

IEEE 802.11 MAC

- CSMA/CA with exponential backoff
- almost like CSMA/CD
- drop CD
- CSMA with explicit ACK frame
- added optional feature: CA (collision avoidance)

Two modes for MAC operation:

- Distributed coordination function (DCF)
 - multiple access
- Point coordination function (PCF)
 - polling-based priority

... neither PCF nor CA used in practice

CSMA: (i) explicit ACK and (ii) exponential backoff

Sender:

- MAC (firmware in NIC) receives frame from upper layer (i.e., device driver)
- Goto **Backoff** procedure
- Transmit frame
- Wait for ACK
- If timeout, goto **Backoff** procedure

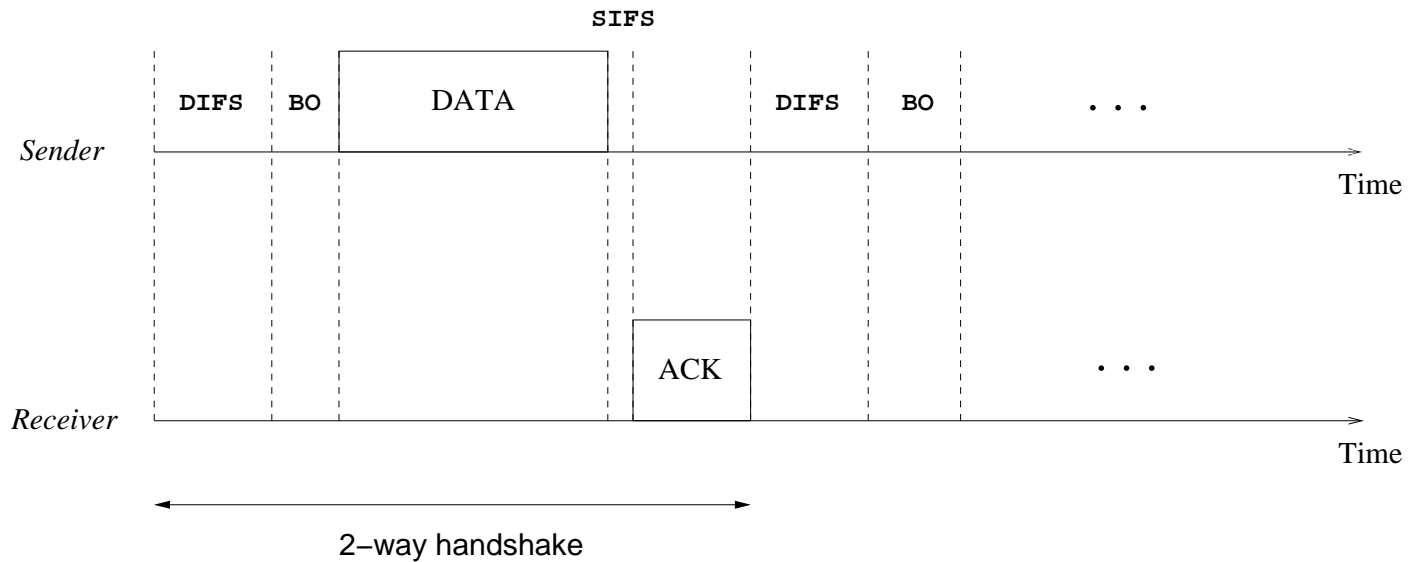
Receiver:

- Check if received frame is ok
- Wait for SIFS
- Transmit ACK

Backoff:

- If due to timeout, double contention window (**CW**)
- Else wait until channel is idle plus an additional DIFS
- Choose random waiting time between $[1, \mathbf{CW}]$
 - **CW** is in units of slot time
- Decrement **CW** when channel is idle
- Return when **CW** = 0

