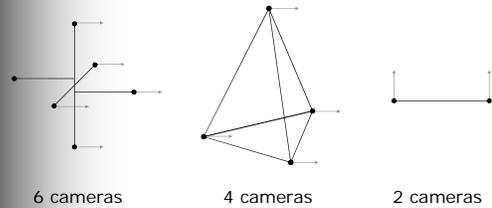
## Lag Camera



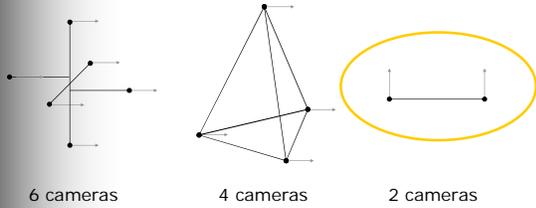
dense and continuous samples over space and time



## Lag Camera Configurations



## Lag Camera Configurations



6 cameras

4 cameras

2 cameras

## 2-view Lag Camera

- For acquisition along a line, it obtains images from (approximately) the same viewpoint but at sequential instances in time.

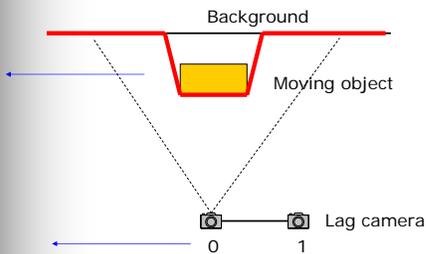


time 0

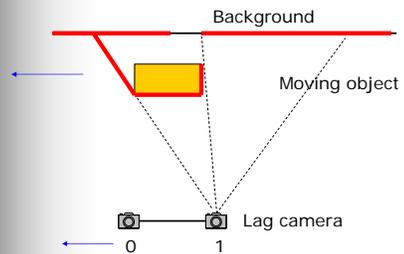


time 1

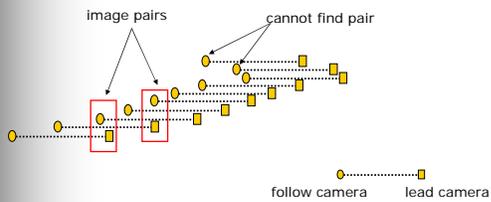
## Lag Camera



## Lag Camera



## Lag Camera Image Pairs



## Lag Camera Image Pairs

- Estimate camera pose
  - Currently we use a mechanically tracked arm
- Proxy-warp the lead image to follow image



follow image



warped lead image

## Lag Camera Capturing



- [capture.avi](#)

## Our Methods: Part 1

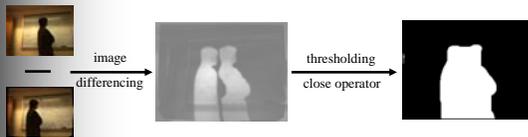


- Foreground Motion
  - A motion detection algorithm that identifies object motion even when camera is moving.
- Background Scene
  - A capturing method that samples a static scene in presence of moving objects.

## Foreground: Motion Mask



- Isolate foreground using a motion mask



## Stop Motion



- However, when motion stops, the difference image goes to zero.



3 consecutive frames of difference images

## Stop Motion



- Re-project the nearby motion masks to the frame where motion stops.



## Motion Mask Composition



- Masks for different segments are composited together.

Constructed by re-projecting adjacent frames



original frame

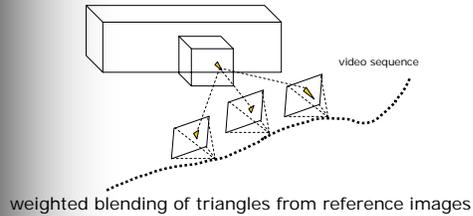
difference image

motion mask

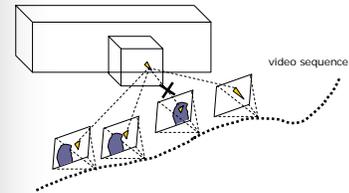
## Background Rendering



### ■ Unstructured Lumigraph Rendering (ULR)



## Modified Unstructured Lumigraph



## Results



- 2 board scenes with 142 and 102 images
  - [board.avi](#)
- 1 bookcase scene with 298 images
  - [bookcase.avi](#)

## Problems So Far...



- Self-similarity of the moving object
  - Causes the mask to be zero when foreground object is similar to itself.
- Conservativeness of the motion mask
  - Sometimes the motion mask is too conservative.

