



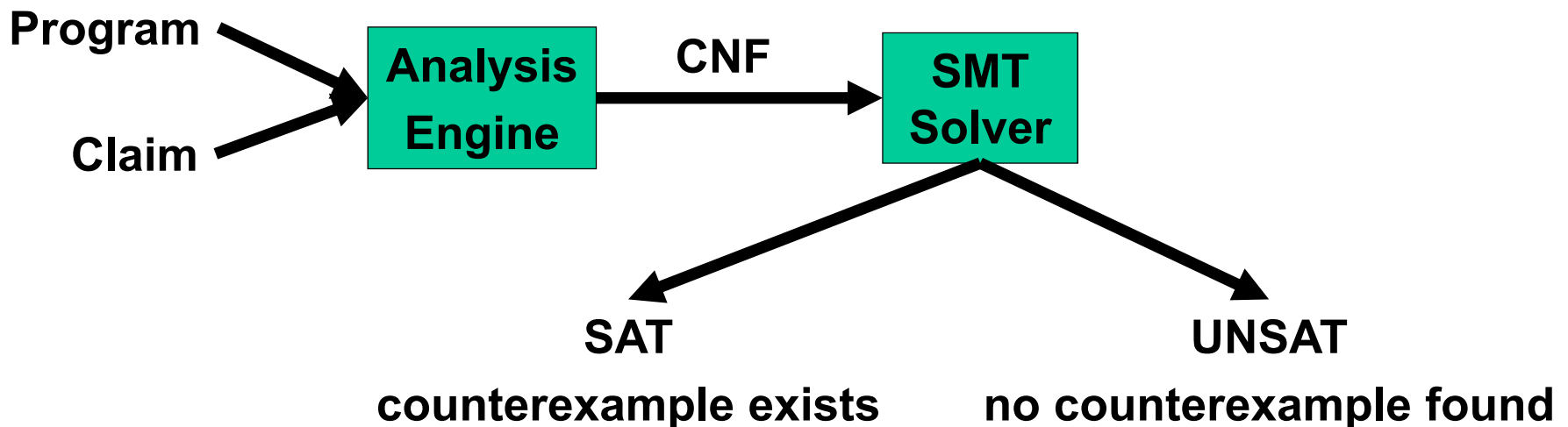
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# Software Model Checking

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# Symbolic Software Model Checking

- Symbolic analysis explicitly explores individual paths, encodes and resolves path conditions
- Model checking directly encodes both the program and the property to check to constraints



# A (very) simple example (1)

## Program

```
int x;  
int y=8,z=0,w=0;  
if (x)  
    z = y - 1;  
else  
    w = y + 1;  
assert (z == 7 ||  
        w == 9)
```

## Constraints

```
y = 8,  
z = x ? y - 1 : 0,  
w = x ? 0 : y + 1,  
z != 7,  
w != 9
```

**UNSAT**  
no counterexample  
assertion always holds!

# A (very) simple example (2)

## Program

```
int x;  
int y=8,z=0,w=0;  
if (x)  
    z = y - 1;  
else  
    w = y + 1;  
assert (z == 5 ||  
        w == 9)
```

## Constraints

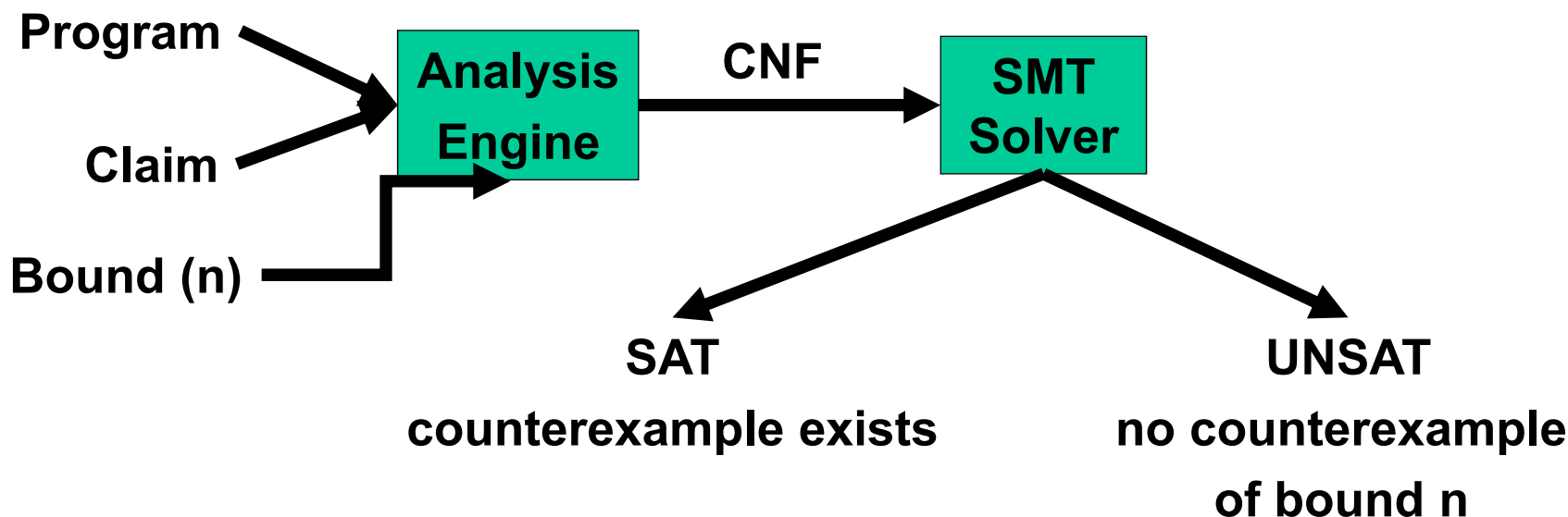
```
y = 8,  
z = x ? y - 1 : 0,  
w = x ? 0 : y + 1,  
z != 5,  
w != 9
```

**SAT**  
**counterexample found!**

**y = 8, x = 1, w = 0, z = 7**

# Procedure

- Unroll loops



- Translate to SSA form
- SSA to SMT constraints

# Loop Unwinding

---

- **All loops are unwound**
  - can use different unwinding bounds for different loops
  - to check whether unwinding is sufficient special “unwinding assertion” claims are added
- **If a program satisfies all of its claims and all unwinding assertions then it is correct!**
- **Same for backward goto jumps and recursive functions**

# Loop Unwinding

```
void f(...) {  
    ...  
    while(cond) {  
        Body;  
    }  
    Remainder;  
}
```

- while() loops are unwound iteratively
- Break / continue replaced by goto

# Loop Unwinding

---

```
void f(...) {  
    ...  
    if(cond) {  
        Body;  
        while(cond) {  
            Body;  
        }  
    }  
    Remainder;  
}
```

- while() loops are unwound iteratively
- Break / continue replaced by goto



# Loop Unwinding

```
void f(...) {  
    ...  
    if(cond) {  
        Body;  
        if(cond) {  
            Body;  
            while(cond) {  
                Body;  
            }  
        }  
    }  
    Remainder;  
}
```

- while() loops are unwound iteratively
- Break / continue replaced by goto

# Unwinding assertion

```
void f(...) {  
    ...  
    if(cond) {  
        Body;  
        if(cond) {  
            Body;  
            if(cond) {  
                Body;  
                while(cond) {  
                    Body;  
                }  
            }  
        }  
    }  
    Remainder;  
}
```

- while() loops are unwound iteratively
- Break / continue replaced by goto
- Assertion inserted after last iteration: violated if program runs longer than bound permits



# Example: Sufficient Loop Unwinding

```
void f(...) {  
    j = 1  
    while (j <= 2)  
        j = j + 1;  
    Remainder;  
}
```

**-unwind = 3**

```
void f(...) {  
    j = 1  
    if(j <= 2) {  
        j = j + 1;  
        if(j <= 2) {  
            j = j + 1;  
            if(j <= 2) {  
                j = j + 1;  
                assert(!(j <= 2));  
            }  
        }  
    }  
    Remainder;  
}
```

# Example: Insufficient Loop Unwinding

```
void f(...) {  
    j = 1  
    while (j <= 10)  
        j = j + 1;  
    Remainder;  
}
```

**-unwind = 3**

```
void f(...) {  
    j = 1  
    if(j <= 10) {  
        j = j + 1;  
        if(j <= 10) {  
            j = j + 1;  
            if(j <= 10) {  
                j = j + 1;  
                assert(!(j <= 10));  
            }  
        }  
    }  
    Remainder;  
}
```

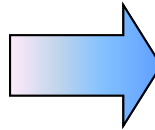
# Transforming Loop-Free Programs Into Equations (1)

---

Easy to transform when every variable is only assigned once!

## Program

```
x = a;  
y = x + 1;  
z = y - 1;
```



## Constraints

```
x = a &&  
y = x + 1 &&  
z = y - 1 &&
```

## Transforming Loop-Free Programs Into Equations (2)

When a variable is assigned multiple times,  
use a new variable for the RHS of each assignment

### Program

```
x=x+y;  
x=x*2;  
a[i]=100;
```



### SSA Program

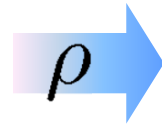
```
x1=x0+y0;  
x2=x1*2;  
a1[i0]=100;
```

# What about conditionals?

## Program

```
if (v)
  x = y;
else
  x = z;

w = x;
```



## SSA Program

```
if (v0)
  x0 = y0;
else
  x1 = z0;

w1 = x??;
```

What should 'x' be?



# What about conditionals?

## Program

```
if (v)
  x = y;
else
  x = z;

w = x;
```



## SSA Program

```
if (v0)
  x0 = y0;
else
  x1 = z0;
x2 = v0 ? x0 : x1;
w1 = x2
```

For each join point, add new variables with selectors

# Encoding

- Declare symbolic variables for each (SSA) scalar variables
- Assignments to equivalence
- Phi functions to ITE expressions
- Array accesses to select/store operations
- Scalar pointer dereferences to identify operations
- Heap dereferences to select/store operations

```
if (v)
    p = &x;
else
    p = &y;

*p = 10;
q=p;
z=*q
```

```
p =(int*) malloc(100);
i = 10;
q = p+i
*q = 10
```

# CBMC: C Bounded Model Checker

---

- Developed at CMU by Daniel Kroening et al.
- Available at:  
<http://www.cs.cmu.edu/~modelcheck/cbmc/>
- Supported platforms: Windows (requires VisualStudio's CL), Linux
- Provides a command line and Eclipse-based interfaces
- Known to scale to programs with over 30K LOC
- Was used to find previously unknown bugs in MS Windows device drivers

# Explicit State Model Checking

---

- The program is indeed executing
  - `jpf <your class> <parameters>`
    - Very similar to "java <your class> <parameters>"
  - Execute in a way that all possible scenarios are explored
    - Thread interleaving
    - Undeterministic values (random values)
  - Concrete input is provided
  - A state is indeed a concrete state, consisting of
    - Concrete values in heap/stack memory

# An Example

```
import java.util.Random;

public class Rand {
    public static void main (String[] args) {
        Random random = new Random(42);           // (1)

        int a = random.nextInt(2);               // (2)
        System.out.println("a=" + a);

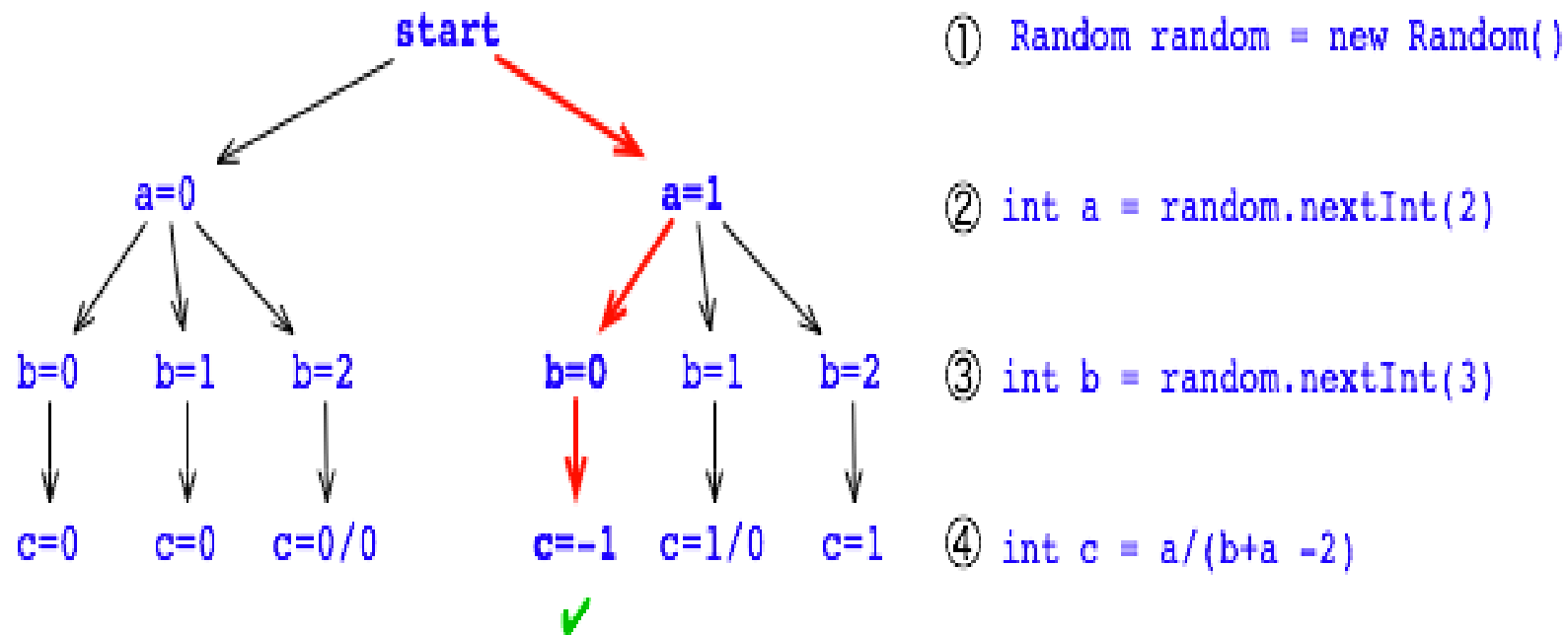
        //... lots of code here

        int b = random.nextInt(3);               // (3)
        System.out.println("  b=" + b);

        int c = a/(b+a -2);                       // (4)
        System.out.println("    c=" + c);
    }
}
```

```
> java Rand
a=1
  b=0
    c=-1
>
```

