

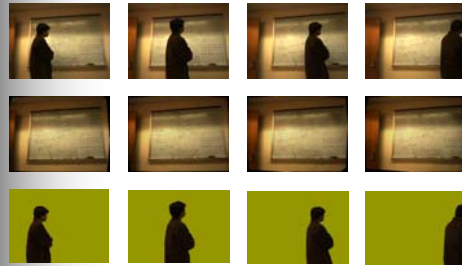


Lag Camera: Separating Foreground and Background Motion

D. Aliaga, Y. Xu, V. Popescu
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Department of Computer Science

Goals



Goals

- Reconstruct the background in the presence of moving objects.
- Foreground object cutout from video.

Applications

- Capture and reconstruct busy environment.
- Enable compositing novel image sequences.

Related Work I

- Scene Acquisition
 - Image-based rendering
only static scenes
 - Spatial-temporal IBR
does not reconstruct background

Related Work II

- Motion segmentation
 - Image segmentation
uses static images
 - Video object cut and paste
 - Interactive object cutout
uses video from a static camera

Challenges



- Reconstructing background with a moving camera.
- Video object cutout is only known for static cameras.

Our solution



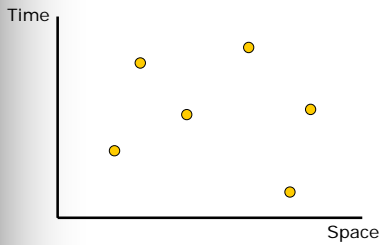
- Lag camera - a moving camera array.



Still Camera



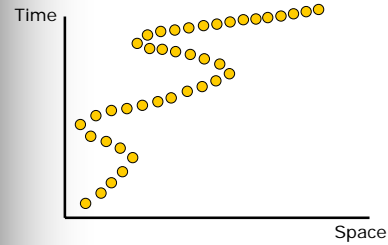
sparse and disjoint samples



Video Camera



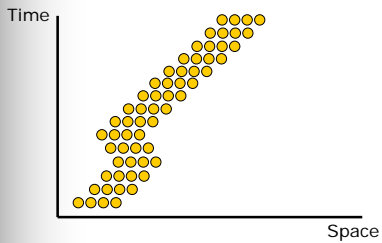
dense and continuous samples over space



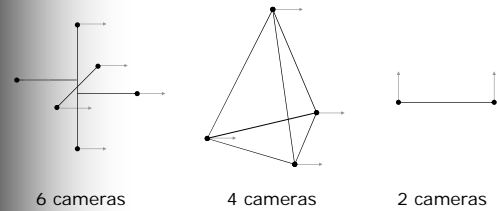
Lag Camera



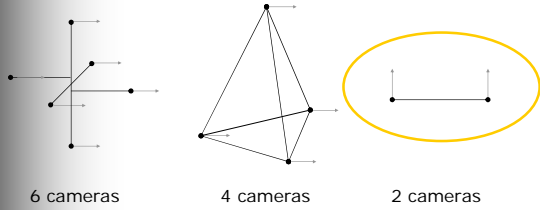
dense and continuous samples over space and time



Lag Camera Configurations



Lag Camera Configurations



6 cameras

4 cameras

2 cameras

2-view Lag Camera

- For acquisition along a line, it obtains images from (approximately) the same viewpoint but at sequential instances in time.

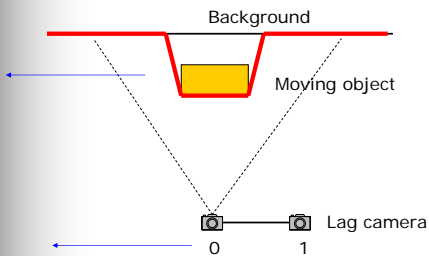


time 0

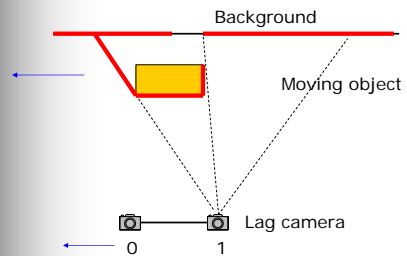


time 1

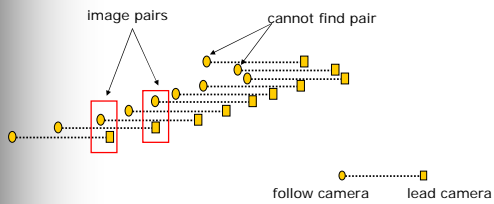
Lag Camera



Lag Camera



Lag Camera Image Pairs



follow camera

lead camera

Lag Camera Image Pairs

- Estimate camera pose
 - Currently we use a mechanically tracked arm
- Proxy-warp the lead image to follow image



follow image



warped lead image

Lag Camera Capturing



- [capture.avi](#)

Our Methods: Part 1

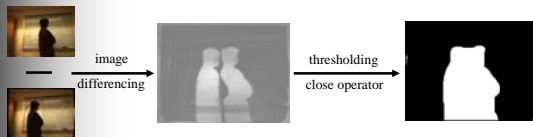


- Foreground Motion
 - A motion detection algorithm that identifies object motion even when camera is moving.
- Background Scene
 - A capturing method that samples a static scene in presence of moving objects.