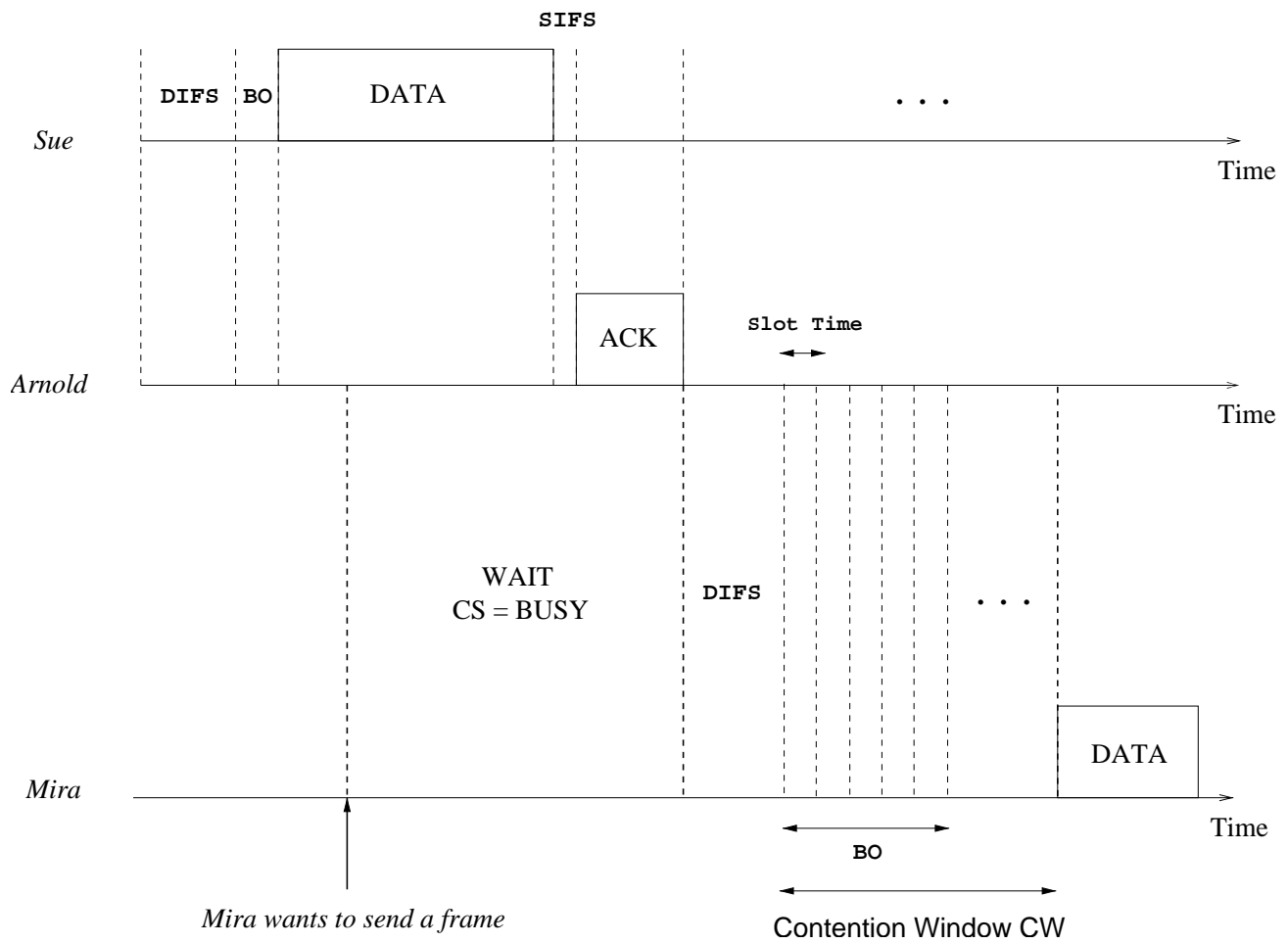
Timeline without collision:



