



Radiometric Calibration

CS635 Spring 2010

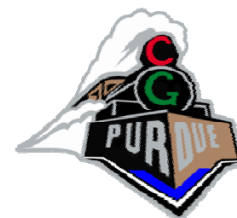
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Radiometric Calibration



- Since color is important, we want to emit and capture the colors we expect
- Example Goal:
 - “Given a desired color \mathbf{x} , instruct the projector to illuminate the color \mathbf{y} such that what appears to the camera is \mathbf{x} ”

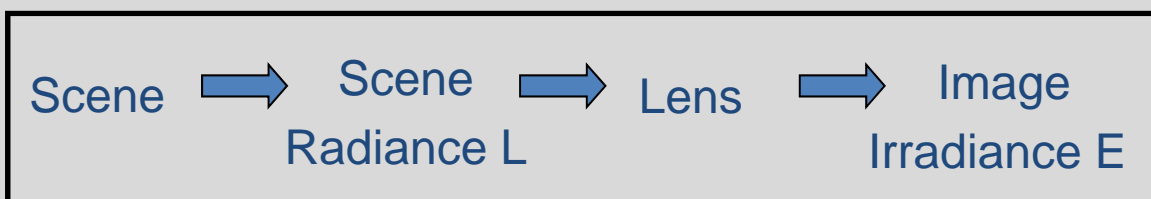
...Ideally $\mathbf{x}=\mathbf{y}$, but in practice this is not the case



Radiometric Calibration

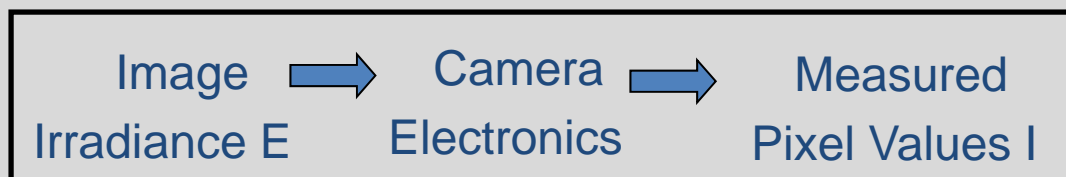
- Coordinate the per-channel color intensities between multiple projectors

Before light hits the image plane:



~Linear Mapping

After light hits the image plane:



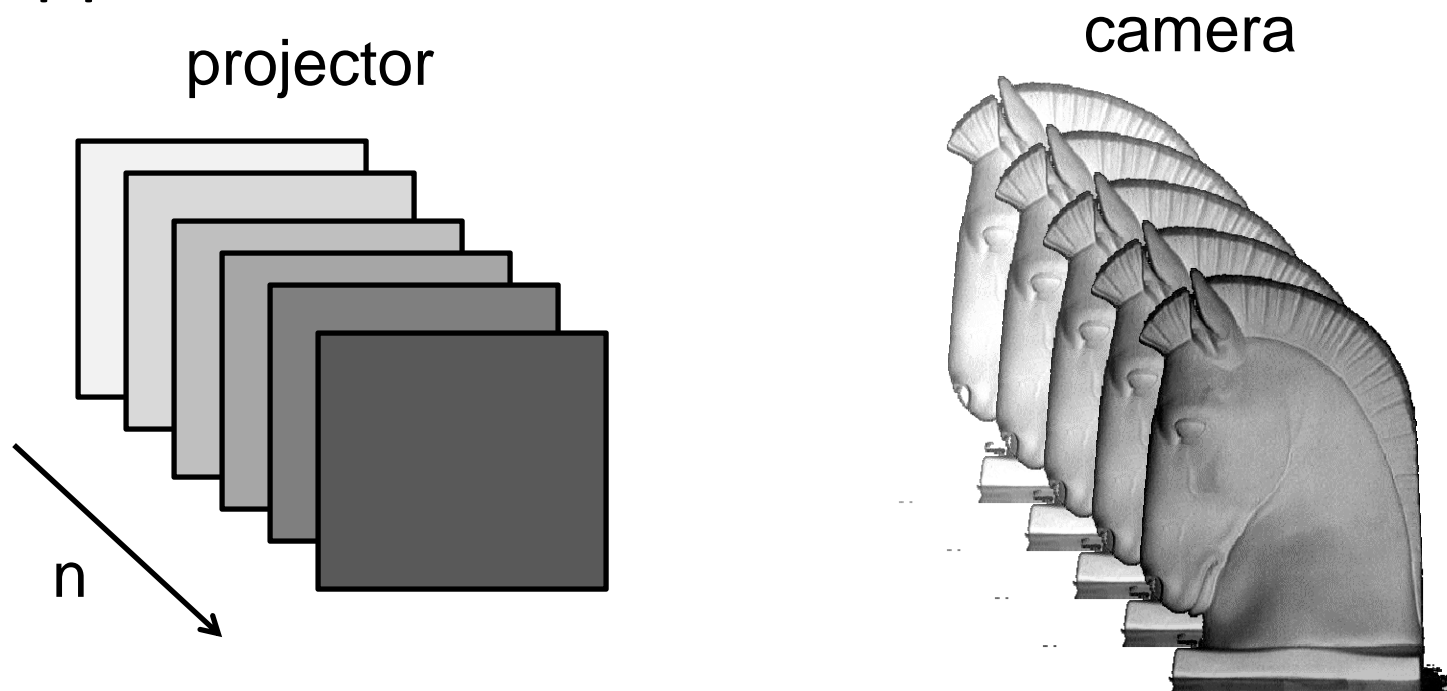
Non-linear Mapping

Can we go from measured pixel value, I , to scene radiance, L ?