# An Example (cont.)



- One execution corresponds to one path.

```
> bin/jpf Rand
```

```
JavaPathfinder v4.1 - (C) 1999-2007 RIACS/NASA Ames Research Center
```

```
===== system under test
```

```
application: /Users/pcmehlitz/tmp/Rand.java
```

```
===== search started: 5/23/07 11:48 PM
```

```
a=1
```

```
  b=0
```

```
    c=-1
```

```
===== results
```

```
no errors detected
```

```
===== search finished: 5/23/07 11:48 PM
```

```
>
```

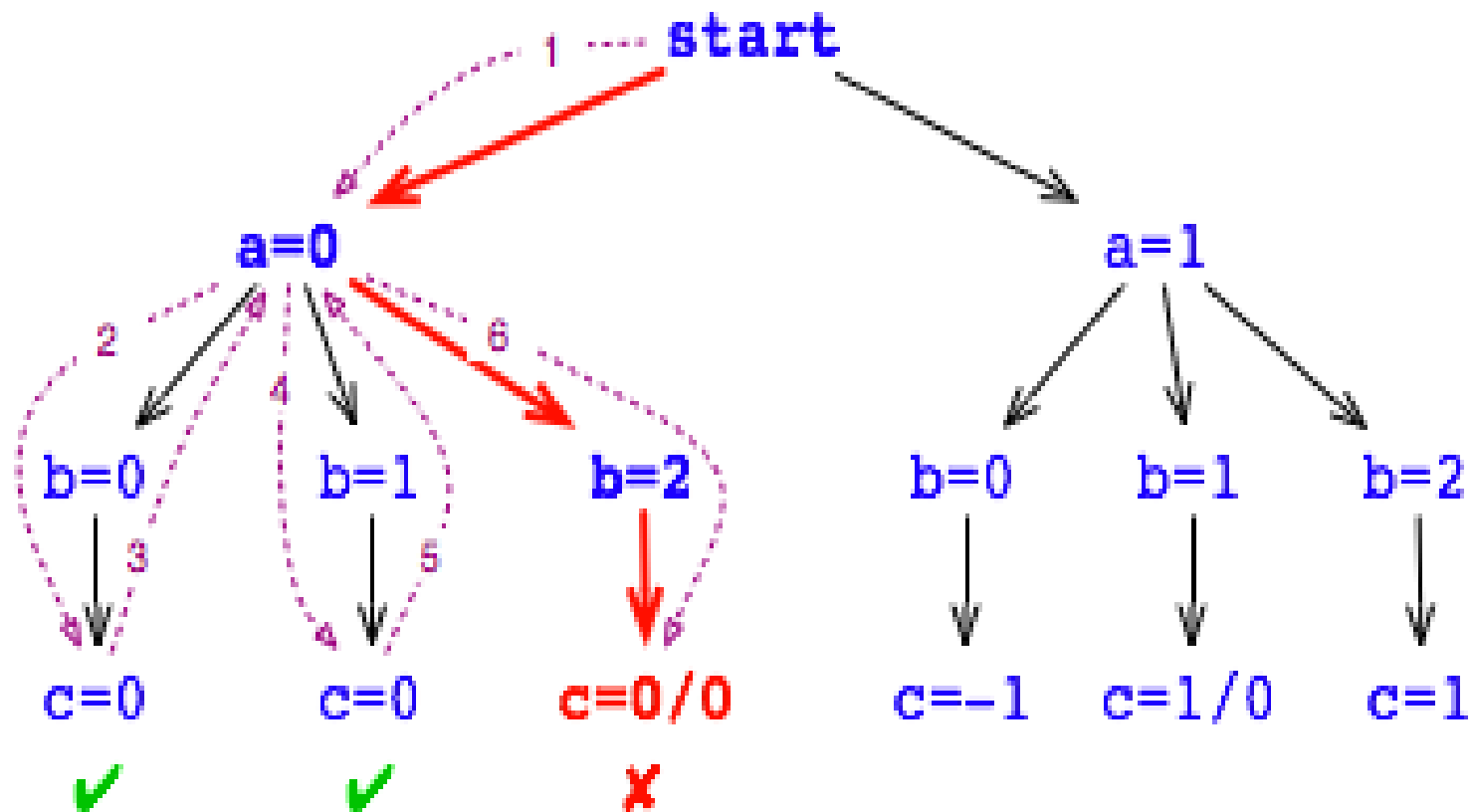
```
> bin/jpf +vm.enumerate_random=true Rand
JavaPathfinder v4.1 - (C) 1999-2007 RIACS/NASA Ames Research Center
===== system under test
application: /Users/pcmehlitz/tmp/Rand.java

===== search started: 5/23/07 11:49 PM
a=0
  b=0
    c=0
  b=1
    c=0
  b=2

===== error #1
gov.nasa.jpjf.jvm.NoUncaughtExceptionsProperty
java.lang.ArithmeticException: division by zero
    at Rand.main(Rand.java:15)

....
>
```





- JPF explores multiple possible executions GIVEN THE SAME CONCRETE INPUT

# Two Essential Capabilities

---

## ● Backtracking

- Means that JPF can restore previous execution states, to see if there are unexplored choices left.
  - While this is theoretically can be achieved by re-executing the program from the beginning, backtracking is a much more efficient mechanism if state storage is optimized.

## ● State matching

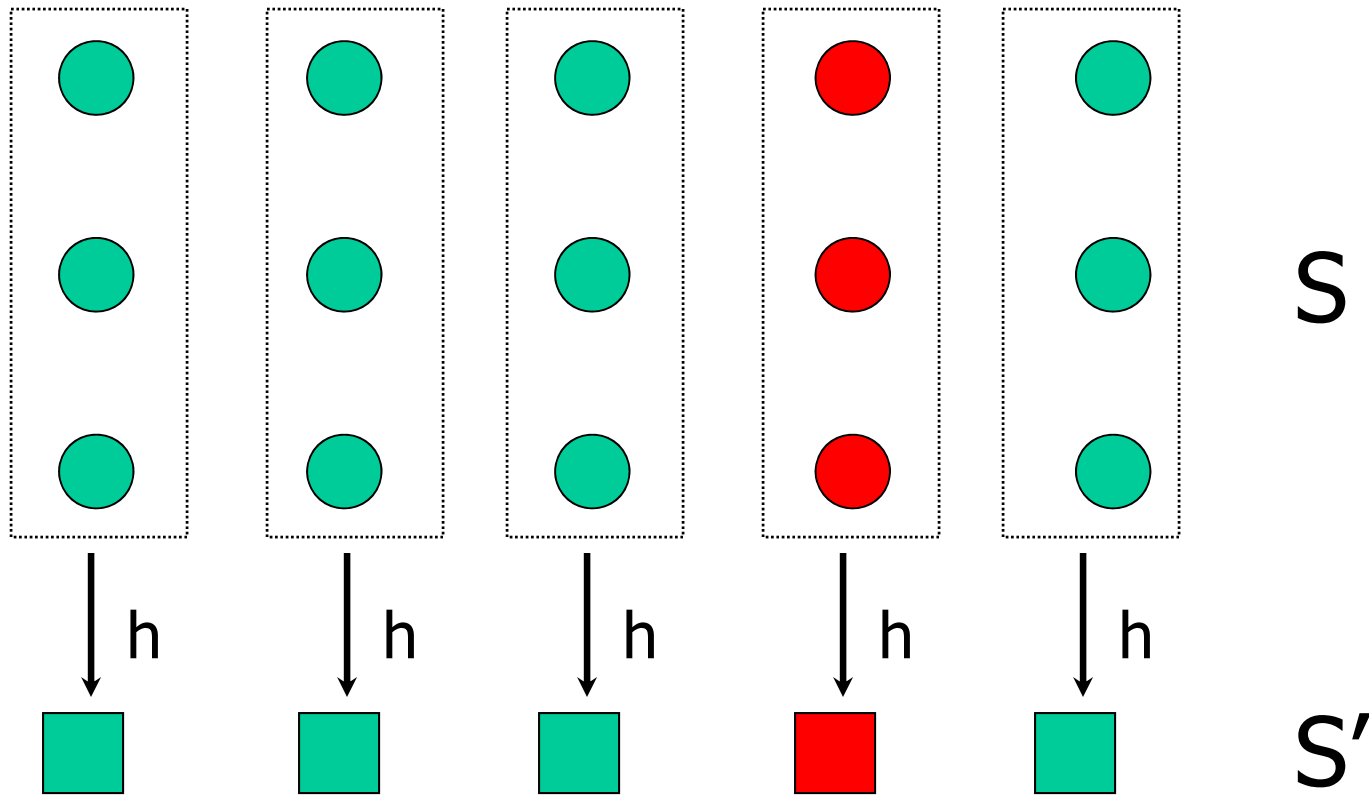
- JPF checks every new state if it already has seen an equal one, in which case there is no use to continue along the current execution path, and JPF can backtrack to the nearest non-explored non-deterministic choice
  - Heap and thread-stack snapshots.

# State Abstraction

---

- Eliminate details irrelevant to the property
- Obtain simple finite models sufficient to verify the property
- Disadvantage
  - Loss of Precision: False positives/negatives

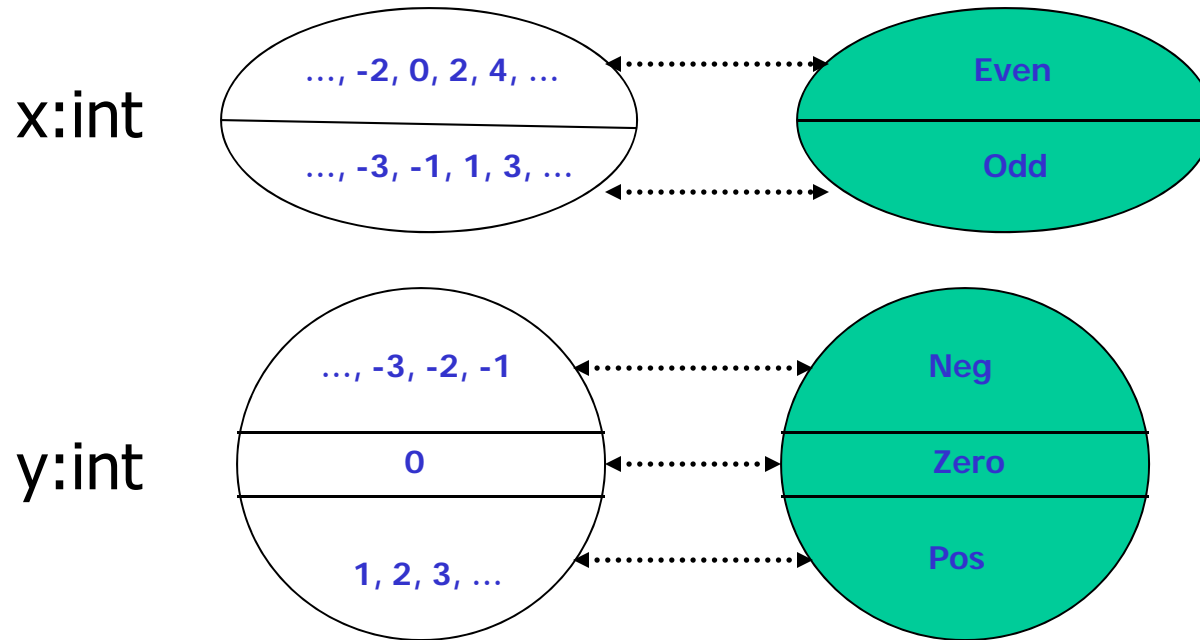
# Data Abstraction



Abstraction Function  $h$  : from  $S$  to  $S'$

# Data Abstraction Example

- Abstraction proceeds component-wise, where variables are components



# How do we Abstract Behaviors?

---

- Abstract domain  $A$ 
  - Abstract concrete values to those in  $A$
- Then compute transitions in the abstract domain

# Data Type Abstraction

Code

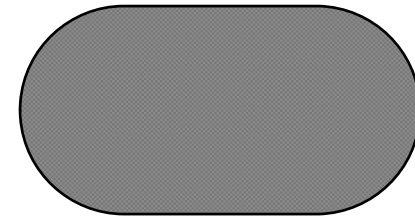
```
int x = 0;  
if (x == 0)  
    x = x + 1;
```



```
Si gns x = ZERO;  
if (Si gns. eq(x, ZERO))  
    x = Si gns. add(x, POS);
```