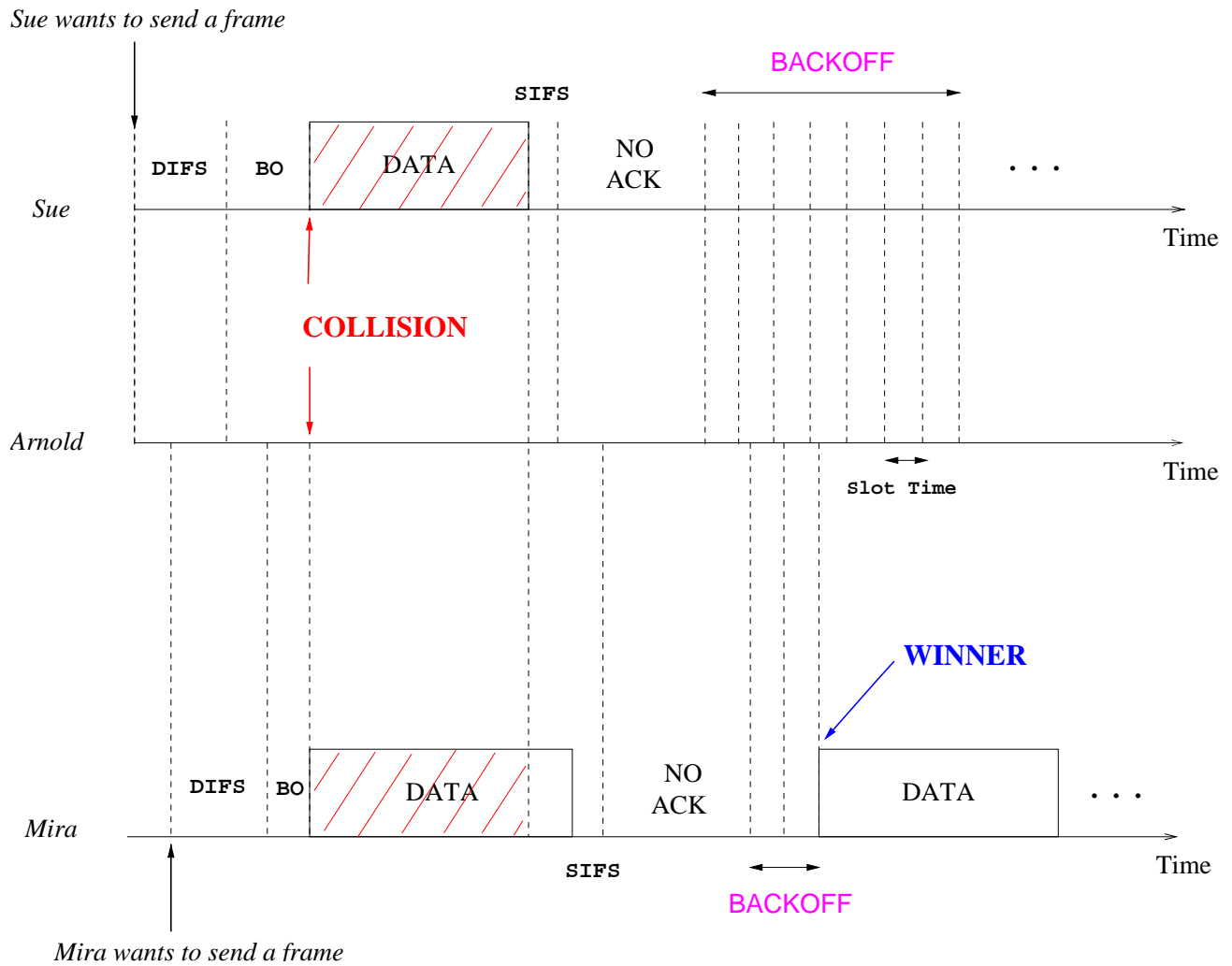
- SIFS (short interframe space): $10 \mu s$
- Slot Time: $20 \mu s$
- DIFS (distributed interframe space): $50 \mu s$
 $\rightarrow \text{DIFS} = \text{SIFS} + 2 \times \text{slot time}$
- BO: variable back-off (within one CW)
 $\rightarrow \text{CW}_{\min}: 31; \text{CW}_{\max}: 1023$

Time snapshot with Mira-come-lately:

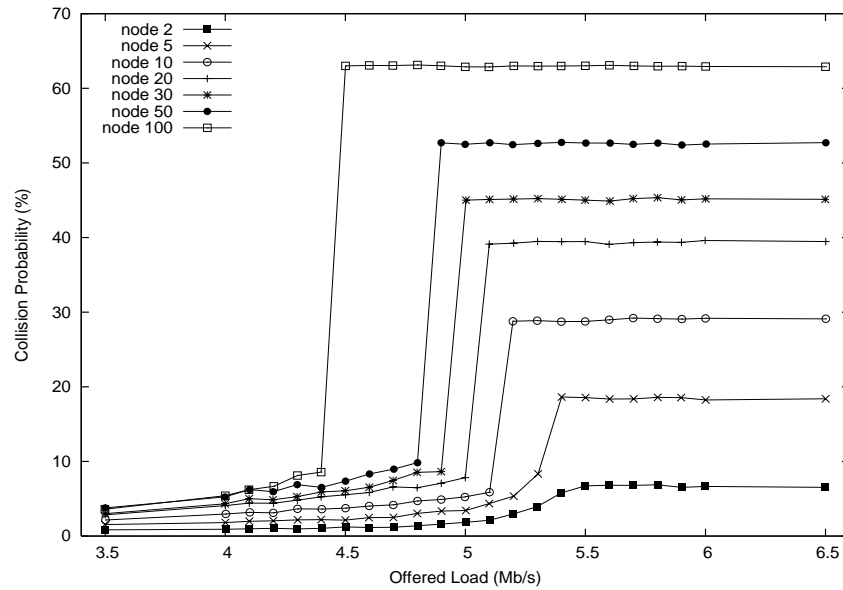
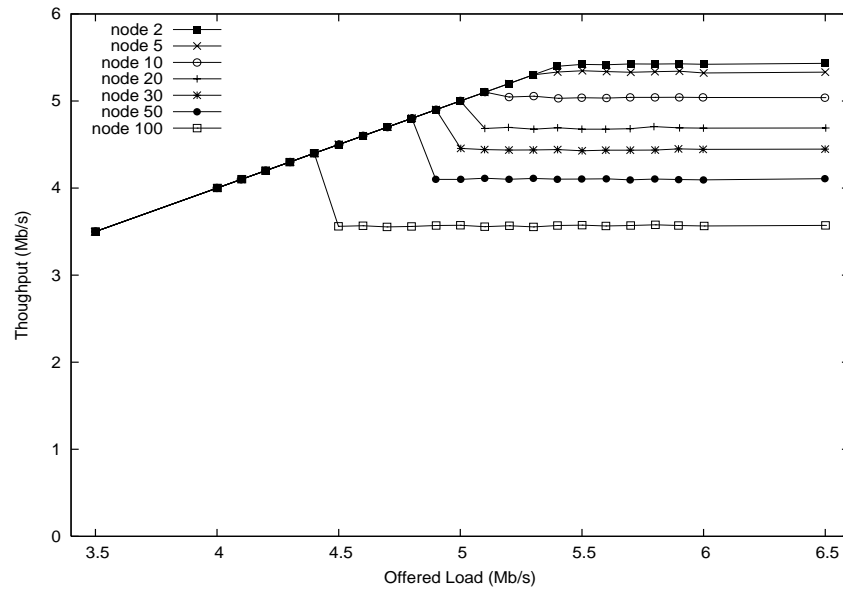
→ Sue sends to Arnold



Time snapshot with collision (Sue & Mira):

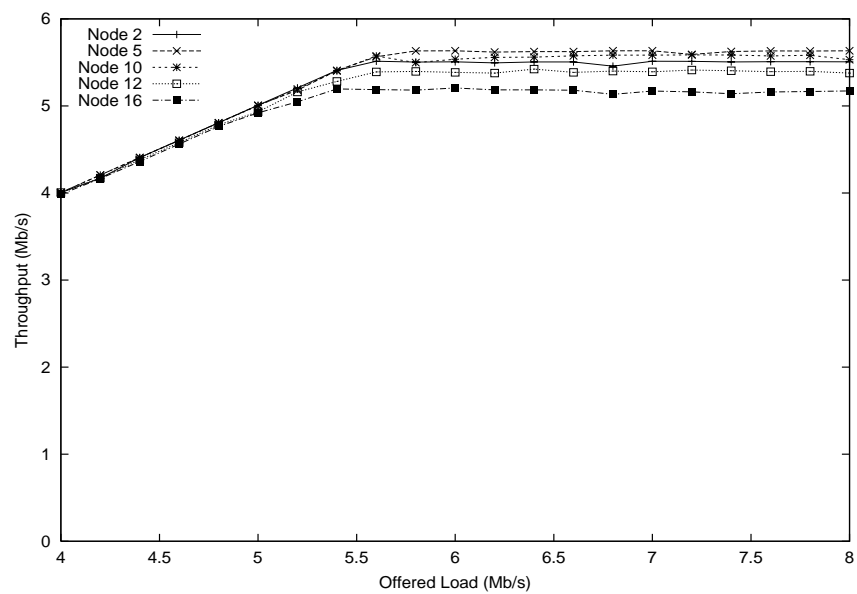


MAC throughput and collision (*ns* simulation):



