

CS526: Information Security
Chris Clifton

August 31, 2004

Access Control Matrix



Description

objects (entities)

	o_1	...	o_m	s_1	...	s_n
s_1						
s_2						
...						
s_n						

subjects

- Subjects $S = \{ s_1, \dots, s_n \}$
- Objects $O = \{ o_1, \dots, o_m \}$
- Rights $R = \{ r_1, \dots, r_k \}$
- Entries $A[s_i, o_j] \subseteq R$
- $A[s_i, o_j] = \{ r_x, \dots, r_y \}$ means subject s_i has rights r_x, \dots, r_y over object o_j



Example 2

- Procedures *inc_ctr*, *dec_ctr*, *manage*
- Variable *counter*
- Rights +, -, *call*

	<i>counter</i>	<i>inc_ctr</i>	<i>dec_ctr</i>	<i>manage</i>
<i>inc_ctr</i>	+			
<i>dec_ctr</i>	-			
<i>manage</i>		<i>call</i>	<i>call</i>	<i>call</i>

3



Boolean Expression Evaluation

- ACM controls access to database fields
 - Subjects have attributes
 - Verbs define type of access
 - Rules associated with objects, verb pair
- Subject attempts to access object
 - Rule for object, verb evaluated, grants or denies access

4



Example

- Subject annie
 - Attributes role (artist), groups (creative)
- Verb paint
 - Default 0 (deny unless explicitly granted)
- Object picture
 - Rule:
paint: 'artist' in subject.role and
'creative' in subject.groups and
time.hour ≥ 0 and time.hour < 5

5



Protection State Transitions

- State $X_i = (S_i, O_i, A_i)$
- Transitions τ_i
 - Single transition $X_i \vdash_{\tau_{i+1}} X_{i+1}$
 - Series of transitions $X \vdash^* Y$
- Access control matrix may change
 - Change command c associated with transition
 - $X_i \vdash_{c_{i+1}(p_{i+1}, \dots, p_{i+1})} X_{i+1}$
- Commands often called *transformation procedures*

6



Special Privileges: Copy, Ownership

- Copy (or grant)
 - Possessor can extend privileges to another
- Own right
 - Possessor can change their own privileges
- Principle of Attenuation of Privilege
 - A subject may not give rights it does not possess

8



Primitive Commands

- Create Object o
 - Adds o to objects with no access
 - $S'=S$, $O'=O\cup\{o\}$, $(\forall x\in S')[a'[x,o]=\emptyset]$,
 $(\forall x\in S')(\forall y\in O)[a'[x,y]=a[x,y]]$
- Create Subject s
 - Adds s to objects, subjects, sets relevant access control to \emptyset
- Enter r into $a[s,o]$
- Delete r from $a[s,o]$
- Destroy subject s , destroy object o

9



Create Subject

- Precondition: $s \notin S$
- Primitive command: **create subject s**
- Postconditions:
 - $S' = S \cup \{s\}$, $O' = O \cup \{s\}$
 - $(\forall y \in O')[a'[s, y] = \emptyset]$, $(\forall x \in S')[a'[x, s] = \emptyset]$
 - $(\forall x \in S)(\forall y \in O)[a'[x, y] = a[x, y]]$

11



Create Object

- Precondition: $o \notin O$
- Primitive command: **create object o**
- Postconditions:
 - $S' = S$, $O' = O \cup \{o\}$
 - $(\forall x \in S')[a'[x, o] = \emptyset]$
 - $(\forall x \in S)(\forall y \in O)[a'[x, y] = a[x, y]]$

12



Add Right

- Precondition: $s \in S, o \in O$
- Primitive command: enter r into $a[s, o]$
- Postconditions:
 - $S' = S, O' = O$
 - $a'[s, o] = a[s, o] \cup \{r\}$
 - $(\forall x, y \in S \times O - \{s, o\}) \quad [a'[x, y] = a[x, y]]$

13



Delete Right

- Precondition: $s \in S, o \in O$
- Primitive command: **delete** r from $a[s, o]$
- Postconditions:
 - $S' = S, O' = O$
 - $a'[s, o] = a[s, o] - \{r\}$
 - $(\forall x, y \in S \times O - \{s, o\}) \quad [a'[x, y] = a[x, y]]$

14



Destroy Subject

- Precondition: $s \in S$
- Primitive command: **destroy subject s**
- Postconditions:
 - $S' = S - \{s\}, O' = O - \{s\}$
 - $(\forall y \in O')[a'[s, y] = \emptyset], (\forall x \in S')[a'[x, s] = \emptyset]$
 - $(\forall x \in S')(\forall y \in O') [a'[x, y] = a[x, y]]$

15



Destroy Object

- Precondition: $o \in O$
- Primitive command: **destroy object o**
- Postconditions:
 - $S' = S, O' = O - \{o\}$
 - $(\forall x \in S')[a'[x, o] = \emptyset]$
 - $(\forall x \in S')(\forall y \in O') [a'[x, y] = a[x, y]]$