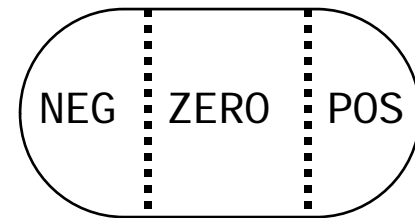
Abstract Data domain

int



(n < 0) : NEG  
(n == 0) : ZERO  
(n > 0) : POS

Si gns



# Existential/Universal Abstractions

---

## ● Existential

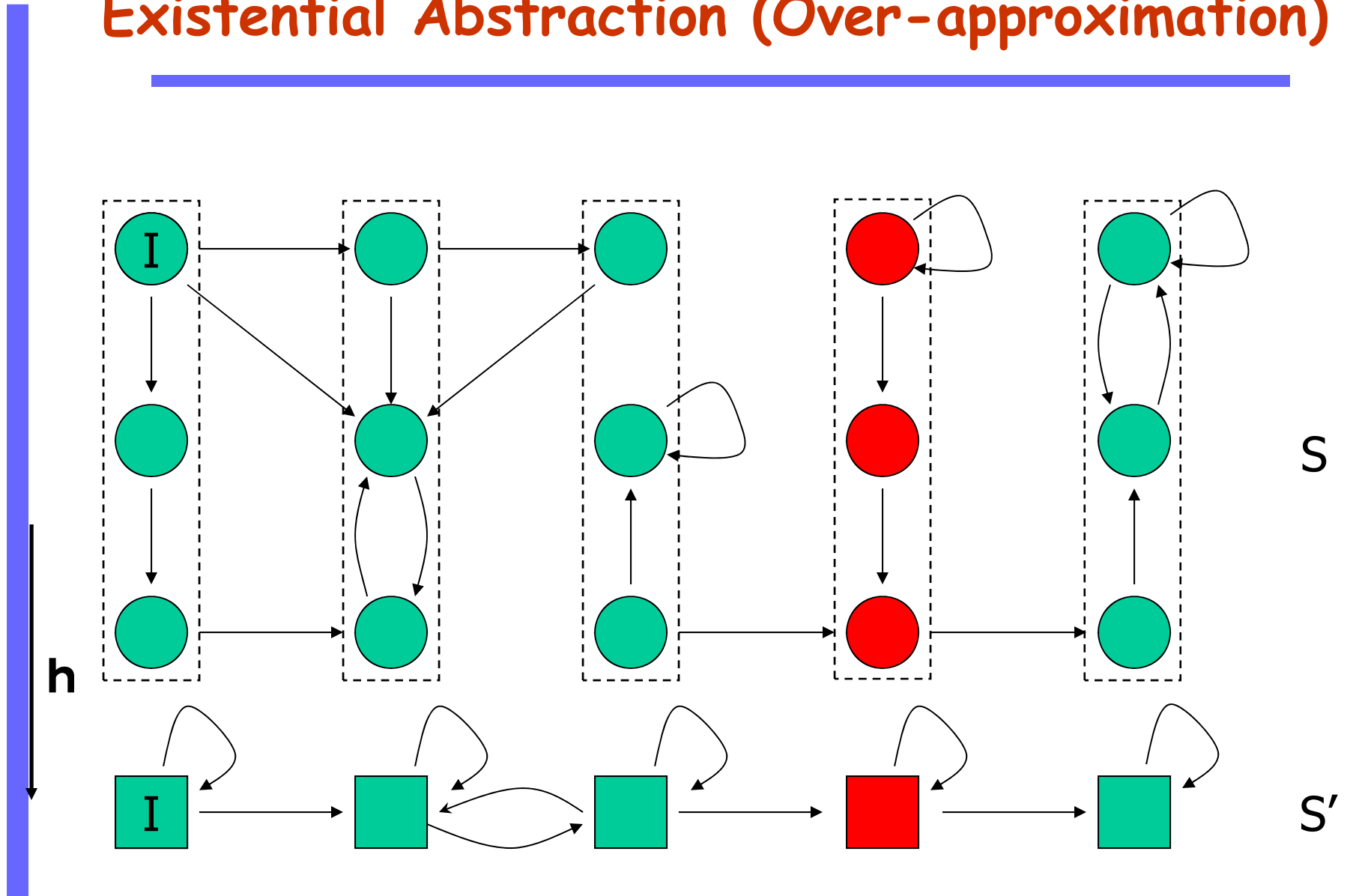
- Make a transition from an abstract state if **at least one** corresponding concrete state has the transition.
- Abstract model  $M'$  simulates concrete model  $M$

## ● Universal

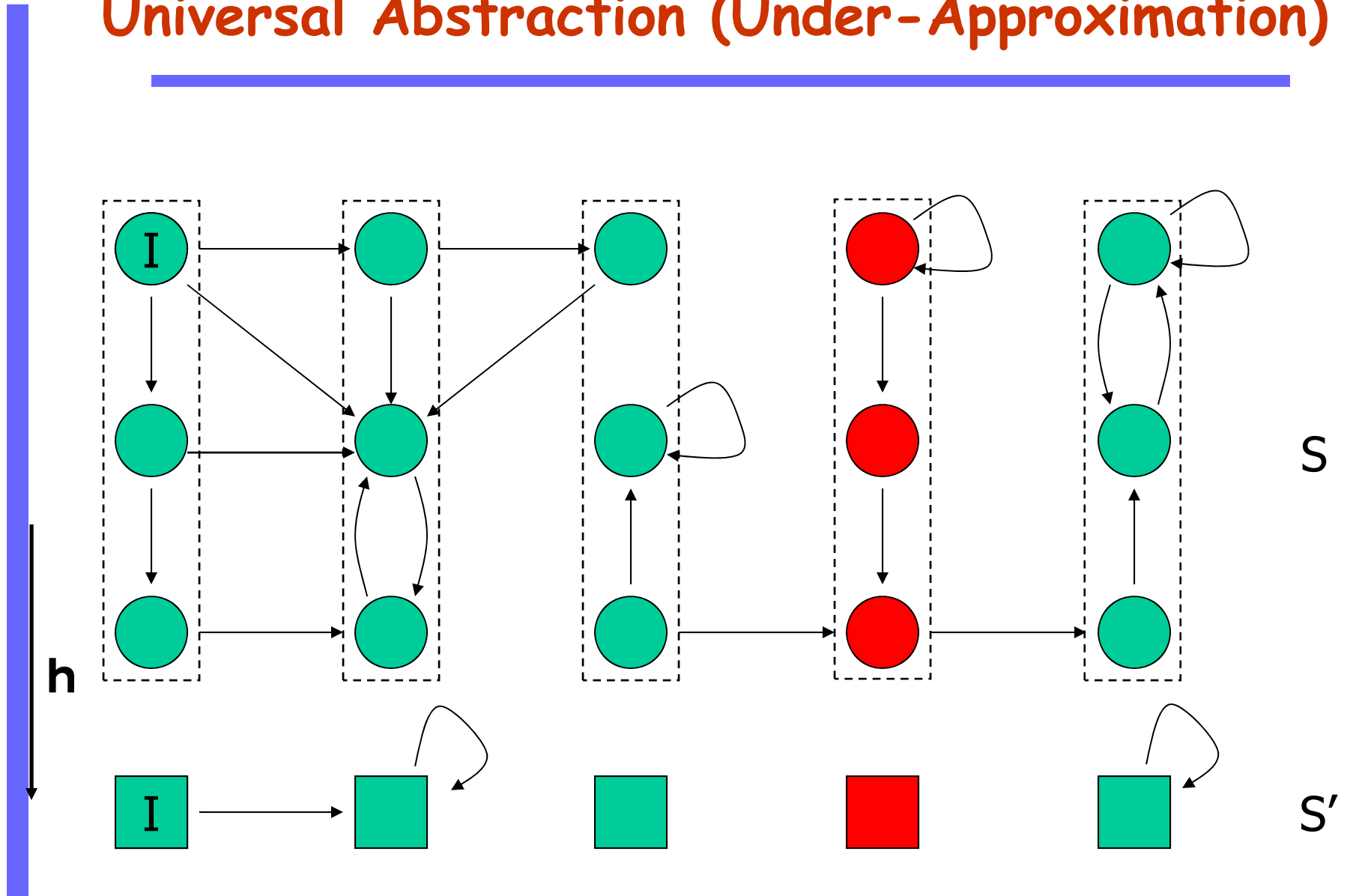
- Make a transition from an abstract state if **all** the corresponding concrete states have the transition.



# Existential Abstraction (Over-approximation)



# Universal Abstraction (Under-Approximation)



# Guarantees from Abstraction

---

Assume  $M'$  is an abstraction of  $M$

- Strong Preservation:
  - $P$  holds in  $M'$  iff  $P$  holds in  $M$
- Weak Preservation:
  - $P$  holds in  $M'$  implies  $P$  holds in  $M$

# Guarantees from Exist. Abstraction

- ◆ Let  $\varphi$  be a *hold-for-all-paths* property
- ◆  $M'$  existentially abstracts  $M$

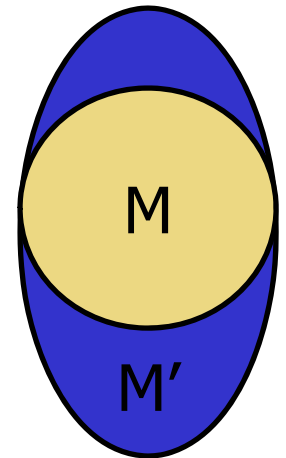
- ◆ Preservation Theorem

$$M' \models \varphi \rightarrow M \models \varphi$$

- ◆ Converse does not hold

$$M' \not\models \varphi \not\rightarrow M \not\models \varphi$$

- ◆  $M' \not\models \varphi$  : counterexample may be spurious



# Guarantees from Univ. Abstraction

◆ Let  $\varphi$  be a existential-quantified property and  $M$  simulates  $M'$

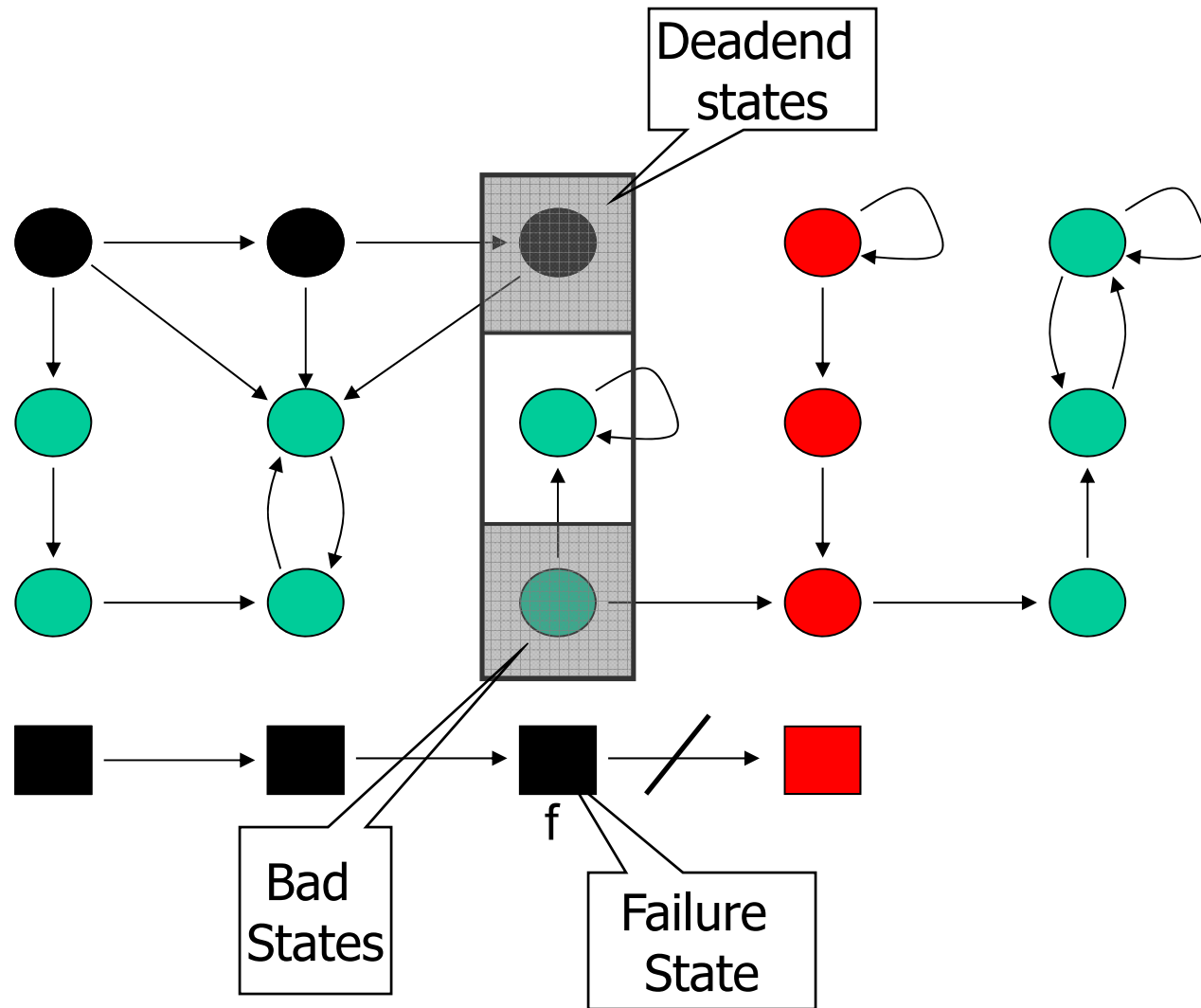
● Preservation Theorem

$$M' \models \varphi \rightarrow M \models \varphi$$

◆ Converse does not hold

$$M \models \varphi \not\rightarrow M' \models \varphi$$

# Spurious counterexample in Over-approximation

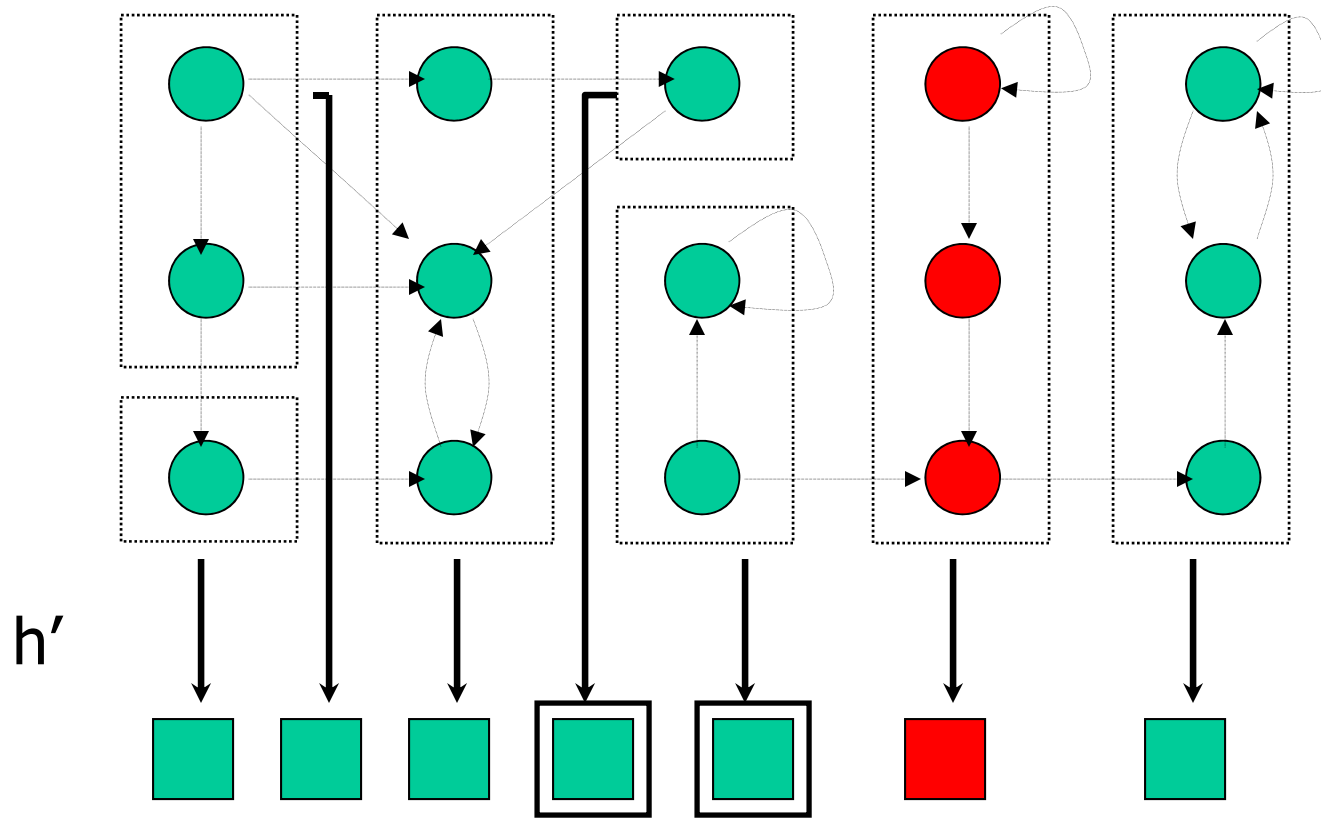


# Refinement

---

- **Problem:** Deadend and Bad States are in the same abstract state.
- **Solution:** Refine abstraction function.
- The sets of Deadend and Bad states should be separated into different abstract states.