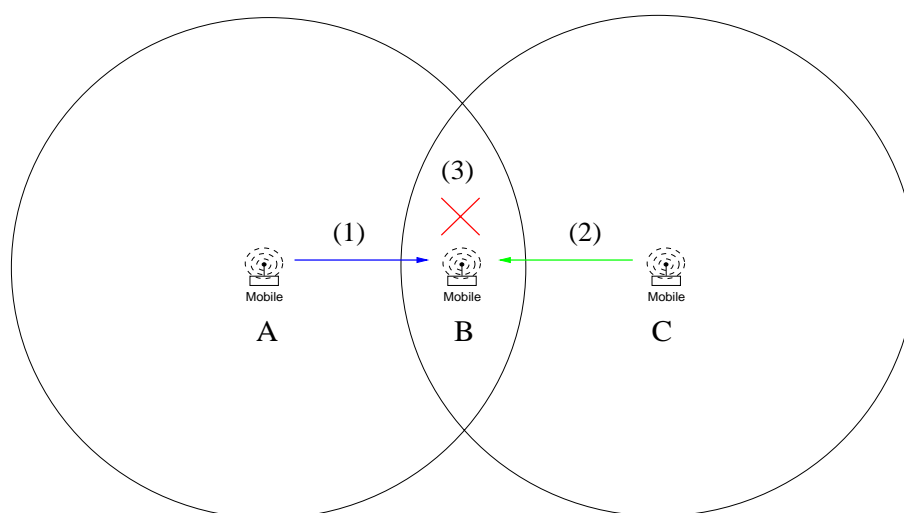
MAC throughput:

→ experiment: iPAQ running Linux



Additional issues with CSMA in wireless media:

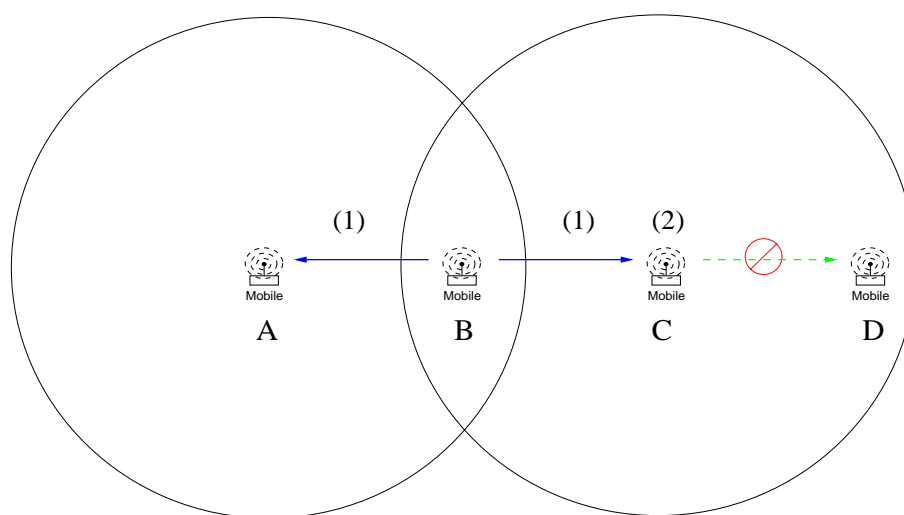
Hidden station problem:



Hidden Station Problem

- (1) A transmits to B
- (2) C does not sense A ; transmits to B
- (3) interference occurs at B : i.e., collision

Exposed station problem:



Exposed Station Problem

(1) B transmits to A

(2) C wants to transmits to D but senses B

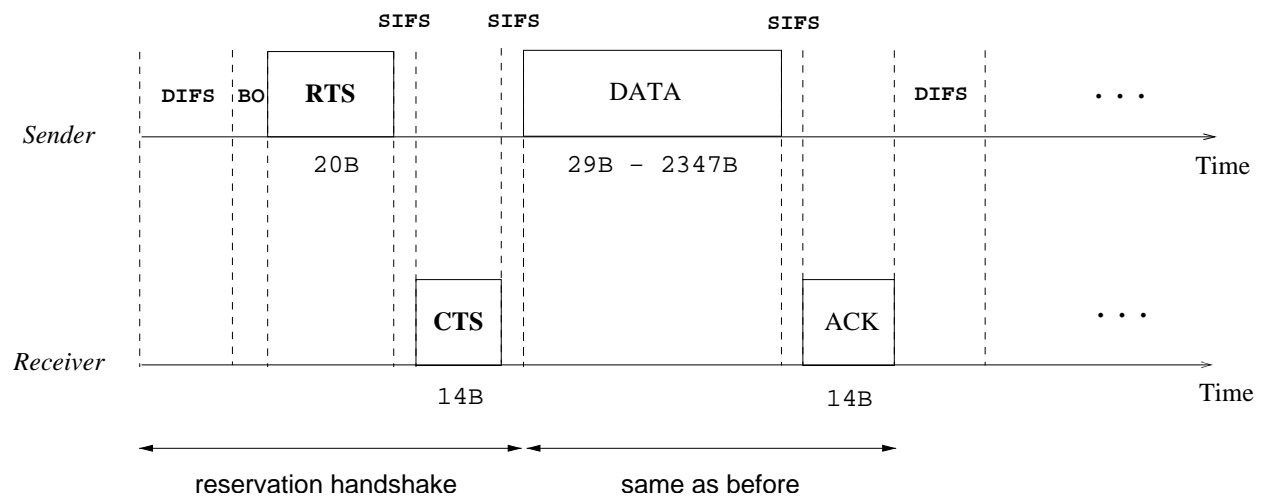
→ C refrains from transmitting to D

→ omni-directional antenna

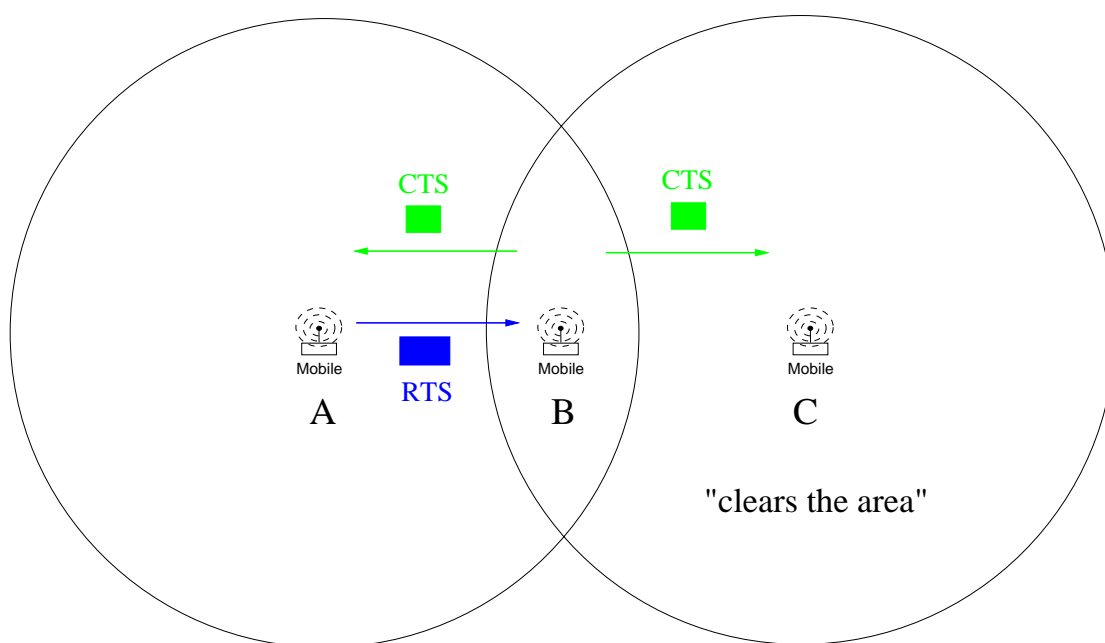
Solution: CA (congestion avoidance)

→ RTS/CTS reservation handshake

- Before data transmit, perform RTS/CTS handshake
- RTS: request to send
- CTS: clear to send



Hidden station problem: RTS/CTS handshake “clears” hidden area



RTS/CTS Handshake

RTS/CTS perform only if data $>$ RTS threshold

→ why not for small data?