16



Creating File

- Process p creates file f with r and w permission

```
command create•file( $p, f$ )  
  create object  $f$ ;  
  enter own into  $A[p, f]$ ;  
  enter  $r$  into  $A[p, f]$ ;  
  enter  $w$  into  $A[p, f]$ ;  
end
```

17



Mono-Operational Commands

- Make process p the owner of file g
command *make•owner*(p, g)
 enter *own* into $A[p, g]$;
 end
- Mono-operational command
 - Single primitive operation in this command

18



Conditional Commands

- Let p give q r rights over f , if p owns f
command *grant•read•file•1*(p, f, q)
 if *own* **in** $A[p, f]$
 then
 enter r **into** $A[q, f]$;
 end
- Mono-conditional command
 - Single condition in this command

19



Multiple Conditions

- Let p give q r and w rights over f , if p owns f and p has c rights over q
command *grant•read•file•2*(p, f, q)
 if *own* **in** $A[p, f]$ **and** c **in** $A[p, q]$
 then
 enter r **into** $A[q, f]$;
 enter w **into** $A[q, f]$;
 end

20



Copy Right

- Allows possessor to give rights to another
- Often attached to a right, so only applies to that right
 - *r* is read right that cannot be copied
 - *rc* is read right that can be copied
- Is copy flag copied when giving *r* rights?
 - Depends on model, instantiation of model

21



Own Right

- Usually allows possessor to change entries in ACM column
 - So owner of object can add, delete rights for others
 - May depend on what system allows
 - Can't give rights to specific (set of) users
 - Can't pass copy flag to specific (set of) users

22



Attenuation of Privilege

- Principle says you can't give rights you do not possess
 - Restricts addition of rights within a system
 - Usually *ignored* for owner
 - Why? Owner gives herself rights, gives them to others, deletes her rights.

23



Key Points

- Access control matrix simplest abstraction mechanism for representing protection state
- Transitions alter protection state
- 6 primitive operations alter matrix
 - Transitions can be expressed as commands composed of these operations and, possibly, conditions

24

CS526: Information Security
Chris Clifton

September 2, 2004
Decidability



What is *Secure*?

- A secure system doesn't allow violations of policy
 - Is this a good definition?
 - Can we use it?
- Alternative view: based on rights
 - Start with access control matrix A
 - *Leak*: commands can add right r to an element of A not containing r
 - *Safe*: System is *safe with respect to* r if r cannot be leaked



Formally:

- Given
 - initial state $X_0 = (S_0, O_0, A_0)$
 - Set of primitive commands c
- Can we reach a state X_n where $\exists s, o$ such that $A_n[s, o]$ includes a right r not in $A_0[s, o]$?
 - If so, the system is not safe
 - But is “safe” secure?

Are commands correctly implemented?

27



Example: Unix File System

- Access Control Matrix
 - Root has access to all files
 - Owner has access to their own files
- Safe with respect to file access right?
 - No chmod/chown command
 - Only “root” can get root privileges
 - Only user can authenticate as themselves

Is “Safe” definition useful?

28



Solution: Trust

- Safety doesn't distinguish leak from authorized transfer of rights
- Subjects authorized to receive transfer of rights deemed "trusted"
 - Eliminate trusted subjects from matrix

29



Decidability Result (Harrison, Ruzzo, Ullman)

- Given a system where each command consists of a single *primitive* command, There exists an algorithm that will determine if a protection system with initial state X_0 is safe with respect to right r .
- Proof: determine minimum commands k to leak
 - Delete/destroy: Can't leak (or be detected)
 - Create/enter: new subjects/objects "equal", so treat all new subjects as one
 - If n rights, leak possible, must be able to leak $n(|S_0|+1)(|O_0|+1)+1$ commands
- Enumerate all possible to decide

30



Decidability: Non-Primitive Commands

- It is undecidable if a given state of a given protection system is safe for a given generic right
- Proof: Reduction from halting problem
 - Symbols, states \Rightarrow rights
 - Tape cell \Rightarrow subject (can create new subjects)
 - Right *own*: s_i owns s_{i+1} for $1 \leq i < k$
 - Cell $s_i A \Rightarrow s_i$ has A rights on itself
 - Cell $s_k \Rightarrow s_k$ has end rights on itself
 - State p , head at $s_i \Rightarrow s_i$ has p rights on itself

31



Example:

Turing Machine

A	B	C	D	...
---	---	---	---	-----



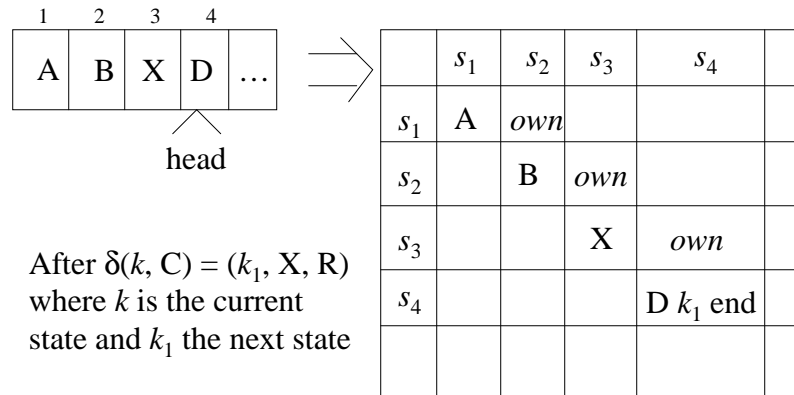
Matrix

	s_1	s_2	s_3	s_4
s_1	A	<i>own</i>		
s_2		B	<i>own</i>	
s_3			C, p	<i>own</i>
s_4				D, <i>end</i>

