



# Extreme Data Streaming Using Image Database

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# Problem

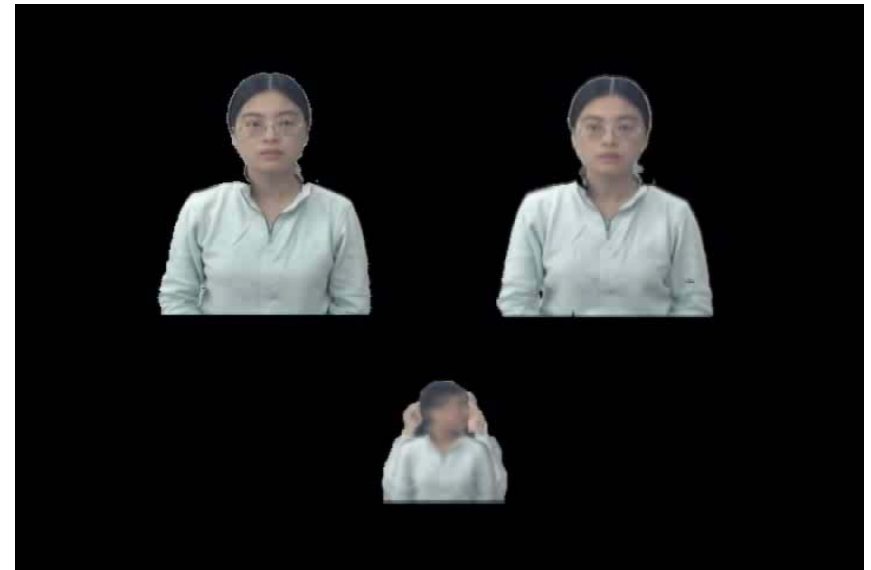


- Current limitation in bandwidth for large data communication
- We want to achieve real time interactive communication under low bandwidth network

# Key Insights



- Limited body motion
  - Pre-record the motion sequence
  - Send the processed movie in the beginning
- Live video captured from webcam is matched with the frames in image database, only the index of the matched frame is sent

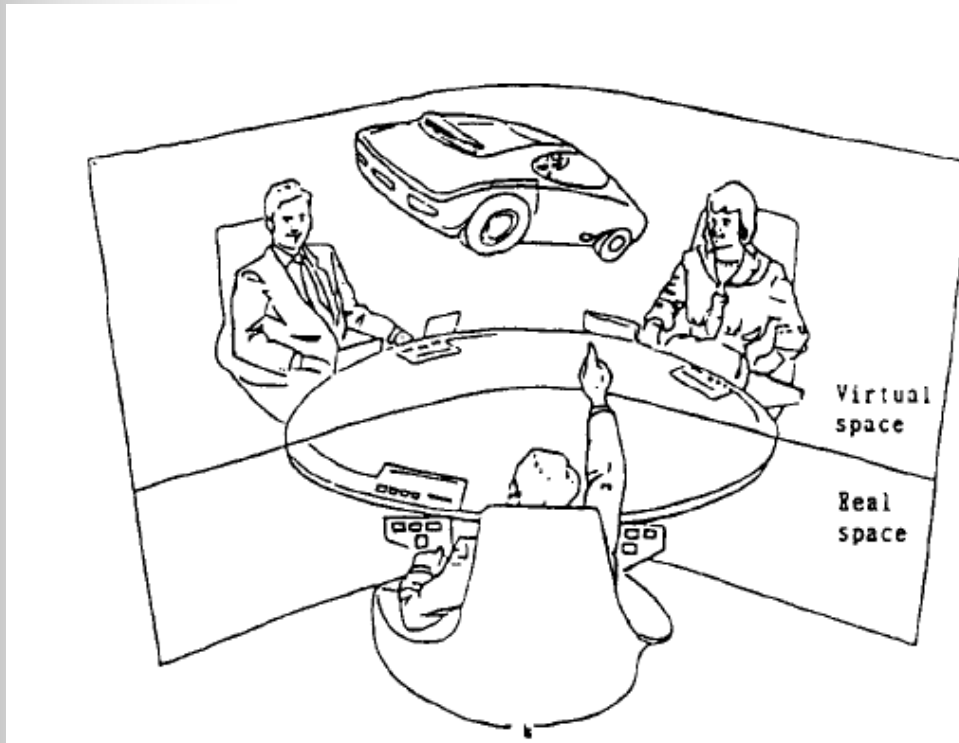


# Possible application



Distance Learning Classroom System

# Another example



Virtual office

Aizawa, Kiyoharu. "Model-Based Image Coding: Advanced Video Coding Techniques for Very Low Bit-Rate Applications". Proceedings of the IEEE, Vol. 83, No. 2, February 1995