# Refinement



$h'$

Refinement :  $h'$

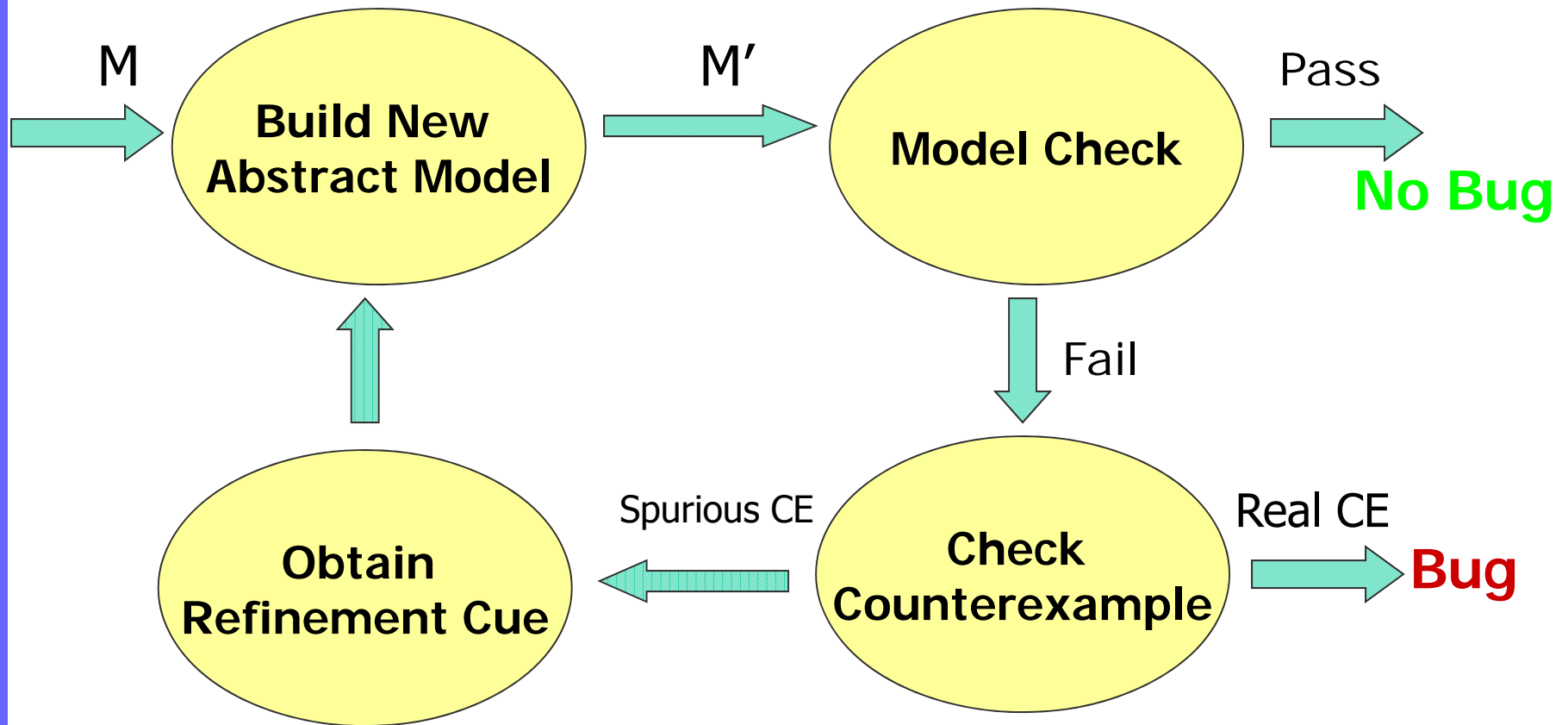


# Automated Abstraction/Refinement

---

- Good abstractions are hard to obtain
  - Automate both Abstraction and Refinement processes
- Counterexample-Guided AR (CEGAR)
  - Build an abstract model  $M'$
  - Model check property  $P$ ,  $M' \models P$ ?
  - If  $M' \models P$ , then  $M \models P$  by Preservation Theorem
  - Otherwise, check if Counterexample (CE) is spurious
  - Refine abstract state space using CE analysis results
  - Repeat

# Counterexample-Guided Abstraction-Refinement (CEGAR)



# Predicate Abstraction

---

- Extract a finite state model from an infinite state system
- Used to prove assertions or safety properties
- Successfully applied for verification of C programs
  - SLAM (used in windows device driver verification)
  - MAGIC, BLAST, F-Soft

# Example for Predicate Abstraction

```
int main() {  
  int i;  
  
  i=0;  
  
  while(even(i))  
    i++;  
}
```

**C program**

+

$p_1 \Leftrightarrow i=0$   
 $p_2 \Leftrightarrow \text{even}(i)$

=

```
void main() {  
  bool p1, p2;  
  
  p1=TRUE;  
  p2=TRUE;  
  
  while(p2)  
  {  
    p1=p1?FALSE:nondet();  
    p2=!p2;  
  }  
}
```

**Boolean program**

[Graf, Saidi '97]

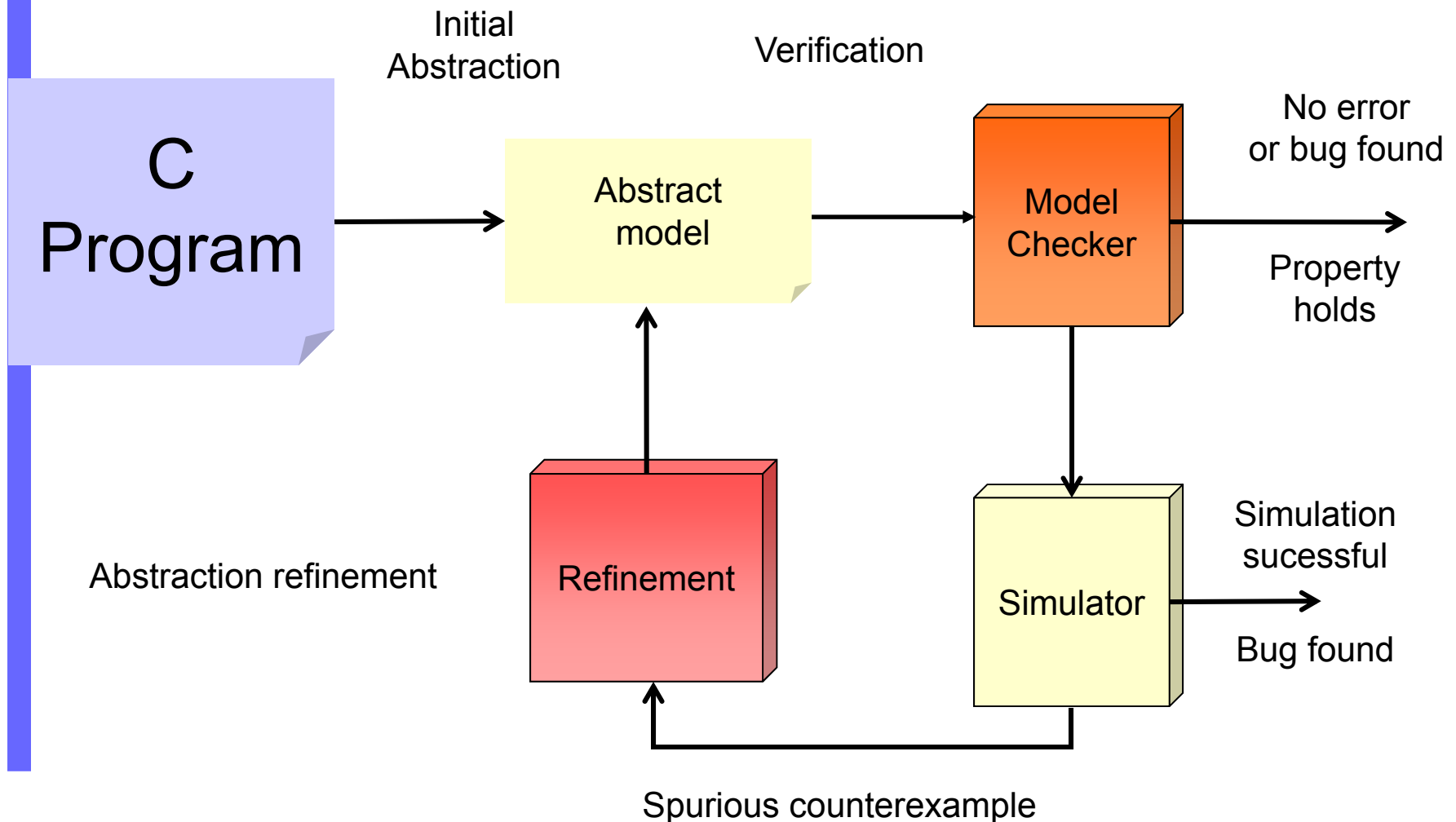
[Ball, Rajamani '01]

# Computing Predicate Abstraction

---

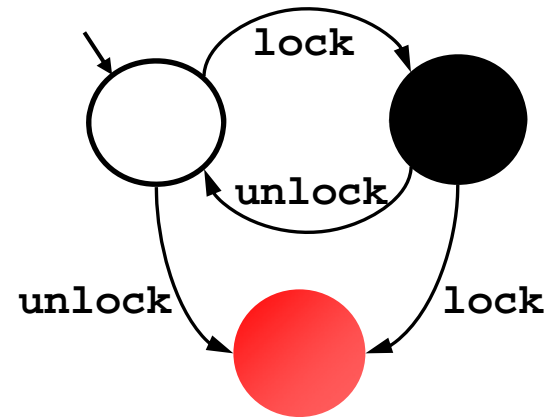
- How to get predicates for checking a given property?
- How do we compute the abstraction?
- Predicate Abstraction is an over-approximation
  - How to refine coarse abstractions