32



Mapping



After $\delta(k, C) = (k_1, X, R)$
 where k is the current
 state and k_1 the next state

33



Command Mapping

$\delta(k, C) = (k_1, X, R)$ at intermediate becomes
command $c_{k,C}(s_3, s_4)$
if *own* **in** $A[s_3, s_4]$ **and** k **in** $A[s_3, s_3]$
 and C **in** $A[s_3, s_3]$
then
 delete k **from** $A[s_3, s_3]$;
 delete C **from** $A[s_3, s_3]$;
 enter X **into** $A[s_3, s_3]$;
 enter k_1 **into** $A[s_4, s_4]$;
end

34



Commands:

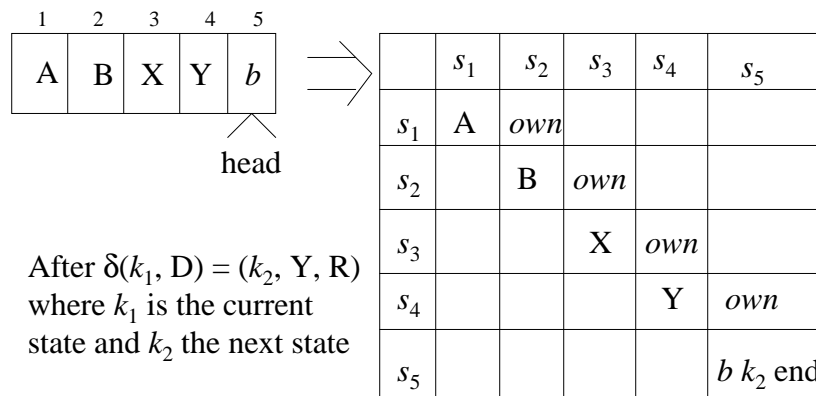
- Halting problem Turing Machine: Symbols A, B ; states p, q
- $C_{p,A}(s_i, s_{i-1})$ (move left)
 - if $own \in a[s_{i-1}, s_i]$ and $p \in a[s_i, s_i]$ and $A \in a[s_i, s_i]$
 - Delete p from $a[s_i, s_i]$, A from $a[s_i, s_i]$
 - Enter B into $a[s_i, s_i]$, q into $a[s_{i-1}, s_{i-1}]$
- Similar commands for move right, move right at end of tape
- Simulates Turing machine
 - Leaks halting state \Rightarrow halting state in the matrix \Rightarrow Halting state reached

This is undecidable!

35



Mapping



36



Command Mapping

$\delta(k_1, D) = (k_2, Y, R)$ at end becomes

```
command crightmostk,c(s4, s5)
if end in A[s4, s4] and k1 in A[s4, s4]
    and D in A[s4, s4]
then
    delete end from A[s4, s4];
    create subject s5;
    enter own into A[s4, s5];
    enter end into A[s5, s5];
    delete k1 from A[s4, s4];
    delete D from A[s4, s4];
    enter Y into A[s4, s4];
    enter k2 into A[s5, s5];
end
```

37



Rest of Proof

- Protection system exactly simulates a TM
 - Exactly 1 *end* right in ACM
 - 1 right in entries corresponds to state
 - Thus, at most 1 applicable command
- If TM enters state q_f , then right has leaked
- If safety question decidable, then represent TM as above and determine if q_f leaks
 - Implies halting problem decidable
- Conclusion: safety question undecidable

38



Other Results

(most from the same authors)

- Set of unsafe systems recursively enumerable
- Without create primitive, safety in P-SPACE
 - Like halting problem reduction, but no unlimited tape
- Without delete/destroy, still undecidable
 - Decidable if at most one condition allowed per command
 - Still holds if delete allowed

39



Where does this leave us?

- Safety decidable for some models
 - Are they practical?
- Safety only works if maximum rights known in advance
 - Policy must specify all rights someone could get, not just what they have
 - Where might this make sense?
- Next: Example of a decidable model
 - Take-Grant Protection Model

40



Mono-Operational Commands

- Answer: yes
- Sketch of proof:
 - Consider minimal sequence of commands c_1, \dots, c_k to leak the right.
 - Can omit **delete**, **destroy**
 - Can merge all **creates** into one
 - Worst case: insert every right into every entry;
with s subjects and o objects initially, and n
rights, upper bound is $k \leq n(s+1)(o+1)$