# Contribution



- Extreme bit-rate reduction (35kbps -> 480 bps for 30 fps)
  - Independent resolution
  - Less overhead – no need to build a 3D model
  - Low computational complexity: based purely on image comparison
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# Data Acquisition



- A movie sequence consists of various upper body gestures.
- Natural pausing between sequence.
- Guiding audio instruction.



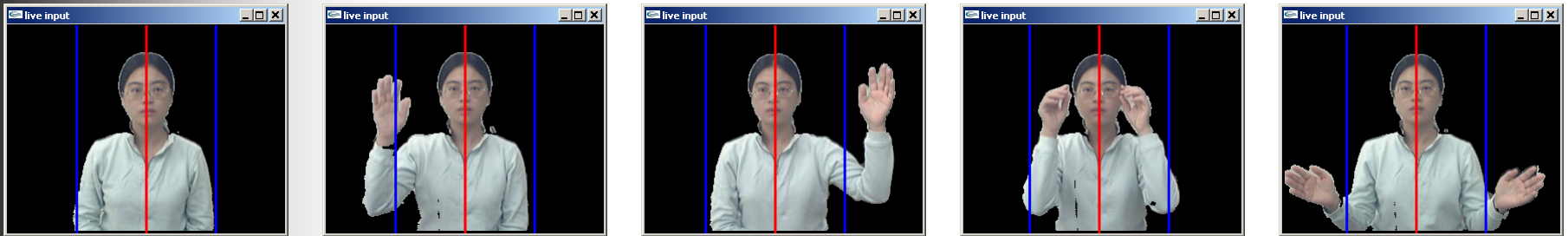
# Data Registration



- Background subtraction
- Frame Segmentation
- Shape Analysis
  - Noise removal
  - Silhouette



# Frame Segmentation



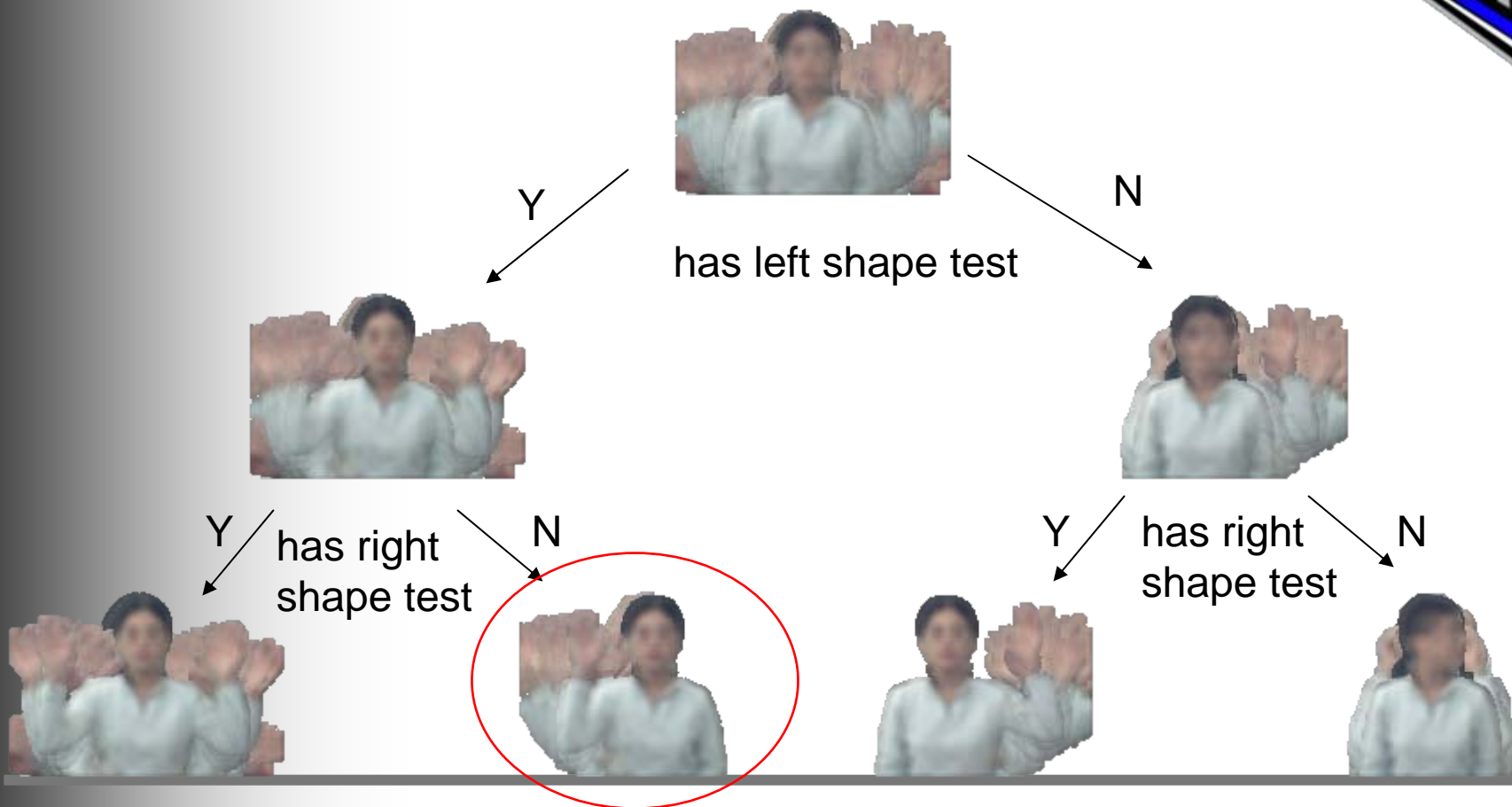
- Central line (red) and shoulder line (blue) defines the stationary region without shape variation