# Counterexample Guided Abstraction Refinement loop

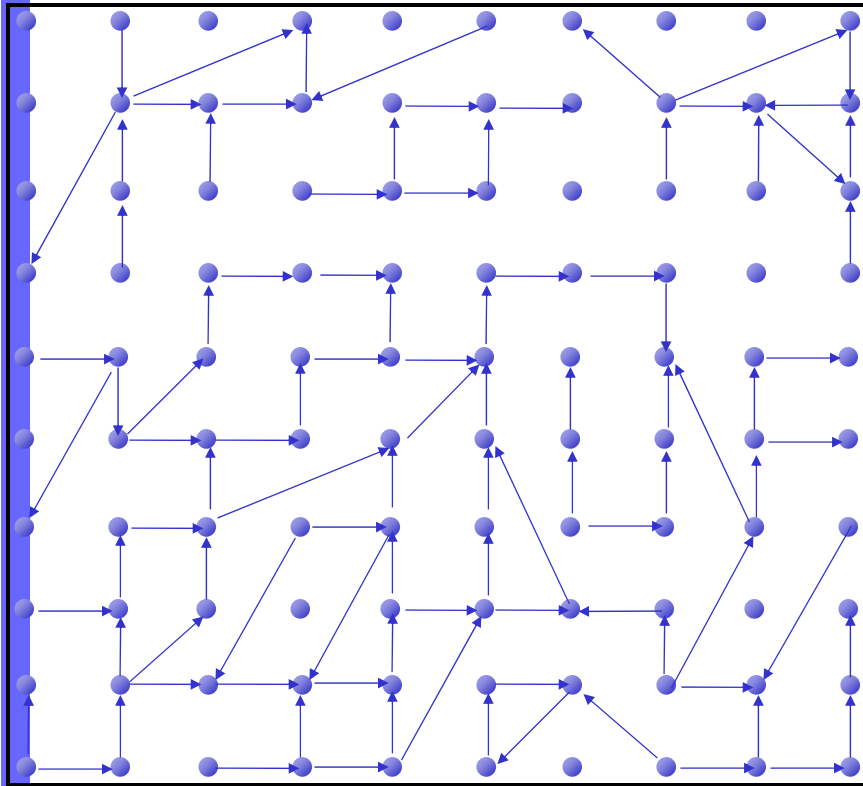


# Example

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:    if (q != NULL){  
3:        q->data = new;  
        unlock();  
        new ++;  
    }  
4: } while(new != old);  
5: unlock ();  
    return;  
}
```



# What a program really is...



State



Transition



*pc*  $\mapsto$  3  
*lock*  $\mapsto$  ●  
*old*  $\mapsto$  5  
*new*  $\mapsto$  5  
*q*  $\mapsto$  0x133a

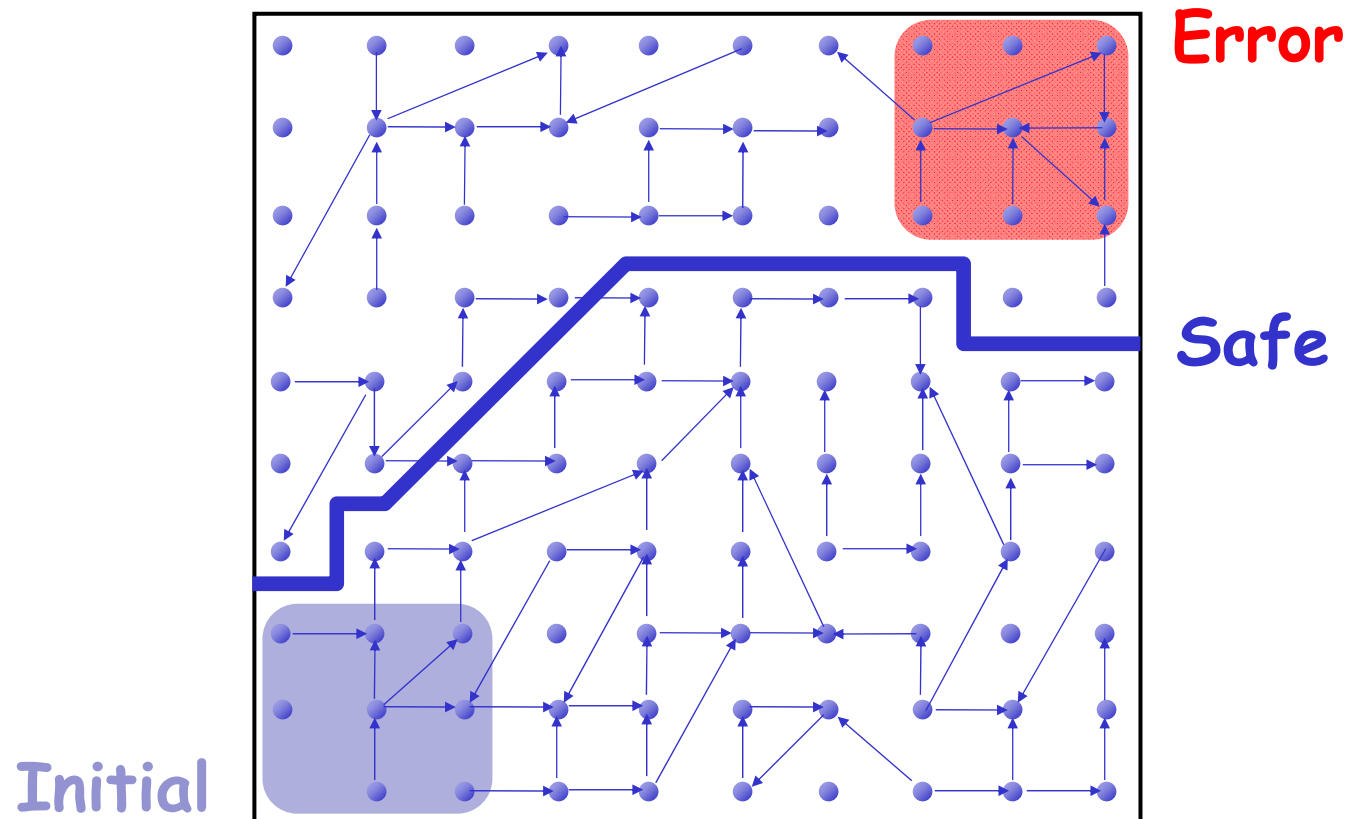
```
3: unlock();  
   new++;  
4: } ...
```

*pc*  $\mapsto$  4  
*lock*  $\mapsto$  ○  
*old*  $\mapsto$  5  
*new*  $\mapsto$  6  
*q*  $\mapsto$  0x133a

```
Example ( ) {  
1: do{  
   lock();  
   old = new;  
   q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: } while(new != old);  
5: unlock ();  
   return;}
```



# The Safety Verification Problem

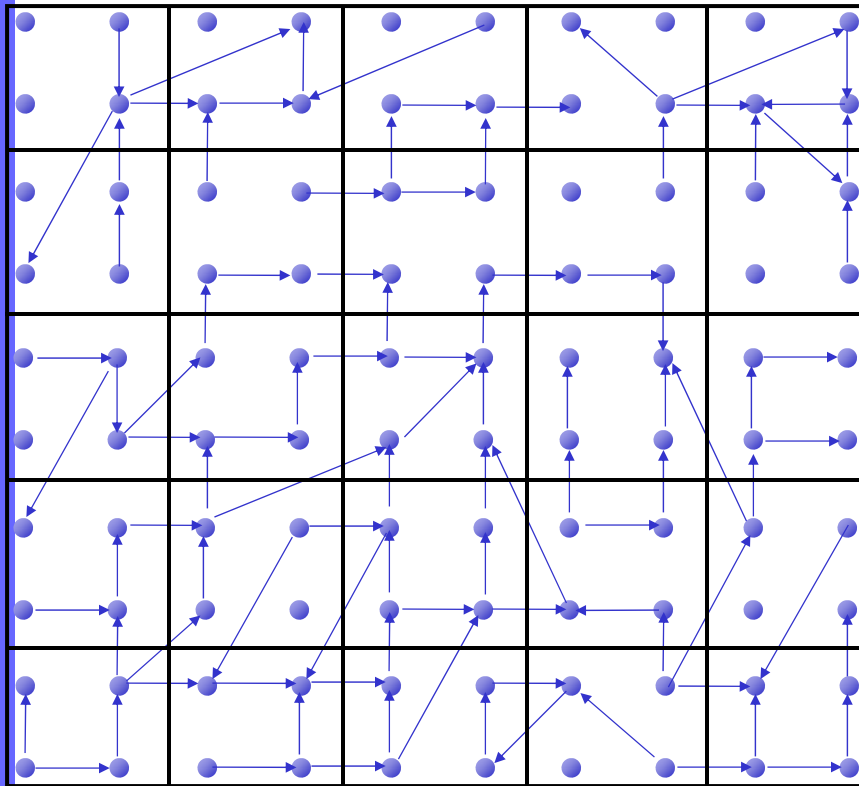


Is there a path from an initial to an error state ?

**Problem:** Infinite state graph

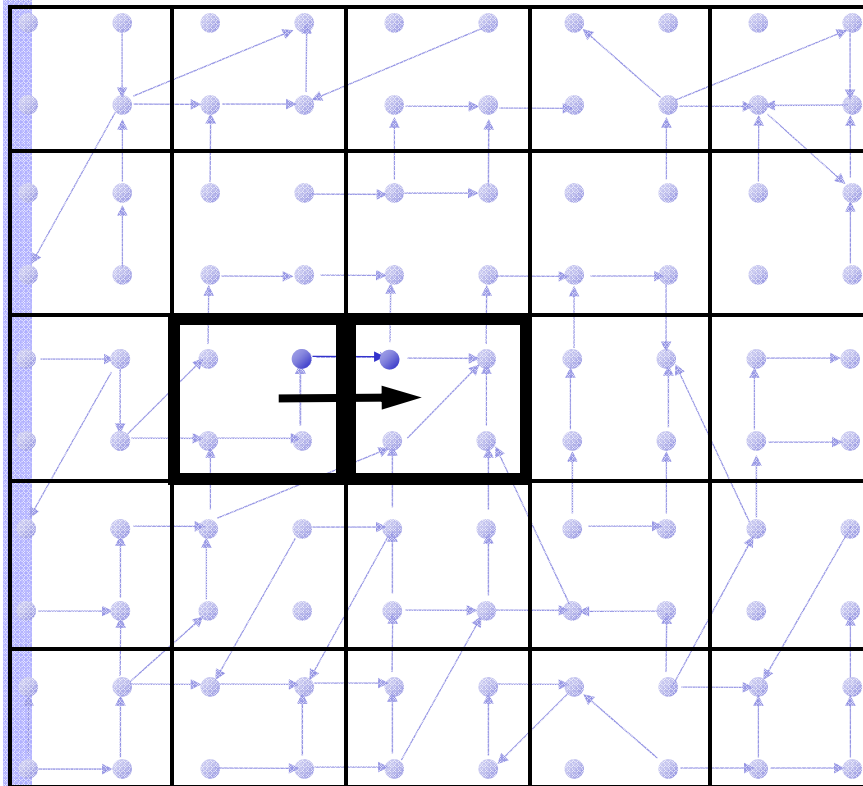
**Solution:** Set of states ' logical formula

# Idea 1: Predicate Abstraction

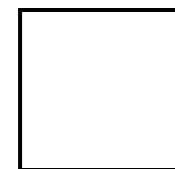
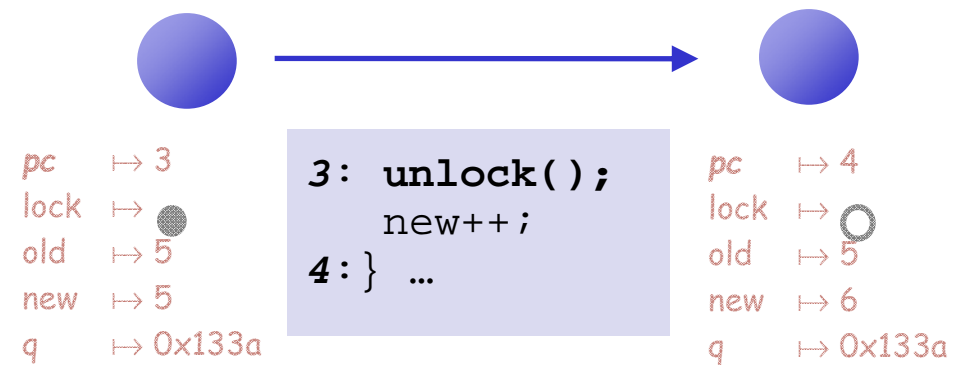


- Predicates on program state:  
*lock*  
*old = new*
- States satisfying same predicates are equivalent
  - Merged into one abstract state
- #abstract states is finite

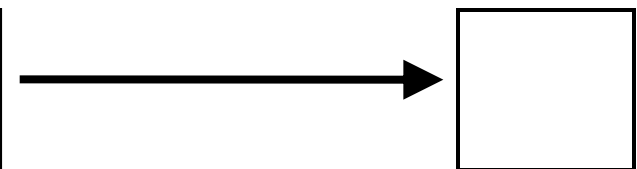
# Abstract States and Transitions



## State

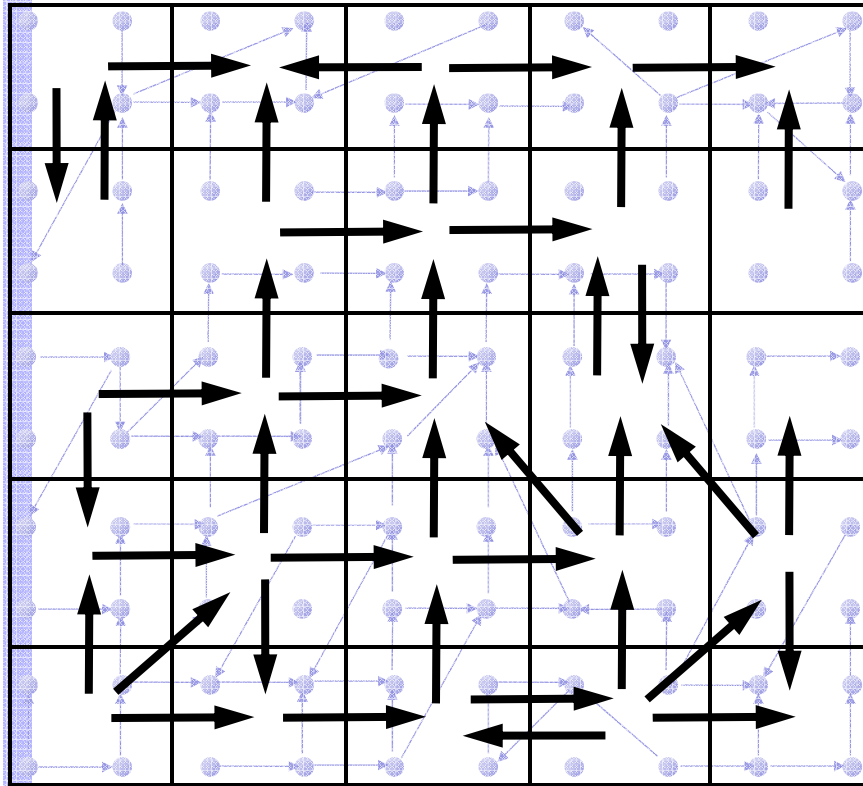


*lock*  
*old=new*



**!** *lock*  
**!** *old=new*

# Abstraction



Existential Approximation

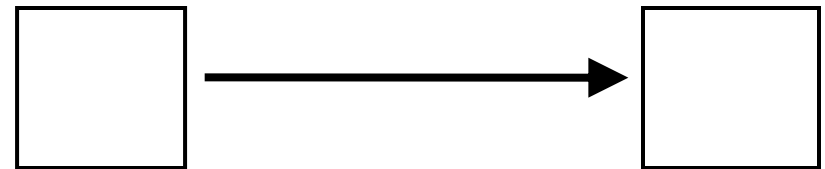
## State



*pc*  $\mapsto$  3  
*lock*  $\mapsto$  ●  
*old*  $\mapsto$  5  
*new*  $\mapsto$  5  
*q*  $\mapsto$  0x133a