Grayscale Calibration

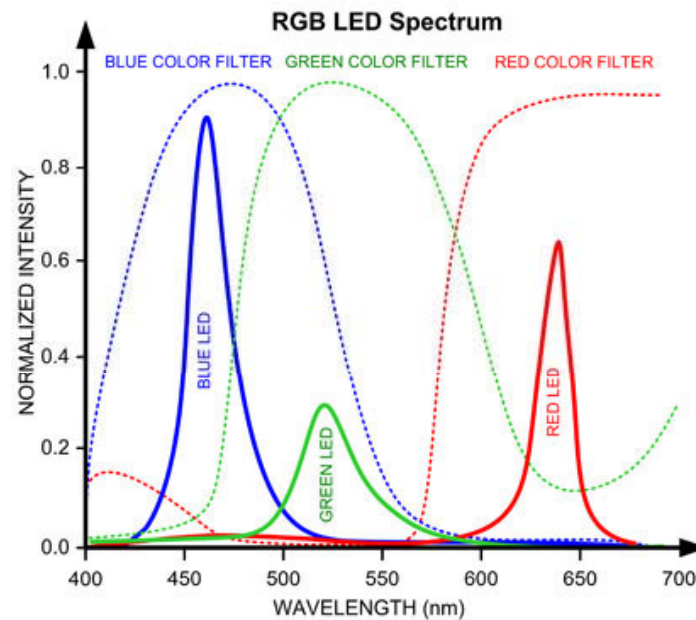
- Assuming n -bit channels, project 2^n “gray-level images” onto the scene and capture the appearance 2^n times





Going to Color

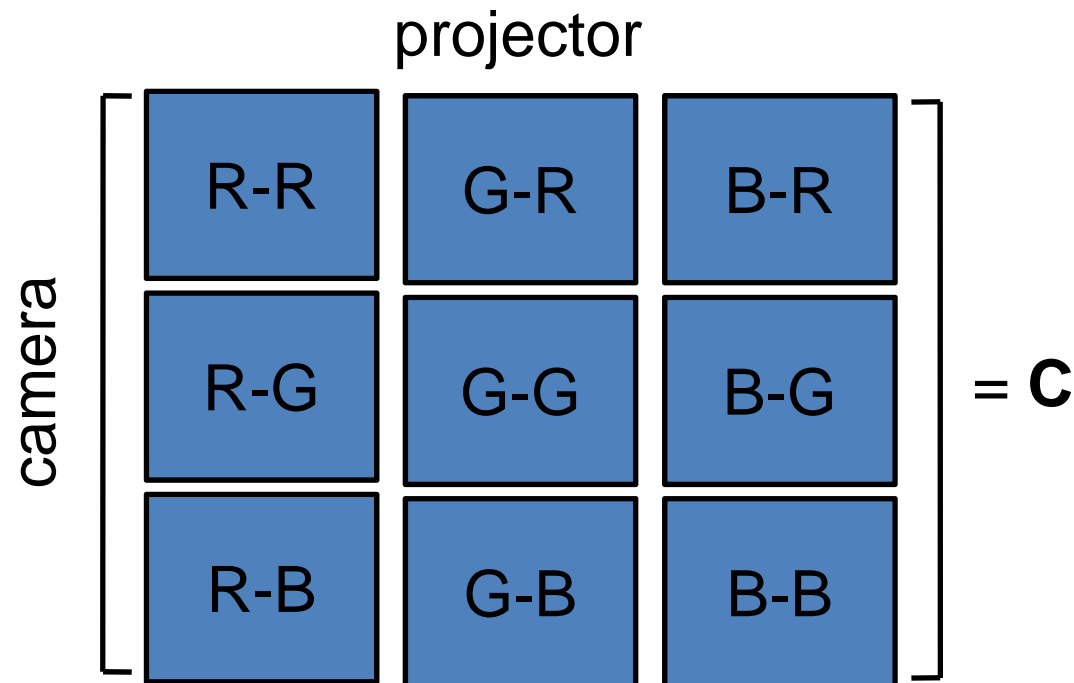
- When extending to color, since color channels are not fully non-overlapping, the color mixture must be taken into account





Color Calibration

- Assuming n -bit RGB channels, project 3×2^n “single-color images” onto the scene and capture the appearance 3×2^n times