# Model Segmentation



- Group division based on pausing
- Skipping redundant frames
- Merging group based on similar shape
- Binary tree built based on shape variation w.r.t. the stationary region

# Tree Visualization



# Tree Leaves



- Leaf node 5: left side only shape

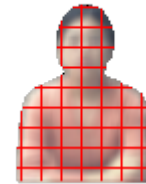
# Image-based Matching

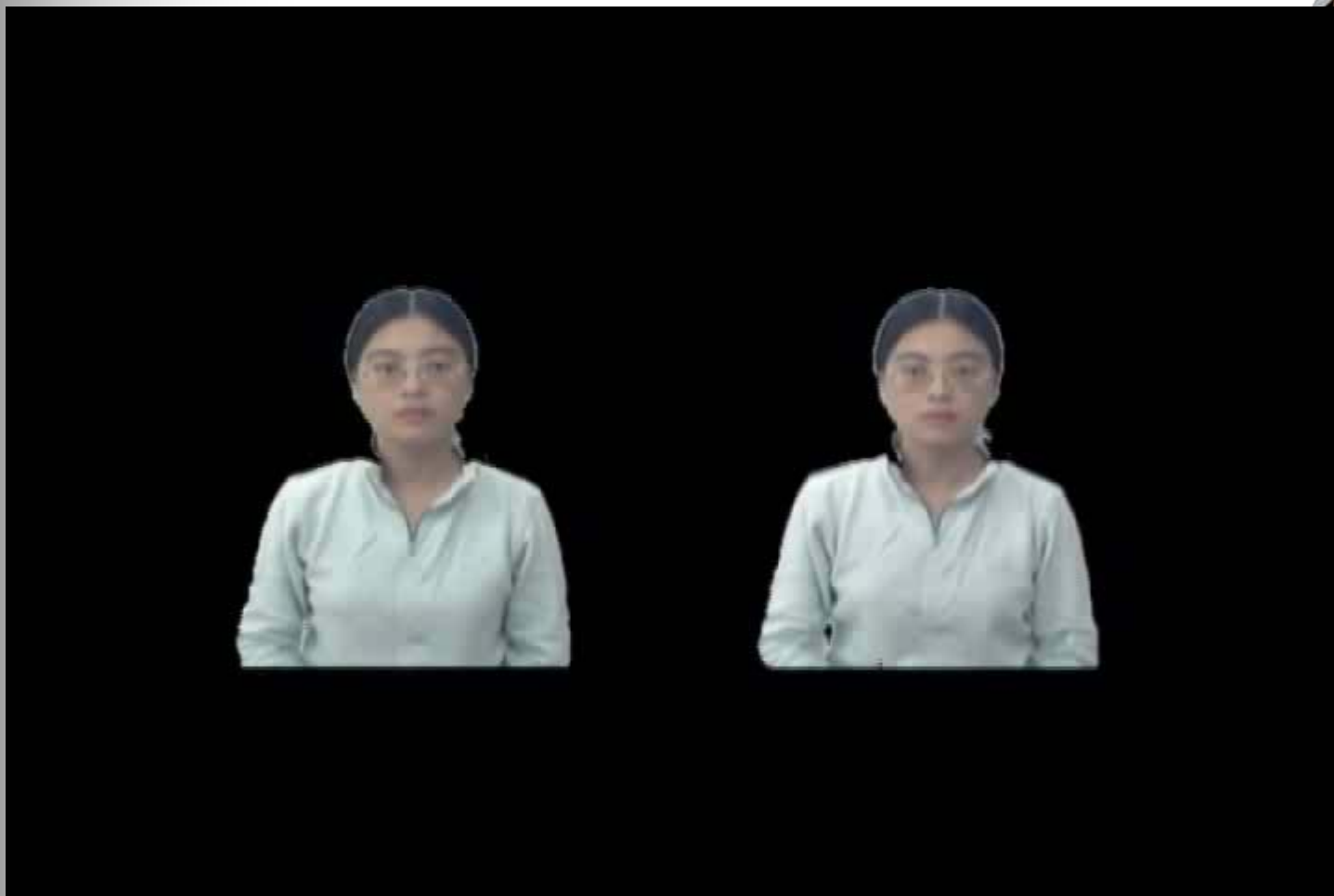


- Linear searching on all images