```
3: unlock();  
   new++;  
4: } ...
```

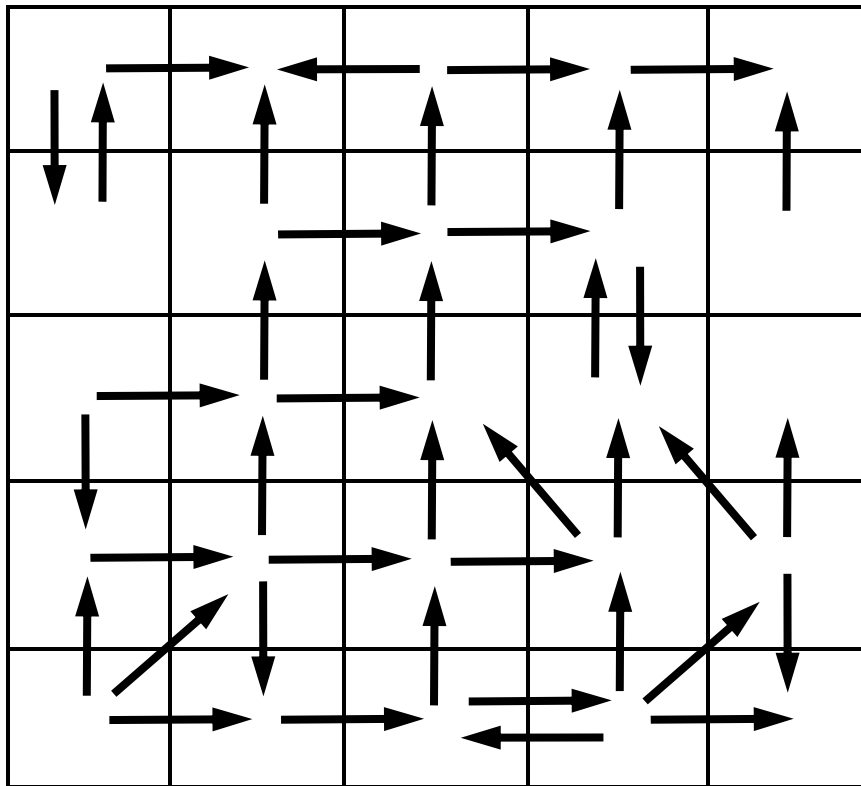
*pc*  $\mapsto$  4  
*lock*  $\mapsto$  ○  
*old*  $\mapsto$  5  
*new*  $\mapsto$  6  
*q*  $\mapsto$  0x133a



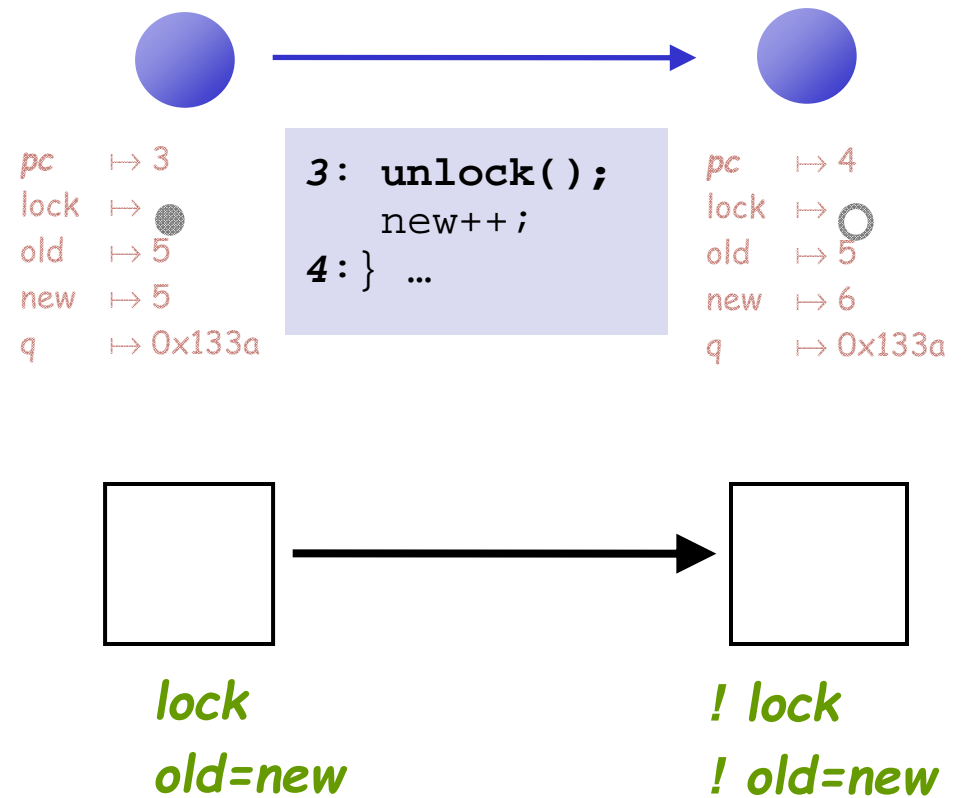
*lock*  
*old=new*

*! lock*  
*! old=new*

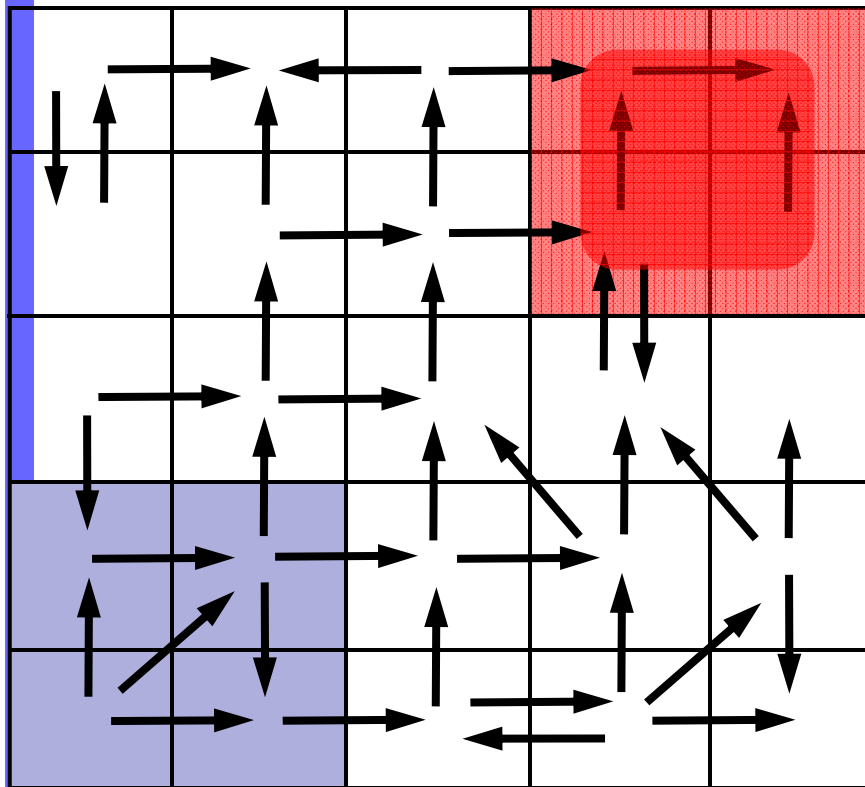
# Abstraction



## State



# Analyze Abstraction



Analyze finite graph

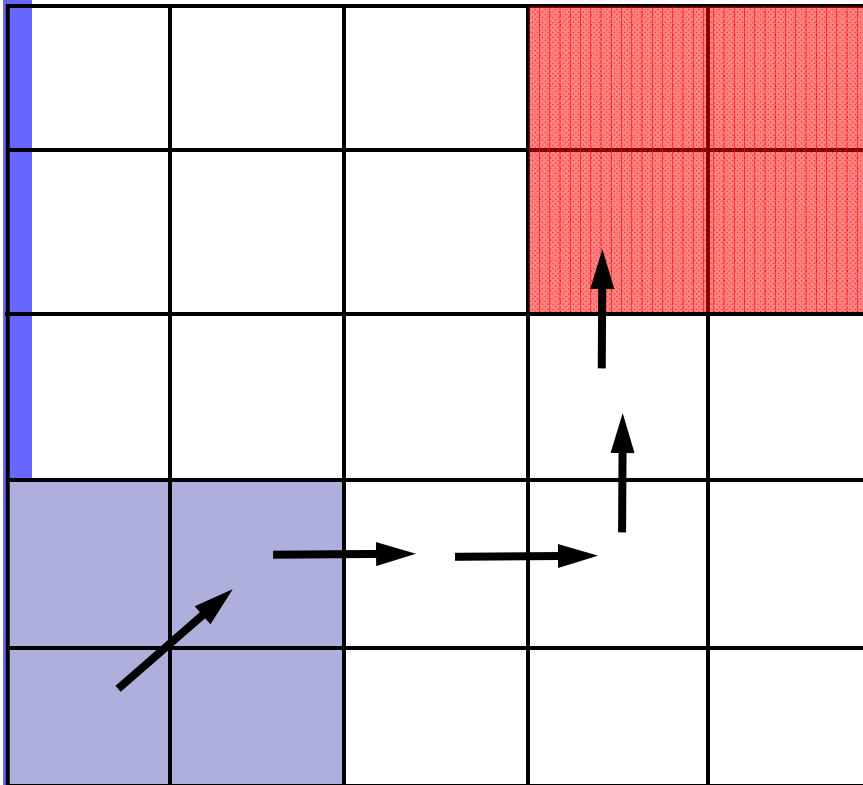
**Over** Approximate:

Safe  $\Rightarrow$  System Safe

**Problem**

Spurious **counterexamples**

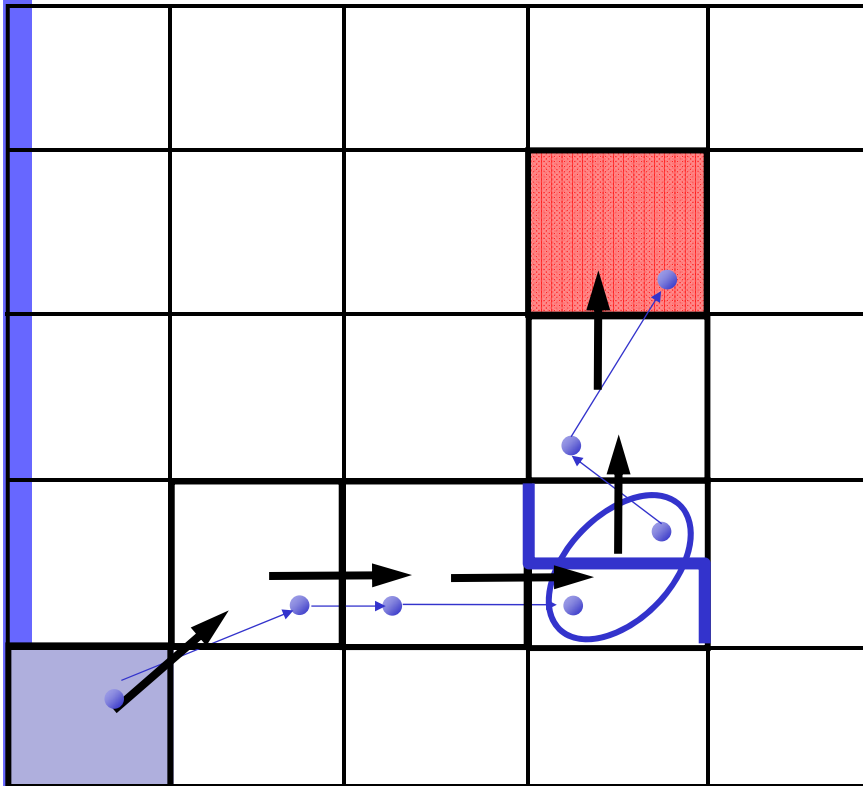
## Idea 2: Counterex.-Guided Refinement



### Solution

Use spurious counterexamples to refine abstraction !

## Idea 2: Counterex.-Guided Refinement



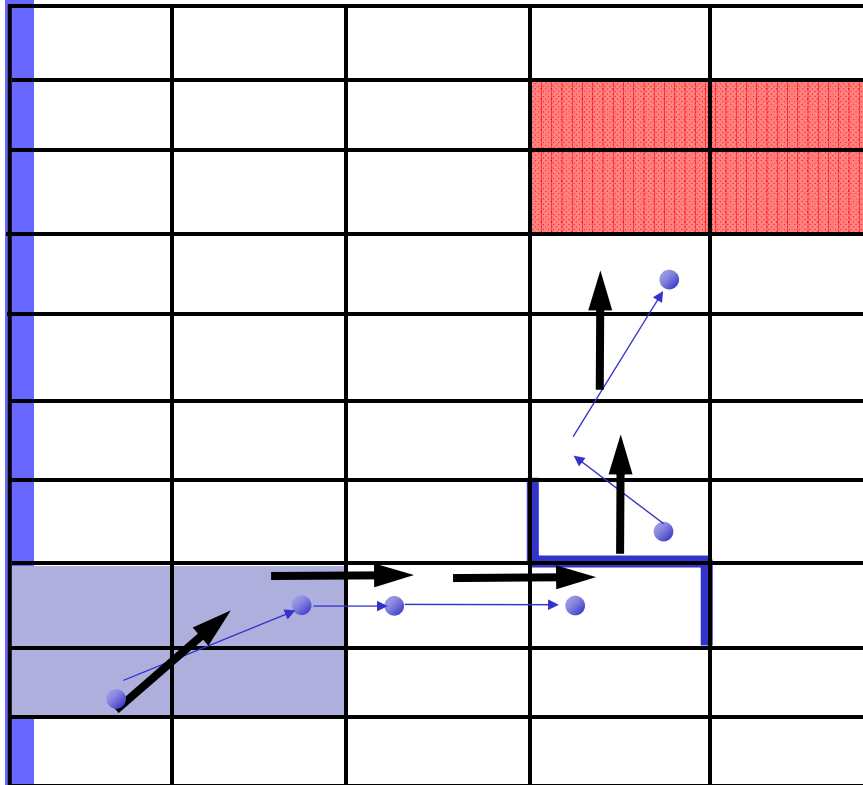
### Solution

Use spurious counterexamples to refine abstraction

1. Add predicates to distinguish states across cut
2. Build refined abstraction



# Iterative Abstraction-Refinement



[Kurshan et al 93] [Clarke et al 00]  
[Ball-Rajamani 01]

## Solution

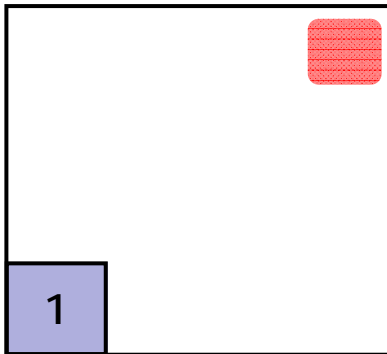
Use spurious counterexamples  
to refine abstraction

1. Add predicates to distinguish states across cut
2. Build refined abstraction  
-eliminates counterexample
3. Repeat search  
Till real counterexample  
or system proved safe

# Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: }while(new != old);  
5: unlock ();  
}
```