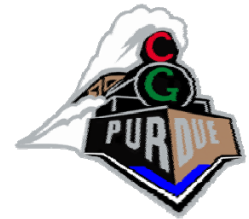


Color Calibration

- **C** is the color mixture matrix
- **x** = projector color, **y** = camera color, thus

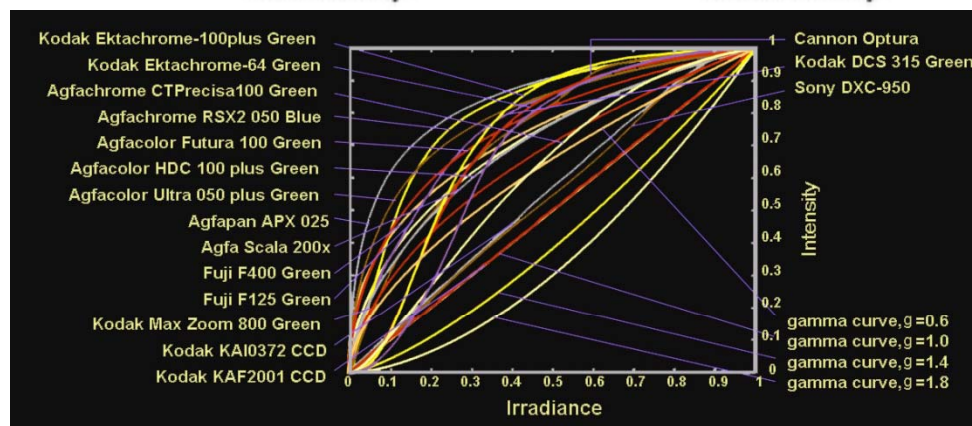
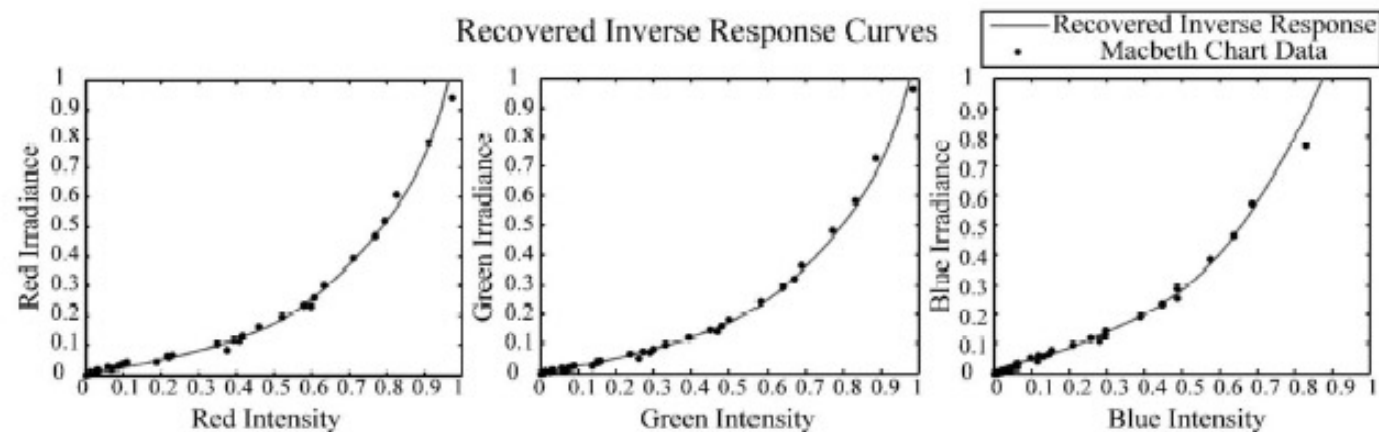
$$\mathbf{y} = \mathbf{C}\mathbf{x}$$

$$\mathbf{x} = \mathbf{C}^{-1}\mathbf{y}$$



Additional Issues

- Linear vs. Nonlinear Response



Nayar et al., CAVE



Additional Issues

- Exposure settings

At what aperture and shutter speed?

...behavior is not necessarily linear

...can fix the settings but that obtains a limited dynamic range

- Vignetting

Reducing Acquisition Time



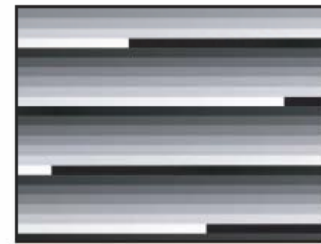
- For 8-bit per channel, RGB, multiple exposures (e.g., 3), means $256 \times 3 \times 3 = 6912$ images

Acceleration schemes:

e.g., total of 6 images

“Making One Object Look Like Another”

Grossberg et al., 2004



(a) Calibration Pattern



(b) Poster of Tulips



(c) Pattern Projected on Tulips



(d) Computed Invariant

Does not handle “inter-reflections” ...