- Linear searching on selected tree leaves
- Linear searching on groups
- Binary searching on groups

# Linear Searching On All Images

- Use segments in database images with the input image
- Optimization
  - Skip frame if bbox not match
  - Use coherence to reduce popping





Linear searching on all images

# Linear Searching On Selected Tree Leaves

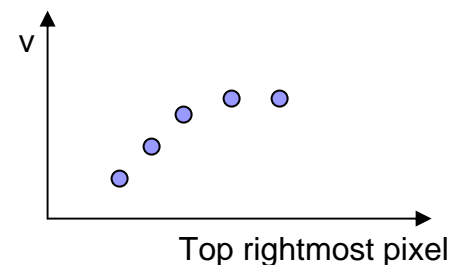
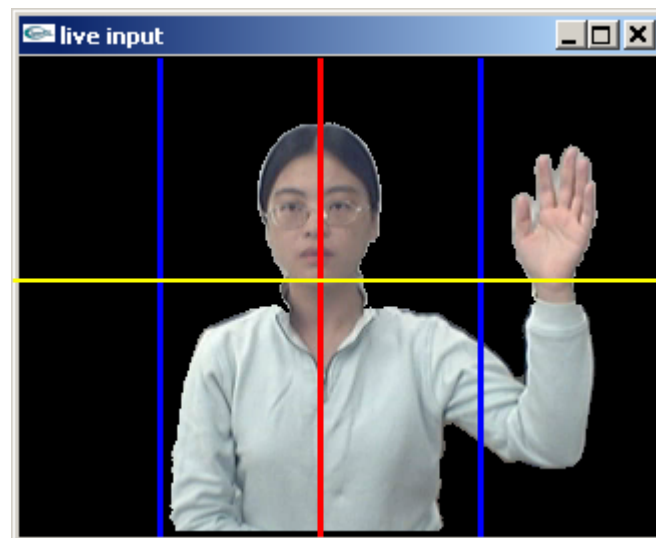