1 !LOCK



Predicates: *LOCK*

# Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: }while(new != old);  
5: unlock ();  
}
```

lock()

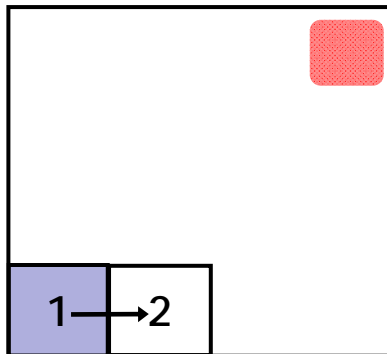
old = new  
q=q->next

1

! LOCK

2

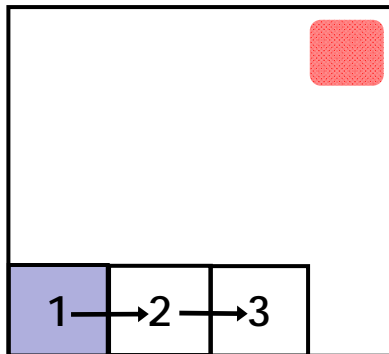
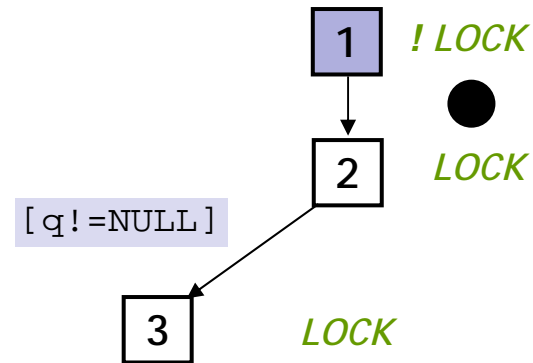
●  
LOCK



Predicates: LOCK

# Build-and-Search

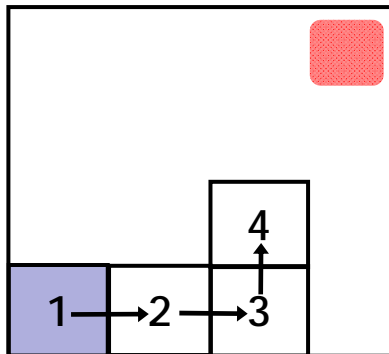
```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
    }  
4: }while(new != old);  
5: unlock ();  
}
```



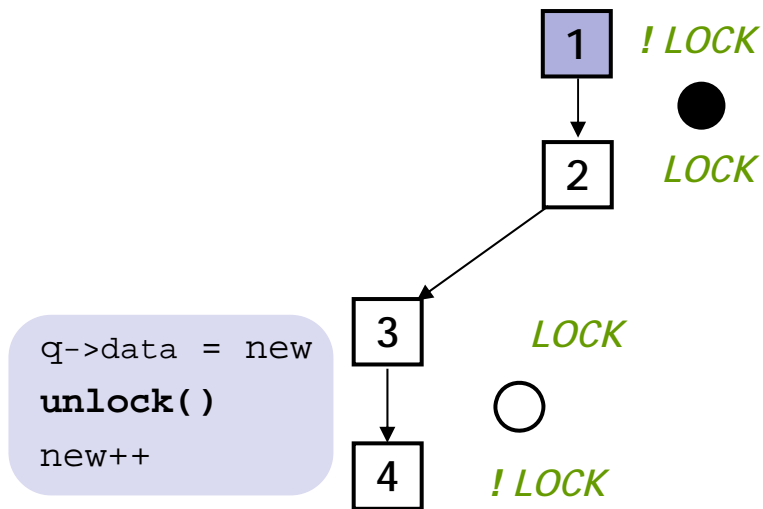
Predicates: **LOCK**

# Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
       unlock();  
       new ++;  
    }  
4: }while(new != old);  
5: unlock ();  
}
```

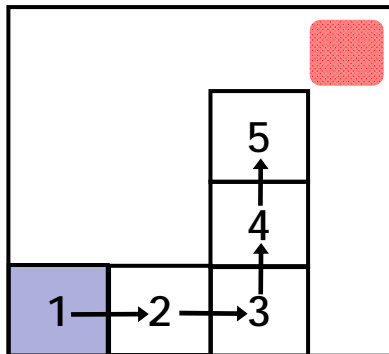


Predicates: *LOCK*

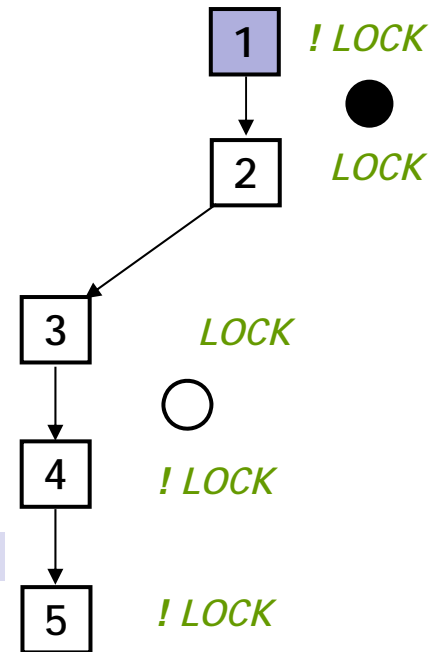


# Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
    }  
4: }while(new != old);  
5: unlock ();  
}
```

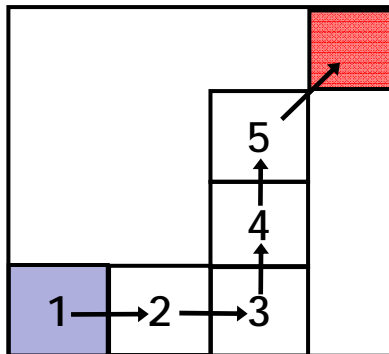


Predicates: *LOCK*

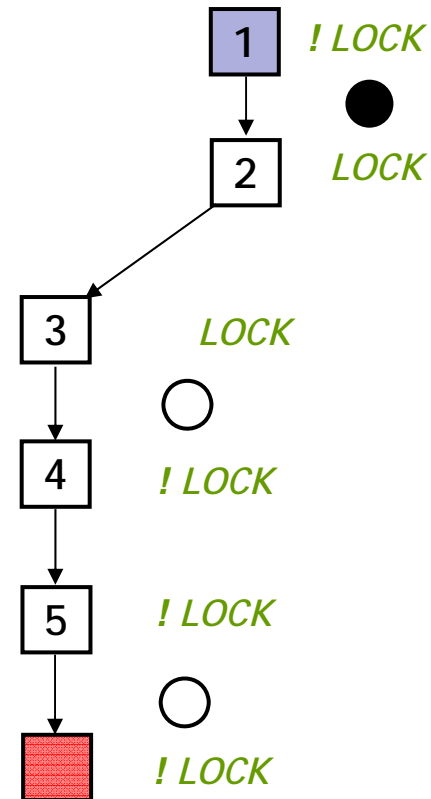


# Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: }while(new != old);  
5: unlock ();  
}
```



Predicates: *LOCK*

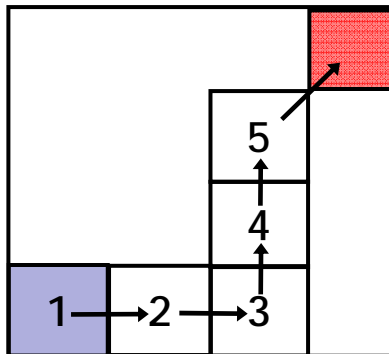


# Analyze Counterexample

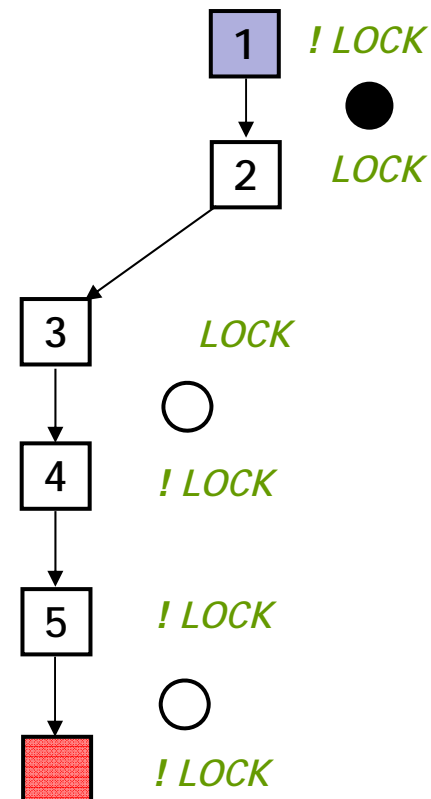
```

Example ( ) {
1: do{
    lock();
    old = new;
    q = q->next;
2:   if (q != NULL){
3:     q->data = new;
        unlock();
        new ++;
    }
4: }while(new != old);
5: unlock ();
}

```



Predicates: *LOCK*



**lock()**  
old = new  
q=q->next

[q!=NULL]

q->data = new  
**unlock()**  
new++

[new==old]

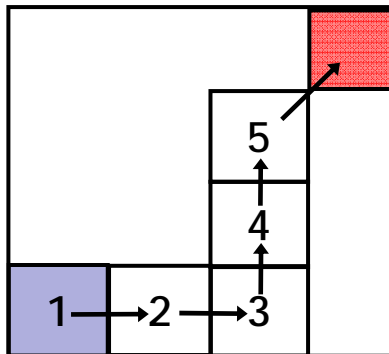
**unlock()**



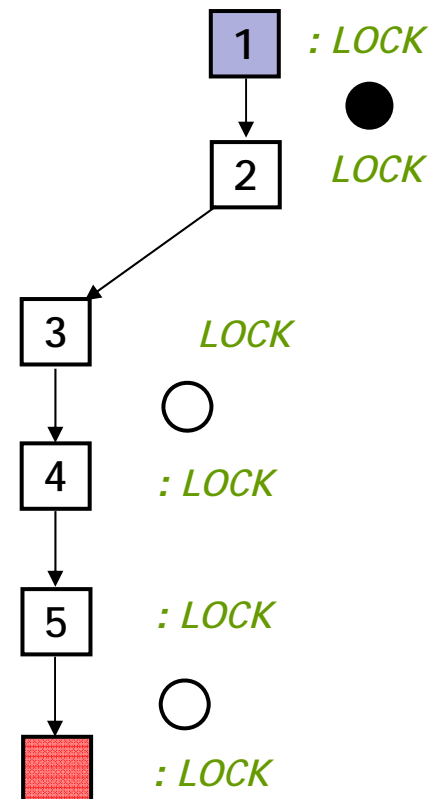
# Analyze Counterexample

```

Example ( ) {
1: do{
    lock();
    old = new;
    q = q->next;
2:   if (q != NULL){
3:     q->data = new;
    unlock();
    new ++;
    }
4: }while(new != old);
5: unlock ();
}
    
```



Predicates: *LOCK*



*old = new*

*new++*

*[new==old]*

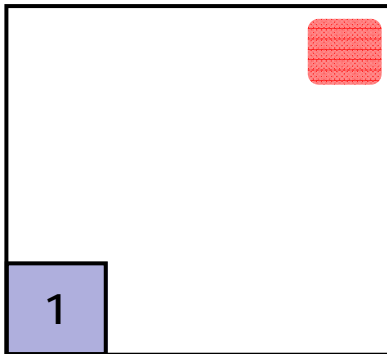
**Inconsistent**

*new == old*

# Repeat Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: }while(new != old);  
5: unlock ();  
}
```

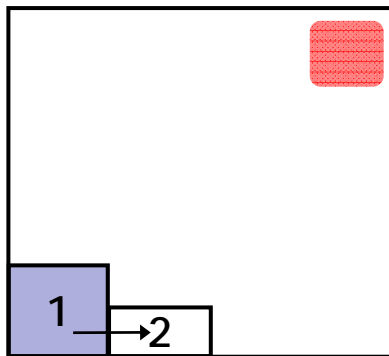
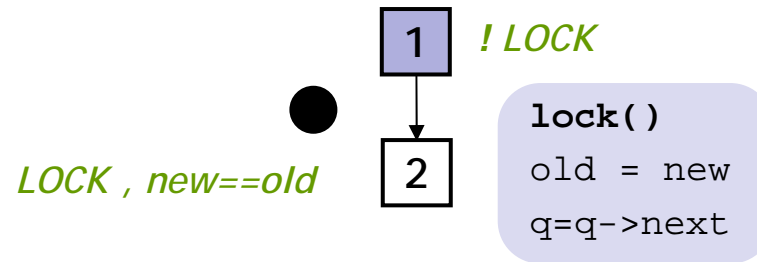
1 : LOCK



Predicates: *LOCK, new==old*

# Repeat Build-and-Search

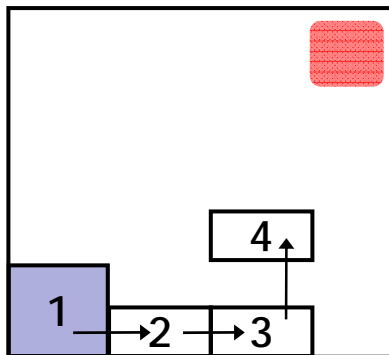
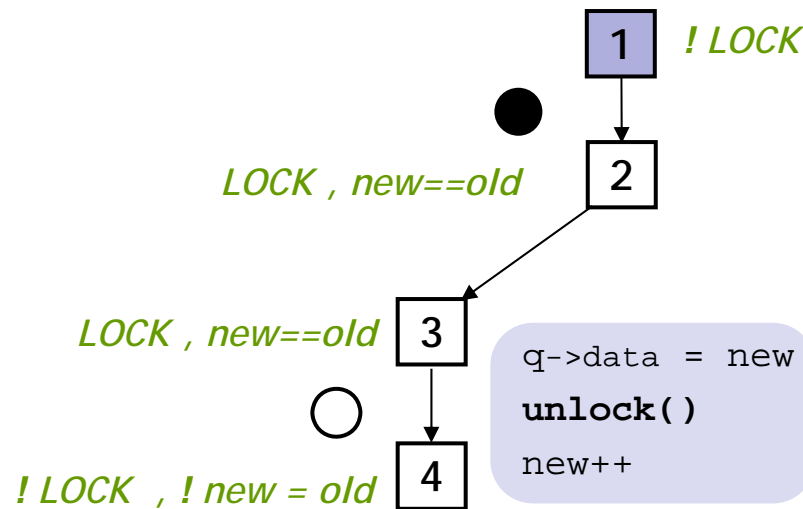
```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: }while(new != old);  
5: unlock ();  
}
```



Predicates: *LOCK, new==old*

# Repeat Build-and-Search

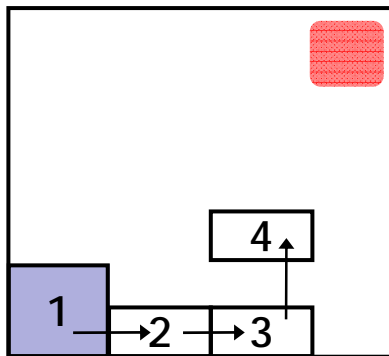
```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
       unlock();  
       new ++;  
    }  
4: }while(new != old);  
5: unlock ();  
}
```



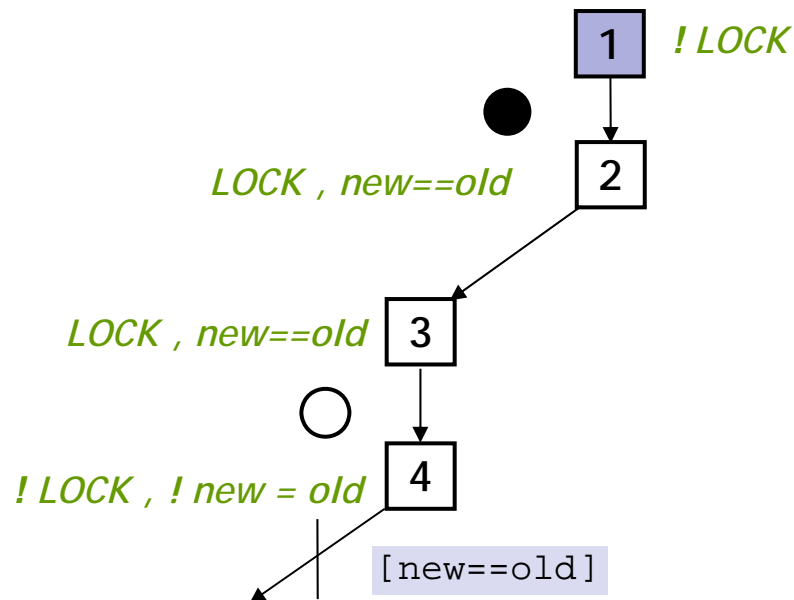
Predicates: *LOCK, new==old*

# Repeat Build-and-Search