## Our Methods: Part 2

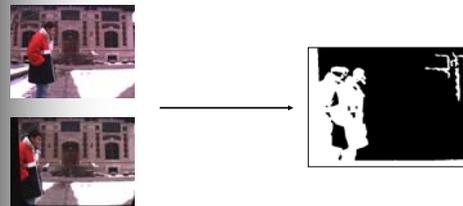


- Foreground Motion Segmentation
  - A color-segmentation-based method to include self-similarity regions in the initial motion mask.
  - An iterative segmentation algorithm for progressively refining the segmentation.

## Initial Motion Mask



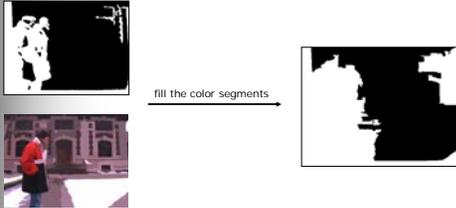
- The self-similarity problem:



## Initial Motion Mask



- Use color segmentation to fill the regions.



## Iterative Refinement



- Rank all the segments in all images.
- Choose the highest ranked segment and convert it from motion mask to background.
- Re-rank all the remaining regions.

## Iterative Refinement



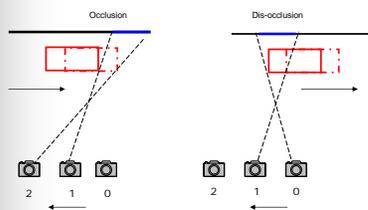
- The definition of the score  $S$  of a segment:
  - $D$ : re-project a segment to nearby images and compute the dissimilarity.
  - $C$ : the percentage of the re-projected region inside the mask.
  - $S = w_1 * D + w_2 * C$

## Interactive Editing Tool

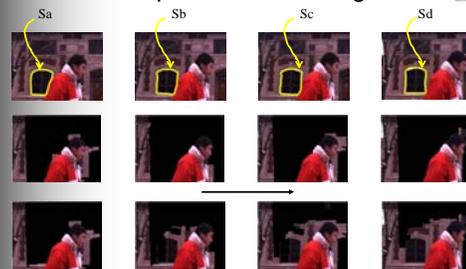


- System iteratively updates the scores, refines the mask; until a threshold is reached.
- User removes some segments from the mask.

## Occlusion-compatible Processing Order



## Occlusion-compatible Processing Order

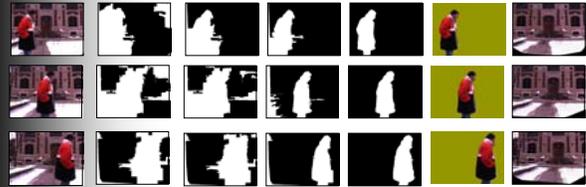


## Results



[boardisr.avi](#)

## Results



[csisr.avi](#)

## Future Work



- Elimination of shadows.
- Vision based camera pose estimation.
- Other lag camera configurations.

## Future Work



- Spatial-temporal coherent image segmentation
  - New formulation of the mean-shift clustering
- Generalized energy term
  - Min-cut

## Conclusions



- An efficient motion detection algorithm with moving camera.
- A capturing method that samples a static scene in presence of moving objects.
- An editing tool for quickly segmenting moving foreground objects captured by moving cameras.
- An iterative segmentation algorithm for progressively refining the segmentation.