... feature available but not actively used

Additional optimization: virtual carrier sense

- transmit connection duration information
- stations maintain NAV (network allocation vector)
→ decremented by clock
- if $NAV > 0$, then do not access even if physical CS says channel is idle

PCF (point coordination function):

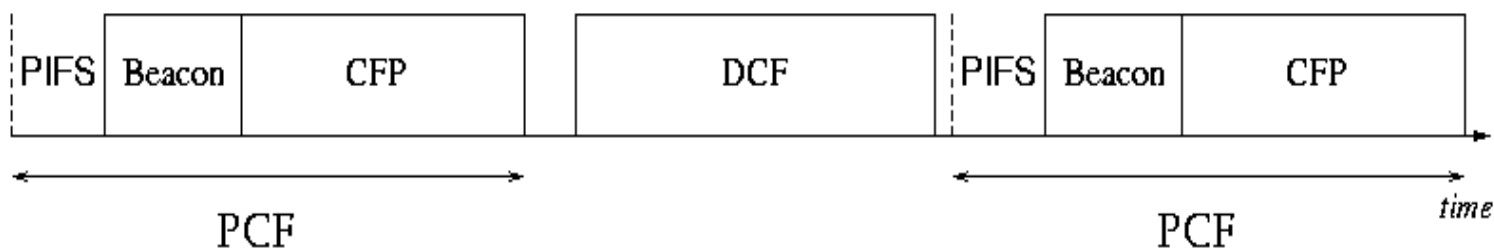
→ support for real-time traffic

- Periodically inject contention free period (CFP)

→ after BEACON

- Under the control of point coordinator: AP

→ polling



PIFS (priority IFS):

→ $SIFS < \text{Slot Time} < PIFS < DIFS$

Properties of PCF:

- BEACON period is not precise
 - has priority (PIFS < DIFS) but cannot preempt DCF
- During CFP services stations on polling list
 - delivery of frames
 - polling: reception of frames
 - must maintain polling list: group membership
- Uses NAV to maintain CFP
- BEACON: separate control frame used to coordinate BSS
 - time stamp, SSID, etc.

IEEE 802.11 wireless LAN standard:

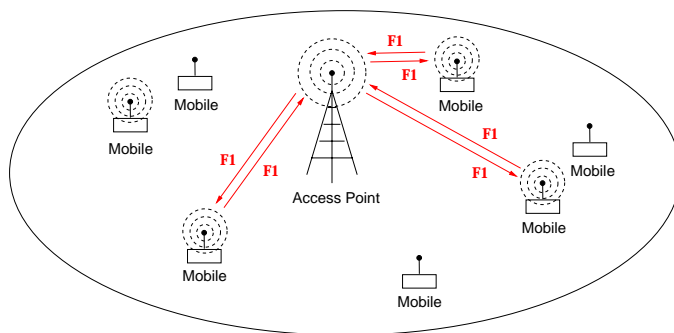
- ratified in 1997: 1/2 Mbps using either DSSS or FHSS
→ 11 bit chip sequence
- uses IEEE 802 address format along with LLC
→ 4 address fields for forwarding/management
- uses 2.4–2.4835 GHz ISM band in radio spectrum
→ ISM (industrial, scientific and medical): unlicensed
- IEEE 802.11b ratified: 5.5/11 Mbps using DSSS only
→ less coding overhead: good for low BER
→ BER (bit error rate) and FER (frame error rate)
- others: e.g., IEEE 802.11a and 802.11g at 54 Mbps
→ 5.725–5.85 vs. 2.4–2.4835 GHz band
→ both use OFDM

Bluetooth, 802.16, etc.; uncertain future . . .

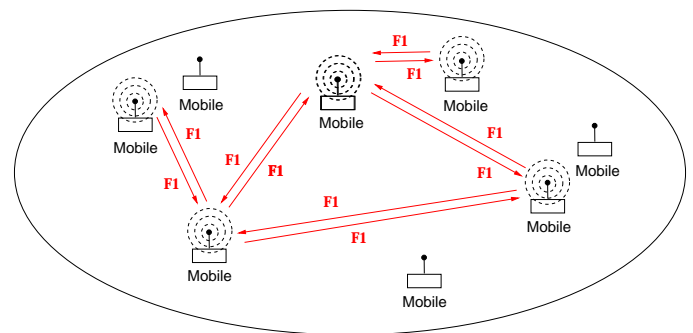
WLAN: ad hoc vs. infrastructure mode

→ a.k.a. why ad hoc, in general, is a bad idea

→ why...