Foreground: Motion Mask



- Isolate foreground using a motion mask



Stop Motion



- However, when motion stops, the difference image goes to zero.



3 consecutive frames of difference images

Stop Motion



- Re-project the nearby motion masks to the frame where motion stops.



Motion Mask Composition



- Masks for different segments are composited together.

Constructed by re-projecting adjacent frames

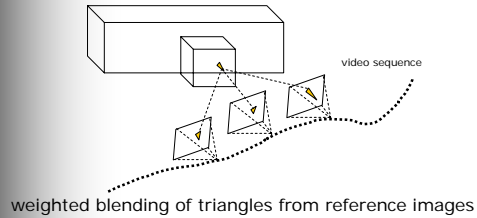


original frame difference image motion mask

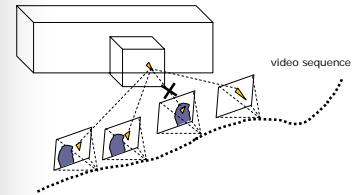
Background Rendering



■ Unstructured Lumigraph Rendering (ULR)



Modified Unstructured Lumigraph



Results



■ 2 board scenes with 142 and 102 images

□ [board.avi](#)

■ 1 bookcase scene with 298 images

□ [bookcase.avi](#)

Problems So Far...



■ Self-similarity of the moving object

□ Causes the mask to be zero when foreground object is similar to itself.

■ Conservativeness of the motion mask

□ Sometimes the motion mask is too conservative.

Our Methods: Part 2



■ Foreground Motion Segmentation

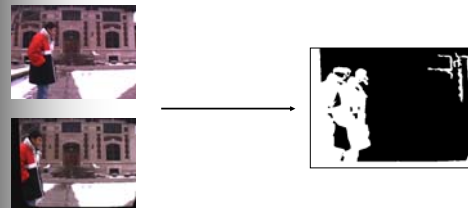
□ A color-segmentation-based method to include self-similarity regions in the initial motion mask.

□ An iterative segmentation algorithm for progressively refining the segmentation.

Initial Motion Mask



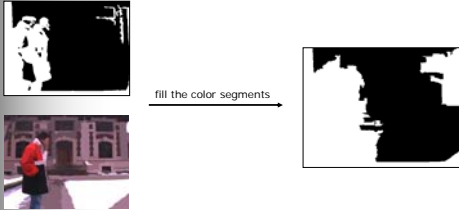
■ The self-similarity problem:



Initial Motion Mask



- Use color segmentation to fill the regions.



Iterative Refinement



- Rank all the segments in all images.
- Choose the highest ranked segment and convert it from motion mask to background.
- Re-rank all the remaining regions.

Iterative Refinement



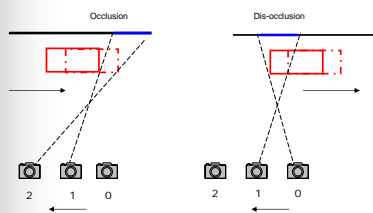
- The definition of the score S of a segment:
 - D : re-project a segment to nearby images and compute the dissimilarity.
 - C : the percentage of the re-projected region inside the mask.
 - $S = w_1 * D + w_2 * C$

Interactive Editing Tool

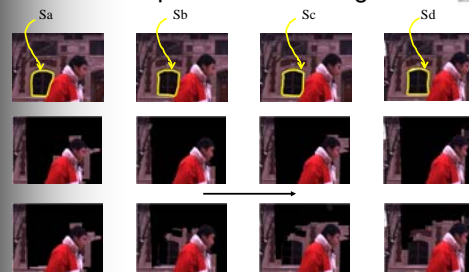


- System iteratively updates the scores, refines the mask; until a threshold is reached.
- User removes some segments from the mask.

Occlusion-compatible Processing Order



Occlusion-compatible Processing Order

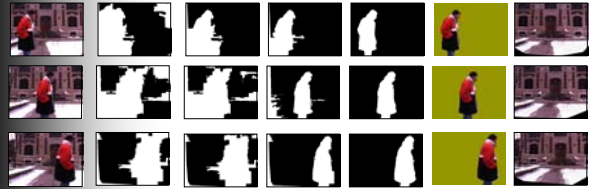


Results



[boardisr.avi](#)

Results



[csisr.avi](#)

Future Work



- Elimination of shadows.
- Vision based camera pose estimation.
- Other lag camera configurations.

Future Work



- Spatial-temporal coherent image segmentation
 - New formulation of the mean-shift clustering
- Generalized energy term
 - Min-cut

Conclusions



- An efficient motion detection algorithm with moving camera.
- A capturing method that samples a static scene in presence of moving objects.
- An editing tool for quickly segmenting moving foreground objects captured by moving cameras.
- An iterative segmentation algorithm for progressively refining the segmentation.