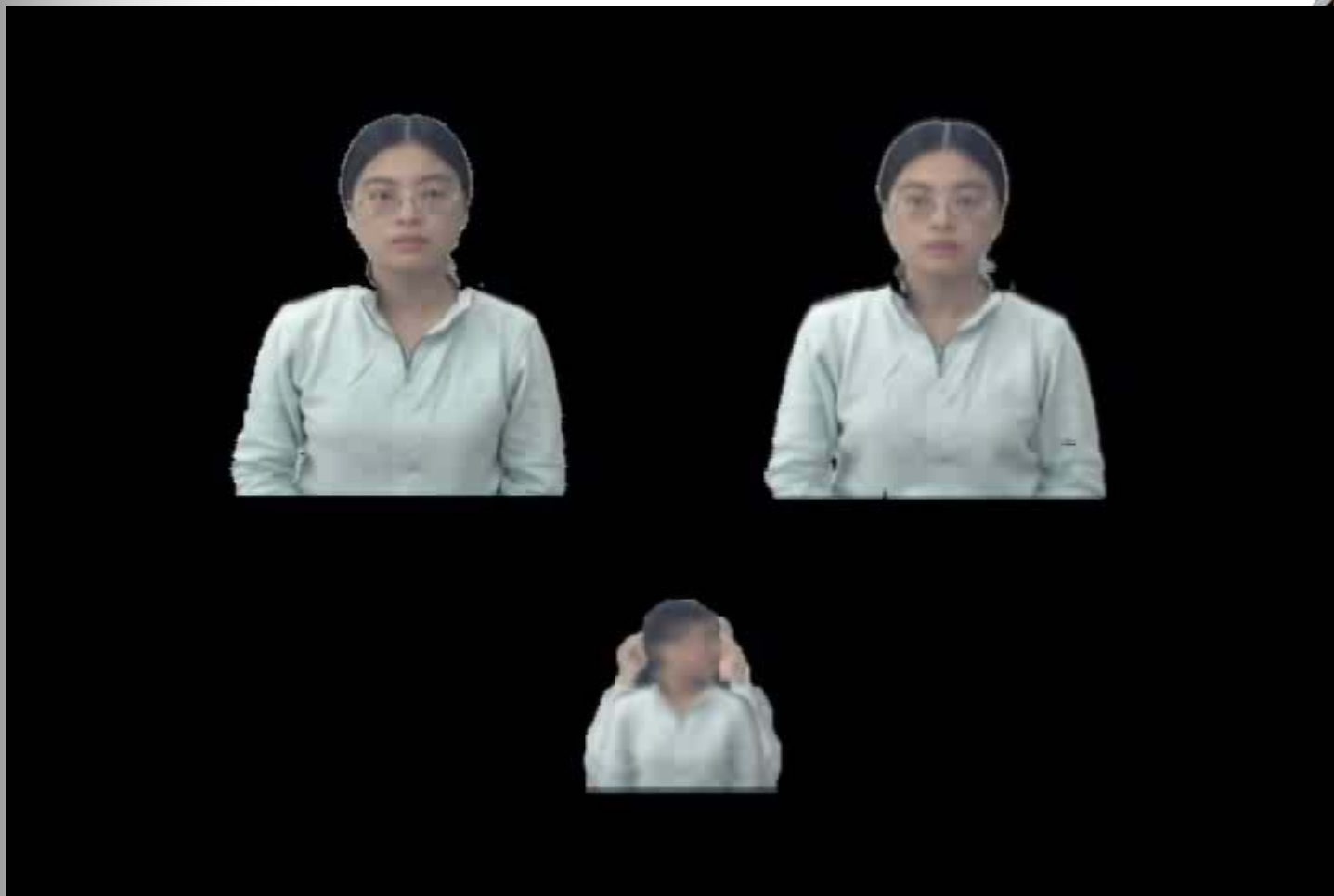
- Walk down the binary tree and find the matched leaf based on shape
- Searching all images under the matched leaf
  - Can do better if using more efficient matching algorithm in linear searching for all images
  - Further divide the frame into top, left, right region w.r.t. the shoulder line



# Subdivision

- Find the discrete curve of the top-, left-, right-most pixel position in each group
- Match the input frame needs only 1D searching





Linear searching on selected tree leaves

# Performance



## ■ Current database

- 1300 frames, captured at 10 fps
- 500 stored frames, 52 groups, 24 merged groups

# Performance Comparison



- Linear searching on all images
  - 68.12 ms per input frame, or 14 fps, use coherence
  - One input frame needs 312 ms, or 0.23 ms computation time for each database image
- Linear searching on selected tree leaves
  - 123 ms per input frame, or 8 fps, no coherence
  - One input frame takes 219 ms computation time

# Future Work



- Acquire data using higher resolution
- Capture facial expression
- Build database using multiple people and do matching