WLAN: Infrastructure Network

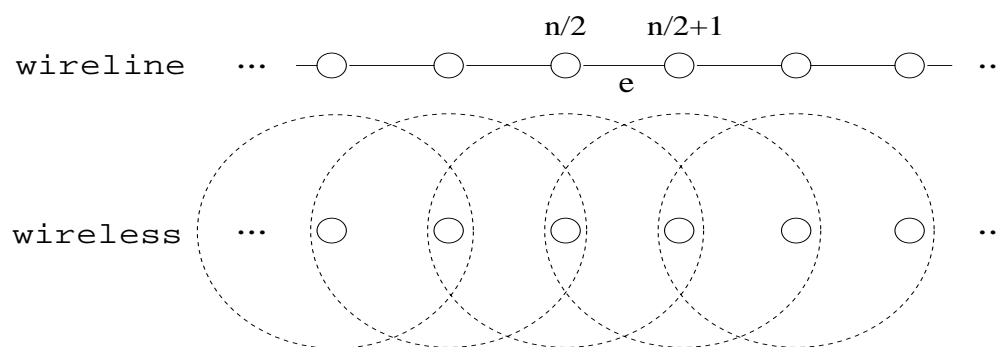


WLAN: Ad Hoc Network

Two key reasons:

- nothing to do with wireless
 - i.e., common to wireline networks
 - “double duty”
- specifically to do with wireless LANs

Consider “corridor” configuration: linear chain



→ connectivity-wise: equivalent

Assume:

- there are n nodes
- link bandwidth: B Mbps
- every node picks a random destination to talk
 - data rate of each node: 1 Mbps
- consider middle link $e = (n/2, n/2 + 1)$
 - how much traffic must go through e ?
 - inherent load or stress on link e

Fixing direction (left or right, i.e., half-duplex):

→ average load on e : $L(e) = n/4$

→ note: still linear in n (i.e., $L(e) = O(n)$)

To satisfy traffic demand:

→ bandwidth on e : $B = n/4$ Mbps

→ else: cannot send or must buffer

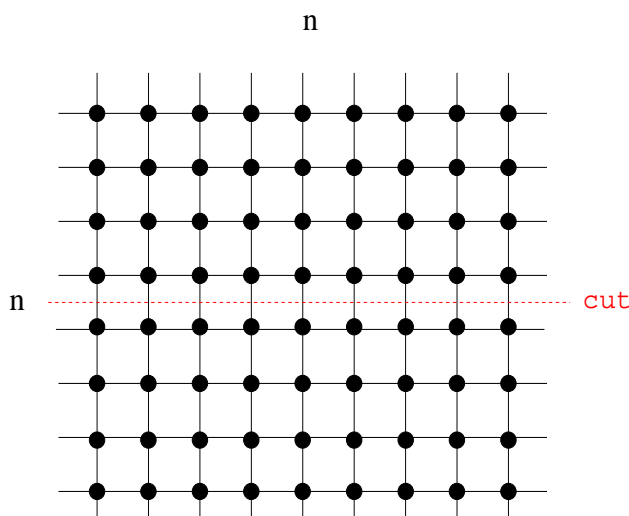
Main observation: under ad hoc mode in both wireline & wireless networks, individual link bandwidth must increase with system size n

→ due to forwarding duty!

→ not scalable w.r.t. system size

Remarks:

- link $e = (n/2, n/2 + 1)$ is typical
 → majority of links are near the middle
- how does link bandwidth requirement X increase in 2-D grid/lattice configuration?



- when side is n long: total n^2 nodes
- hence with \sqrt{n} side: total n nodes
- note: link e was a cut dividing into 2 halves
- average load on each link in 2-D cut?

Average link load: $L(e) = \sqrt{n}/4$

→ under assumption of perfect load balancing

→ note: \sqrt{n} number of links in the cut

Thus in grid topologies, bandwidth requirement increases as: $O(\sqrt{n})$

→ still not scalable

→ in wireline networks: use switches/routers

→ else must upgrade link bandwidth constantly

ad hoc WLANs: additional impact of collision/interference

→ throughput goes down even more

→ Gupta and Kumar '99