```
Example ( ) {  
1: do{  
    lock();  
    old = new;  
    q = q->next;  
2:   if (q != NULL){  
3:     q->data = new;  
     unlock();  
     new ++;  
   }  
4: }while(new != old);  
5: unlock ();  
}
```



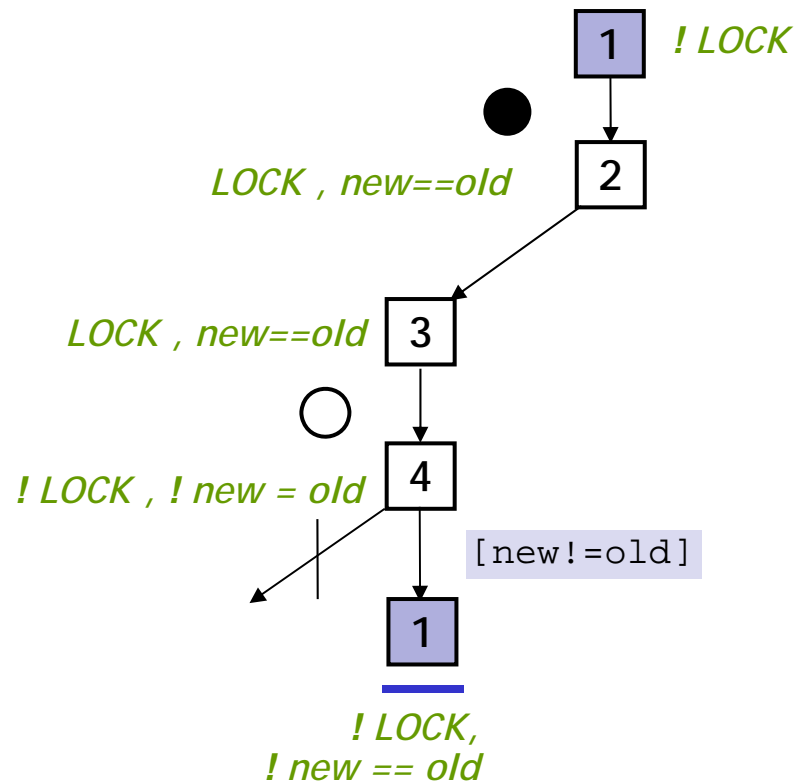
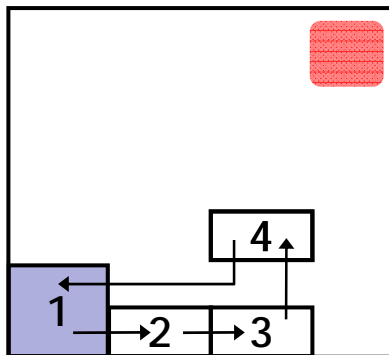
Predicates: *LOCK, new==old*



# Repeat Build-and-Search

```

Example ( ) {
1: do{
    lock();
    old = new;
    q = q->next;
2:   if (q != NULL){
3:     q->data = new;
        unlock();
        new ++;
    }
4: }while(new != old);
5: unlock ();
}
    
```



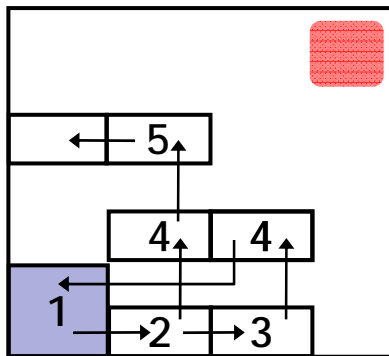
Predicates: *LOCK, new==old*

# Repeat Build-and-Search

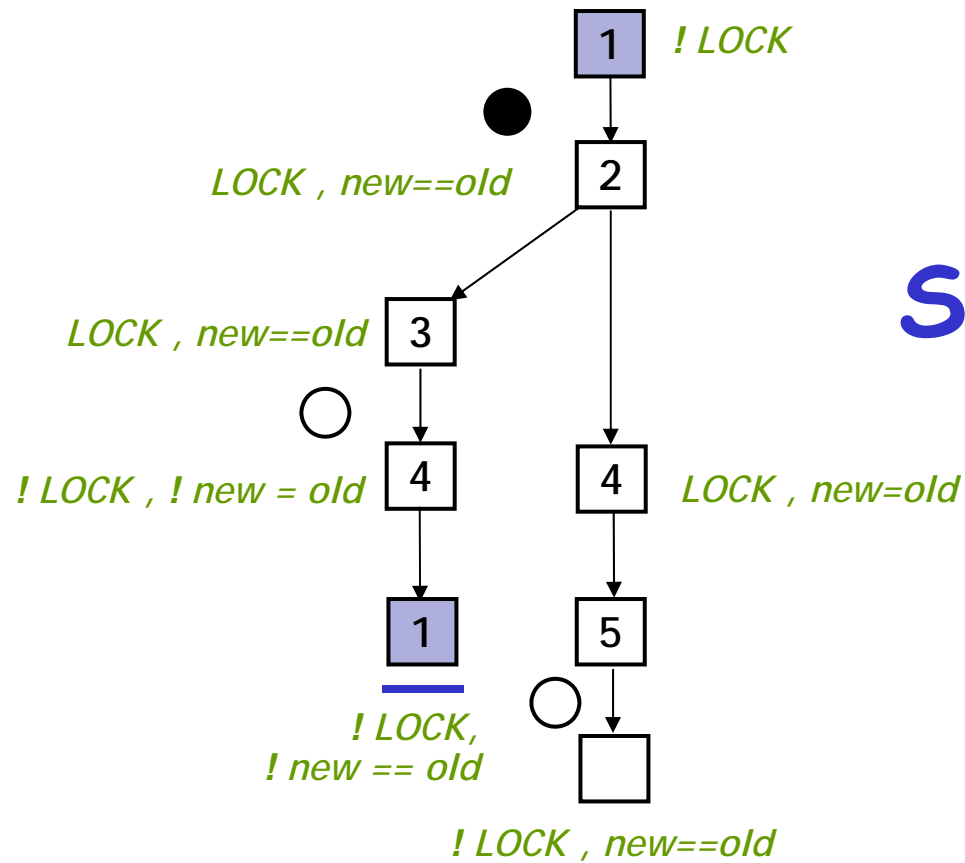
```

Example ( ) {
1: do{
    lock();
    old = new;
    q = q->next;
2:   if (q != NULL){
3:     q->data = new;
    unlock();
    new ++;
  }
4: }while(new != old);
5: unlock ();
}

```



Predicates: *LOCK, new==old*



# Another Example

```
1: x = ctr;  
2: y = ctr + 1;  
3: if (x = i-1){  
4:   if (y != i){  
      ERROR:  
   }  
}
```

**C program**

**Abstract**



```
1: skip;  
2: skip;  
3: if (*){  
4:   if (*){  
      ERROR:  
   }  
}
```

**No predicates  
available currently**



# Checking the abstract model

---

Is ERROR  
reachable?

```
1: skip;  
2: skip;  
3: if (*) {  
4:   if (*) {  
      ERROR:  
   }  
}
```

yes

Abstract  
model has a  
path leading  
to error state

Does this correspond to a real bug?

```
1: skip;  
2: skip;  
3: if (*) {  
4:   if (*) {  
      ERROR:  
   }  
}
```

```
1: x = ctr;  
2: y = ctr + 1;  
3: assume(x == i-1)  
4: assume (y != i)
```

Check using a SAT solver

Not possible

Concrete trace

# Refinement

```
1: x = ctr;  
2: y = ctr + 1;  
3: assume(x == i-1)  
4: assume (y != i)
```

**Spurious Counterexample**

```
1: skip;  
2: skip;  
3: if (*){  
4:   if (*){  
      ERROR:  
   }  
}
```

**Initial abstraction**

# Refinement

```
1: x = ctr;  
2: y = ctr + 1;  
3: assume(x == i-1)  
4: assume (y != i)
```

```
1: skip;  
2: skip;  
3: if (*){  
4:   if (b0){  
      ERROR:  
   }  
}
```

**boolean b0 : y != i**

# Refinement

```
1: x = ctr;  
2: y = ctr + 1;  
3: assume(x == i-1)  
4: assume (y != i)
```

```
1: skip;  
2: skip;  
3: if (b1){  
4:   if (b0){  
      ERROR:  
   }  
}
```

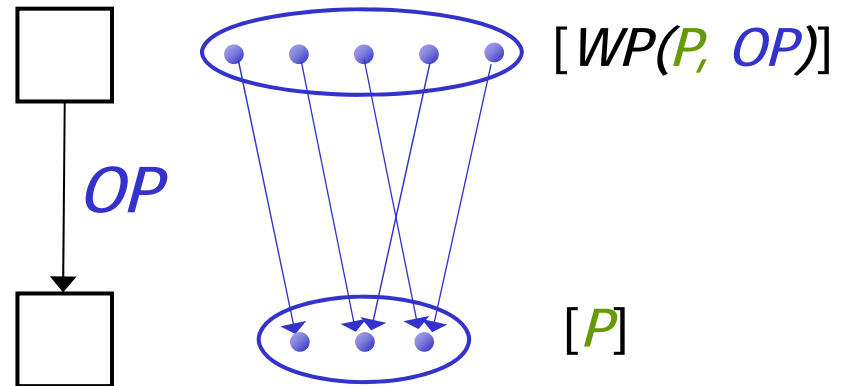
**boolean b0 : y != i**

**boolean b1 : x == i-1**

# Weakest Preconditions

$WP(P, OP)$

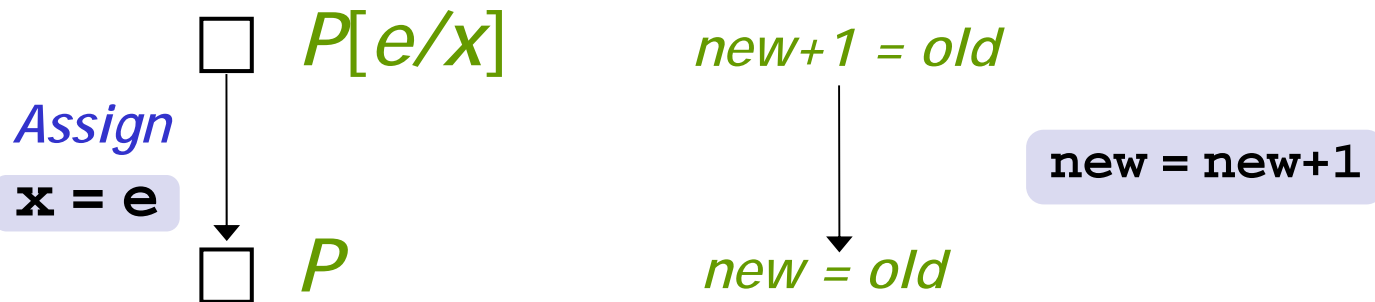
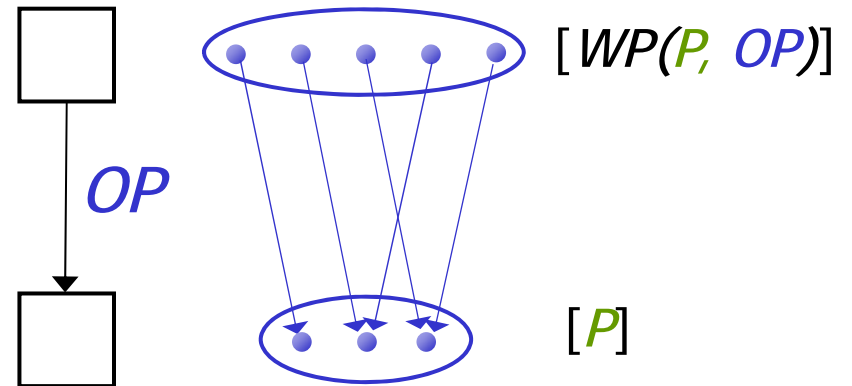
Weakest formula  $P'$  s.t.  
if  $P'$  is true before  $OP$   
then  $P$  is true after  $OP$



# Weakest Preconditions

$WP(P, OP)$

Weakest formula  $P'$  s.t.  
 if  $P'$  is true before  $OP$   
 then  $P$  is true after  $OP$



# Refinement

Weakest precondition of  
 $y \neq i$

$\text{ctr} + 1 \neq i$

```
1: x = ctr;  
2: y = ctr + 1;  
3: assume(x == i-1)  
4: assume (y != i)
```

```
1: skip;  
2: b0 = b2;  
3: if (b1){  
4:   if (b0){  
      ERROR:  
   }  
}
```

boolean b0 :  $y \neq i$

boolean b1 :  $x == i-1$



# Refinement

```
1: x = ctr;  
2: y = ctr + 1;  
3: assume(x == i-1)  
4: assume (y != i)
```

**boolean b2 : ctr + 1 != i**

**boolean b3: ctr == i -1**

```
1: b1 = b3;  
2: b0 = b2;  
3: if (b1){  
4:   if (b0){  
      ERROR:  
   }  
}
```

**boolean b0 : y != i**

**boolean b1 : x== i-1**

# Refinement

What about initial values of b2 and b3?

are mutually exclusive.

b2 = 1, b3 = 0

b2 = 0, b3 = 1

So system is safe!

boolean b2 : ctr + 1 != i

boolean b3: ctr == i - 1

```
1: b1 = b3;  
2: b0 = b2;  
3: if (b1) {  
4:   if (b0) {  
      ERROR:  
   }  
}
```

boolean b0 : y != i

boolean b1 : x == i - 1

# Tools for Predicate Abstraction of C

---

- **SLAM at Microsoft**
  - Used for verifying correct sequencing of function calls in windows device drivers
- **MAGIC at CMU**
  - Allows verification of concurrent C programs
  - Found bugs in MicroC OS
- **BLAST at Berkeley**
  - Lazy abstraction, interpolation
- **SATABS at CMU**
  - Computes predicate abstraction using SAT
  - Can handle pointer arithmetic, bit-vectors
- **F-Soft at NEC Labs**
  - Localization, register sharing